



22nd International Symposium on Graph Drawing  
24-26 September 2014, Würzburg, Germany

# Anchored Drawings of Planar Graphs

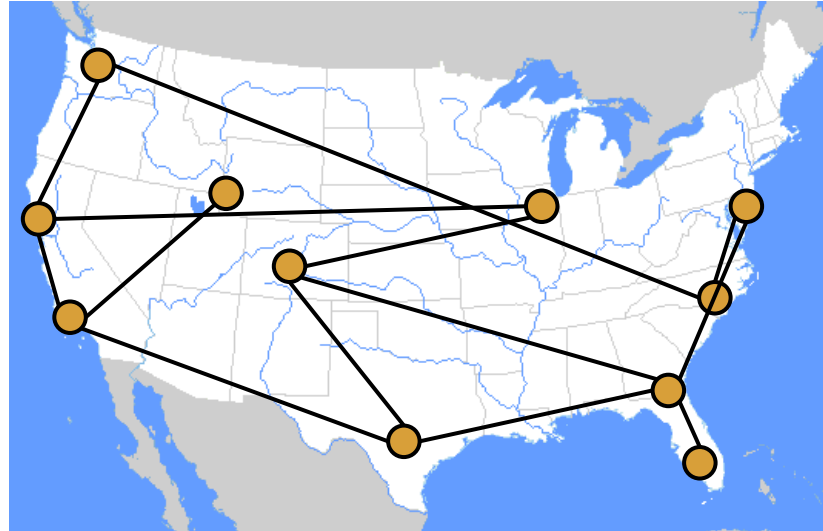
Angelini, Da Lozzo, Di Bartolomeo,  
Di Battista, Hong, Patrignani, Roselli



THE UNIVERSITY OF  
SYDNEY

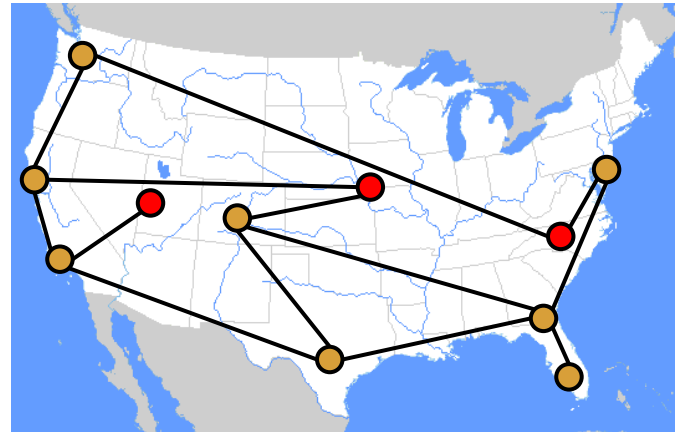
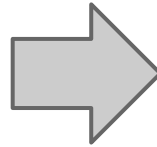
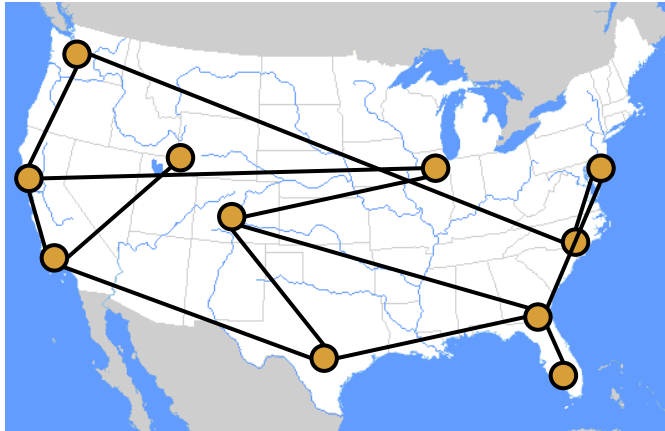
# Applicative Context

- Drawing a graph on a geographical map
- Vertices have fixed positions



# Drawing Nicely

- Our idea:
  - Let vertices move “a bit” around their positions
  - Check if this allows a planar drawing of the graph



# Anchored Graph Drawing Problem

- **Instance**

- Planar graph  $G$
- Initial vertex positions  $\alpha(v)$
- Maximum distance  $\delta$

- **Question**

- Does  $G$  admits a planar drawing
- ...such that vertices move by distance at most  $\delta$
- ...from their initial positions  $\alpha$ ?

# Considered Settings

**Distance  
Function**

“Euclidean”

$$d = (dx^2 + dy^2)^{1/2}$$

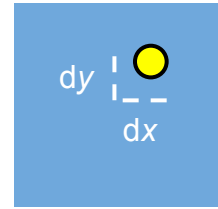
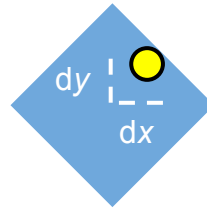
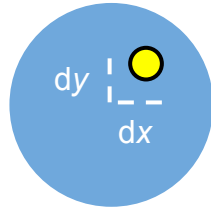
“Manhattan”

$$d = dx + dy$$

“Uniform”

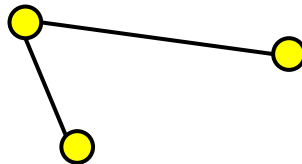
$$d = \max(dx, dy)$$

**Vertex  
Region**

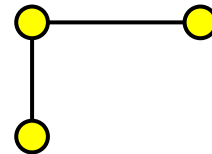


**Drawing  
Style**

Straight-line



Rectilinear

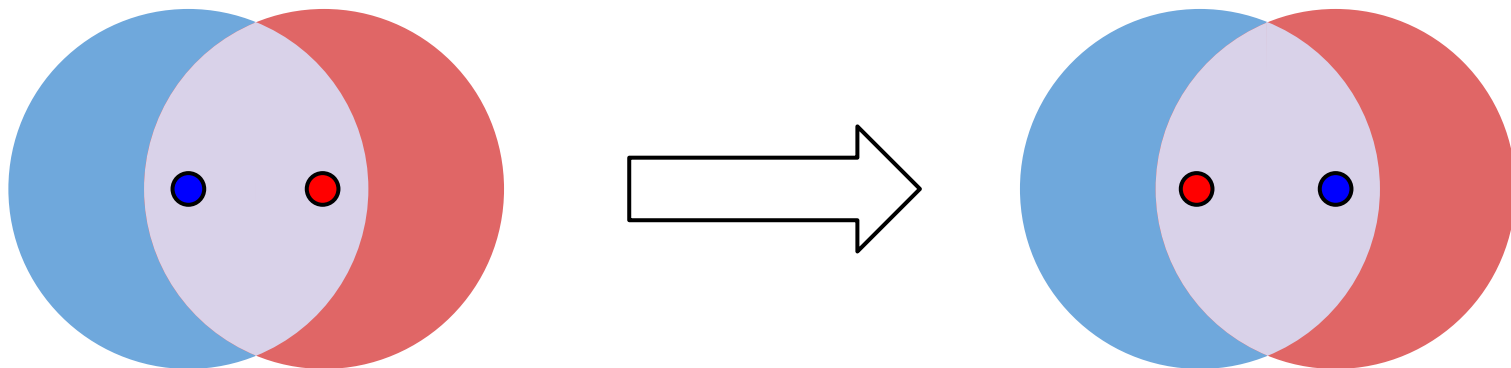


# Previous work




- NP-hard: straight-line and disks of different size
  - Godau. *On the difficulty of embedding planar graphs with inaccuracies*. 1995
- NP-hard: rectilinear and  $\delta = \text{inf}$ 
  - Garg, Tamassia. *On the comp. compl. of upward and rectilinear planarity test*. 2001
- Application of force-directed algorithms
  - Abellanas et. al. *Network drawing with geographical constraints on vertices*. 2005
- Iterative adjustments that preserve mental map
  - Lyons et. al. *Algorithms for cluster busting in anchored graph drawing*. 1998

# Assumption

- No overlap between **vertex regions**
  - Or two vertices may invert their positions
    - Very confusing for a user
  - Relationship with Clustered Planarity with drawn clusters






# Our Results

Metric	Straight-line	Rectilinear
Manhattan 	NP-hard	NP-hard
Euclidean 	NP-hard	NP-hard
Uniform 	NP-hard	Polynomial

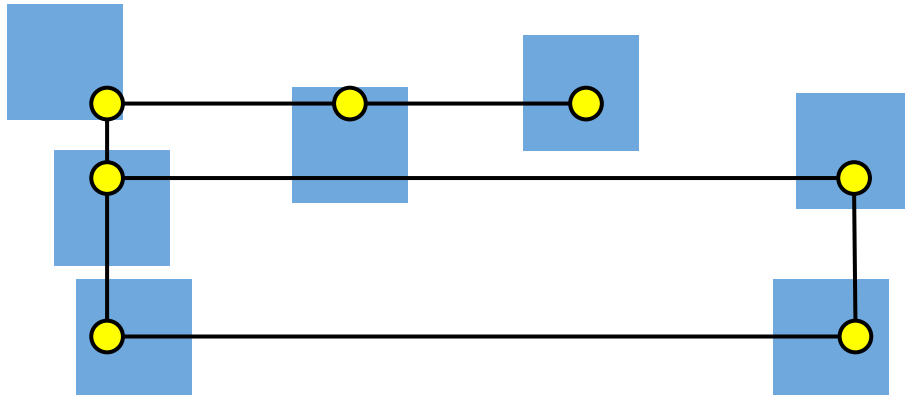


# Our Results

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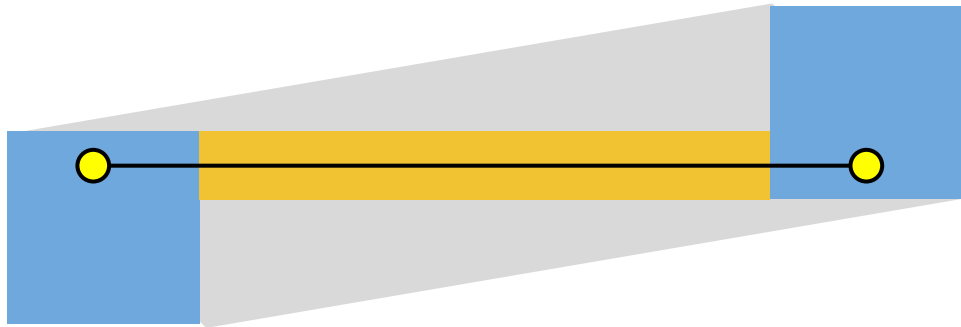
# Polynomial Case

- Connected graph
- Uniform distance (■ regions)
- Rectilinear drawing



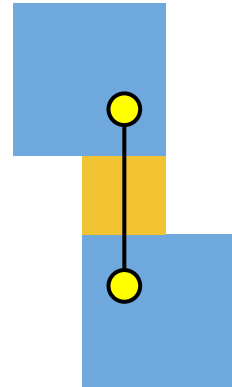
# Edge Pipes

- We call **pipe** the convex hull of two regions
  - Minus the regions
- An edge can be drawn only inside a pipe
- In this setting pipes “get rectilinear” too



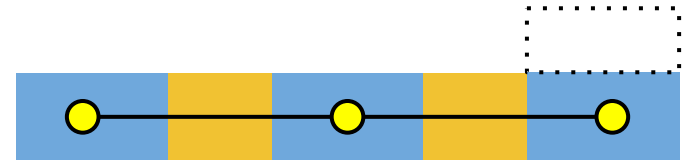
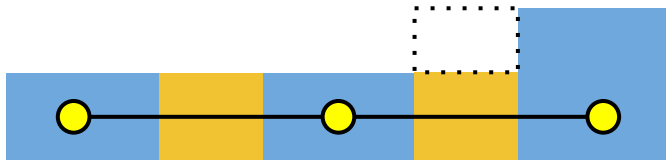
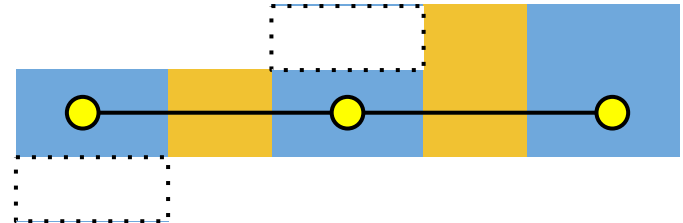
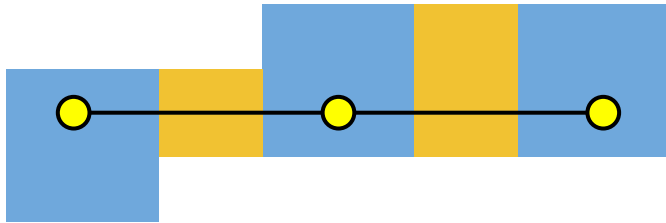
# Rectilinear Edges

- An edge is either **horizontal** or **vertical**
- Can be deduced by the region positions
- **Visibility** is required between two endpoints



# Trimming

- Regions and pipes can trim each other
- A trimmed area cannot be used

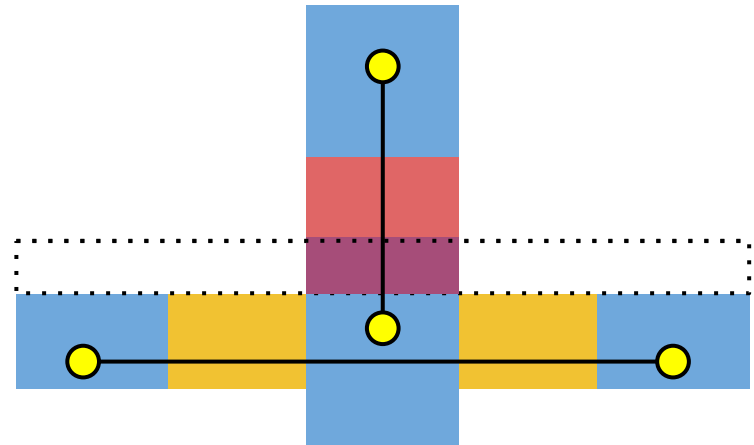
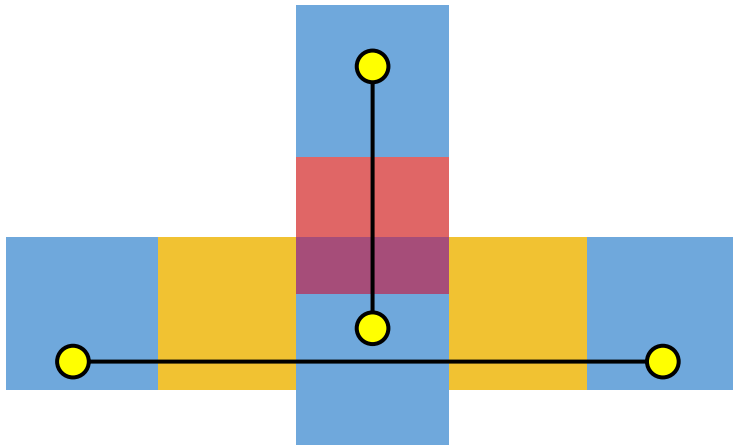


# General Strategy

1. Start from the initial region/pipe configuration
2. While (a trim is possible):
  - a. Trim unusable parts of pipes and regions
  - b. Check if a negative configuration is obtained
3. Flag the instance as positive
4. Draw edges according to the current pipes

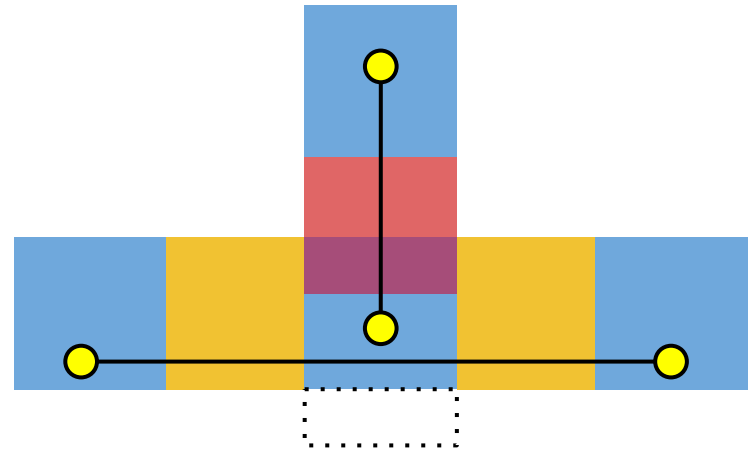
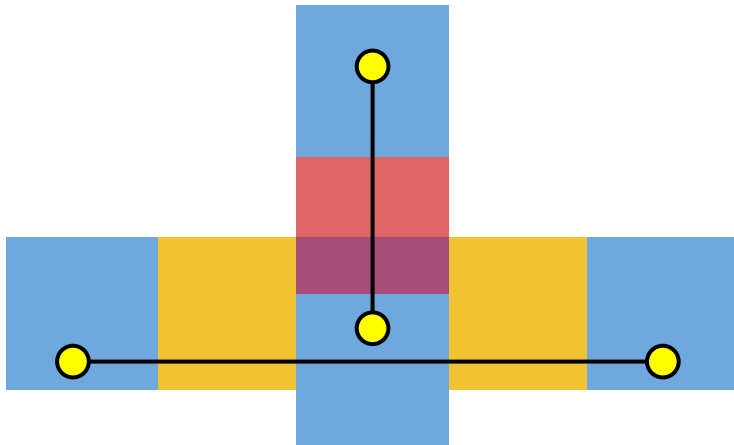
# Trimming Pipes

- *VP-overlaps* can trim a pipe



# Trimming Regions

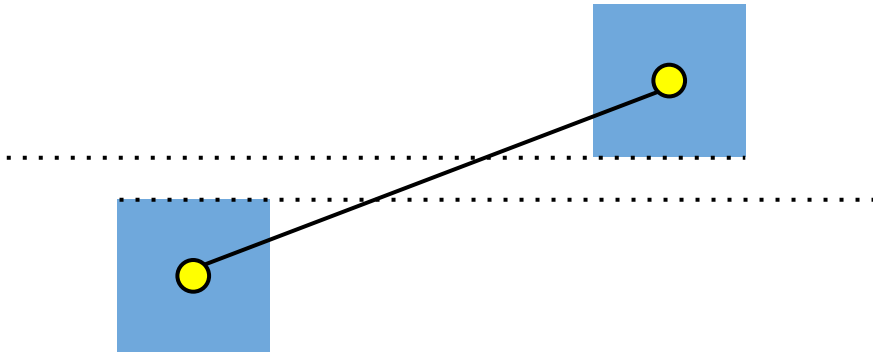
- *VP-overlaps* can trim a region



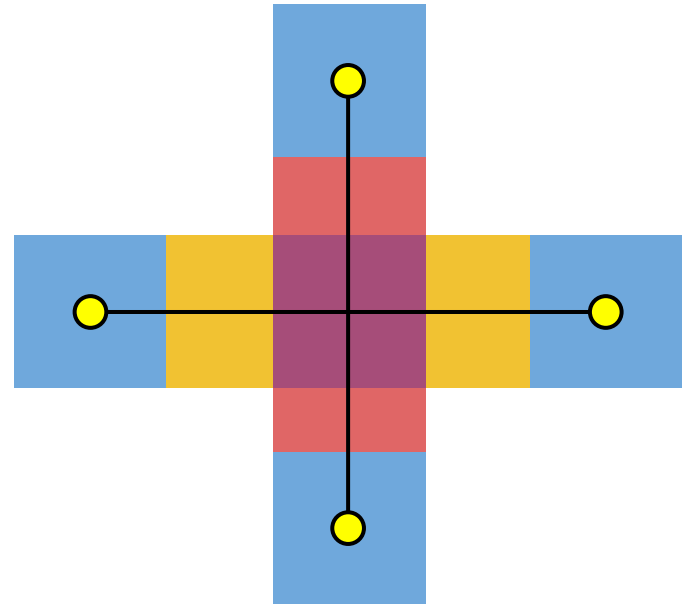


# Negative Instances

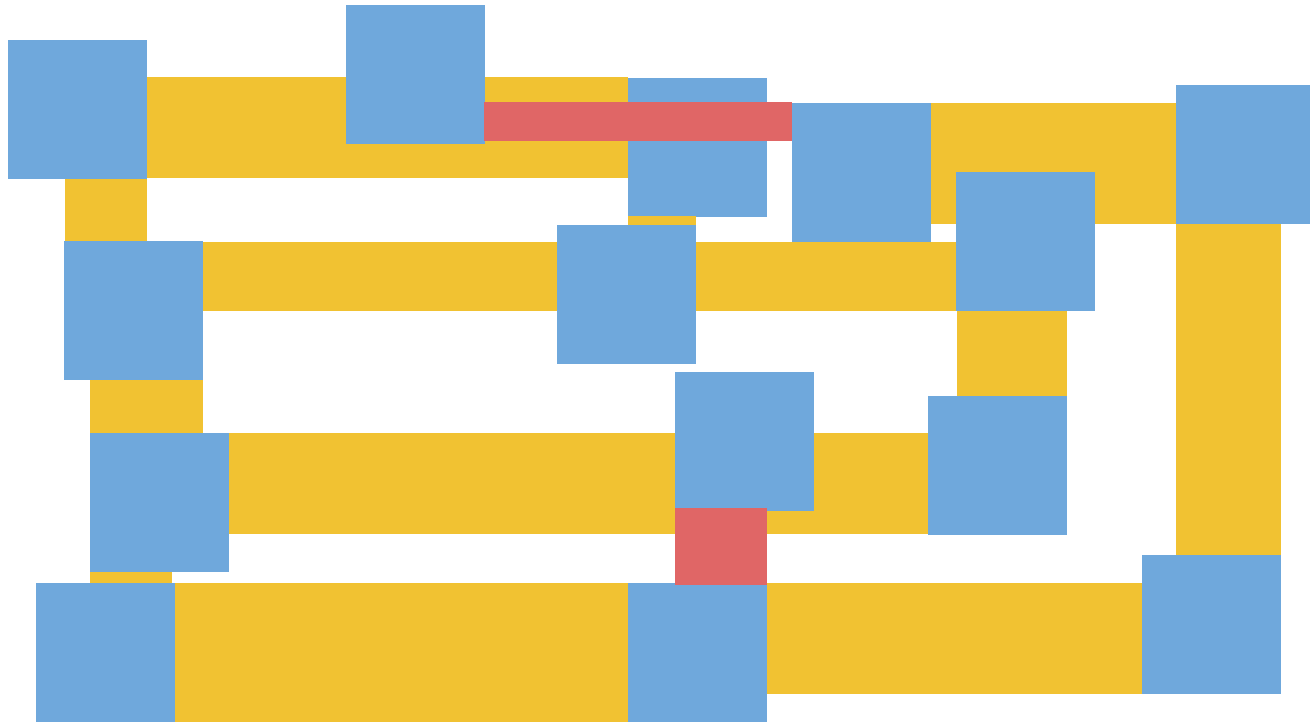
No visibility



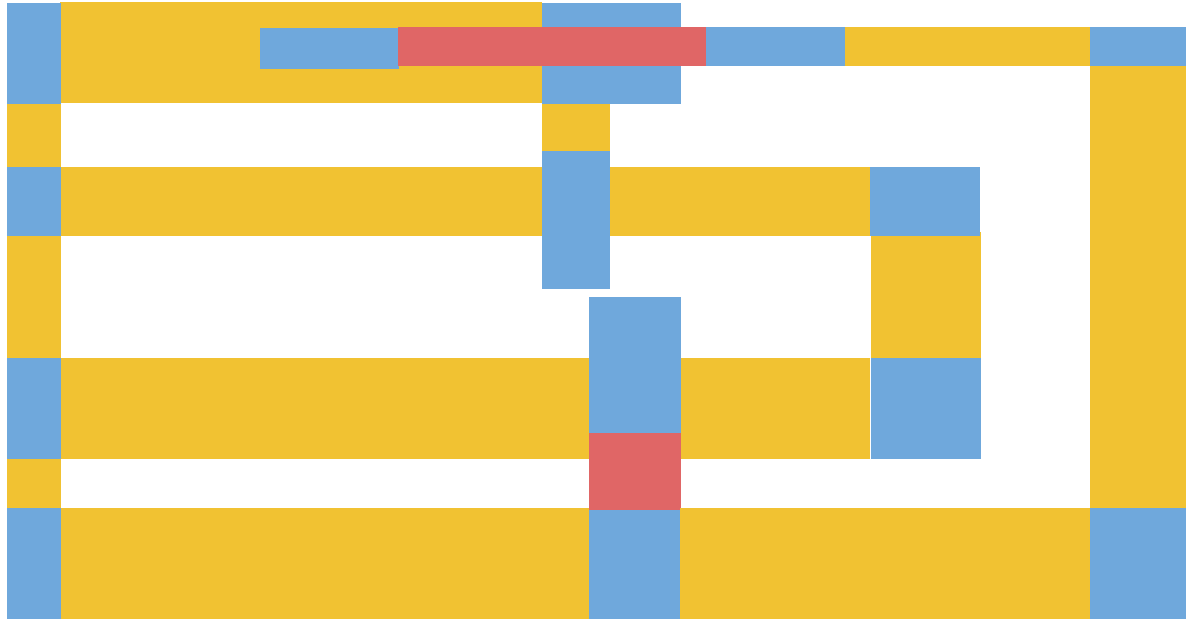
PP-overlap  
(Unavoidable crossing)



# An Example of Execution

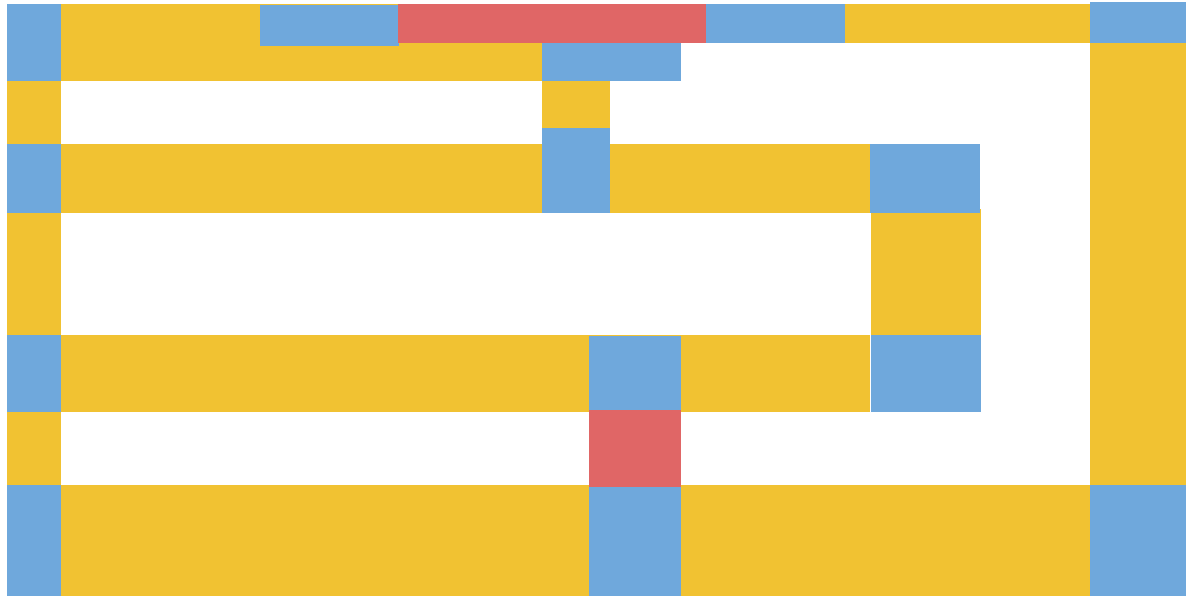


# An Example of Execution

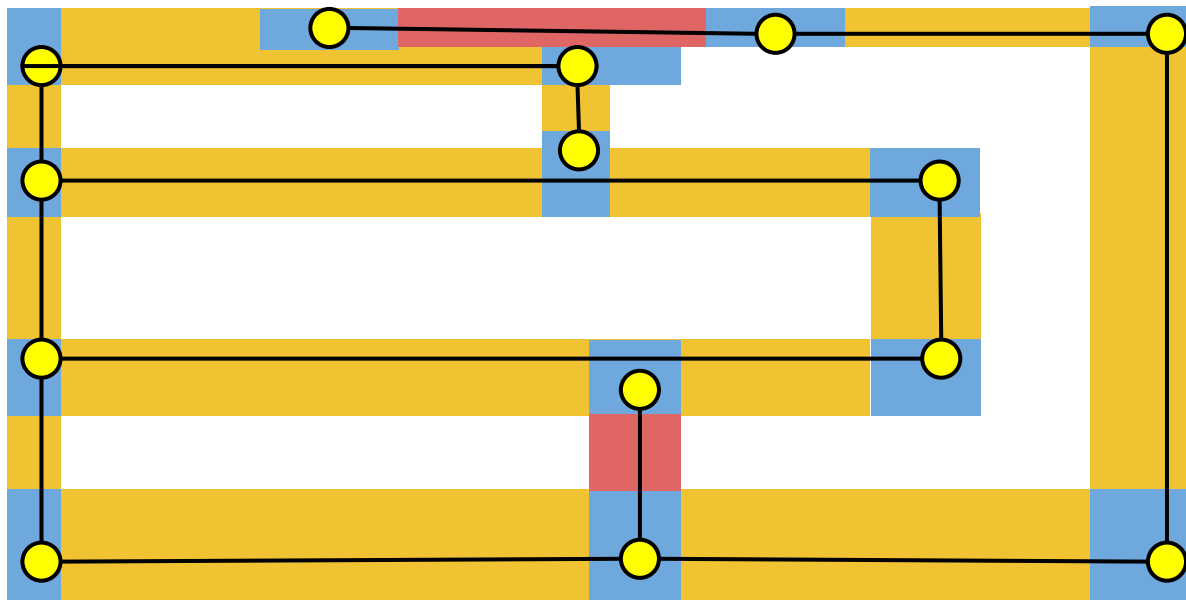




# An Example of Execution

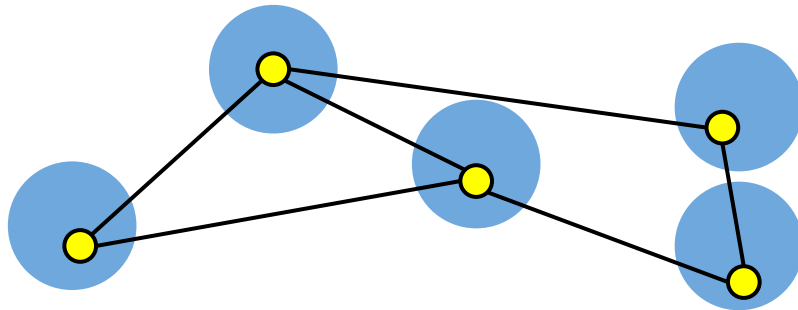


# An Example of Execution



# NP-hard Case

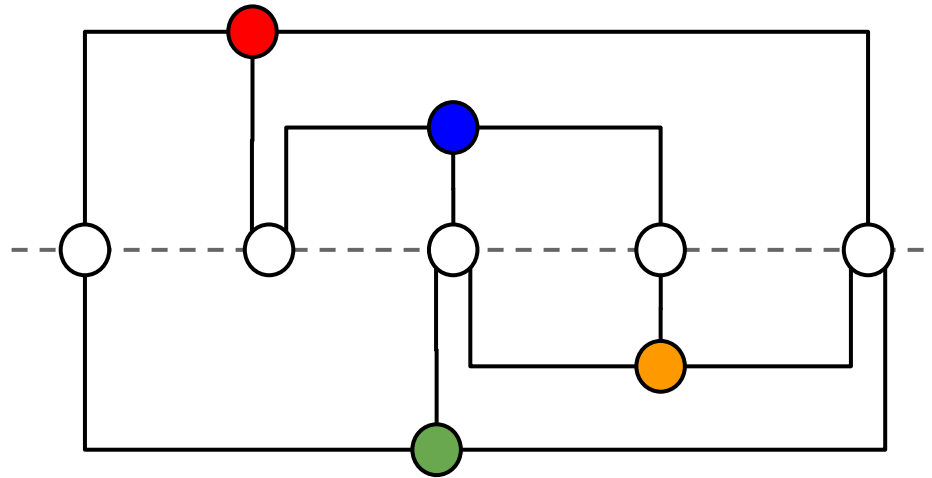
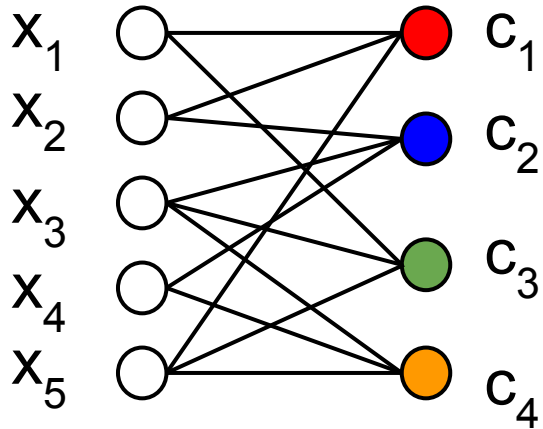
- Euclidean distance ( ● regions)
- Straight-line drawing
- Reduction from *Planar 3-SAT*



# Planar 3-SAT

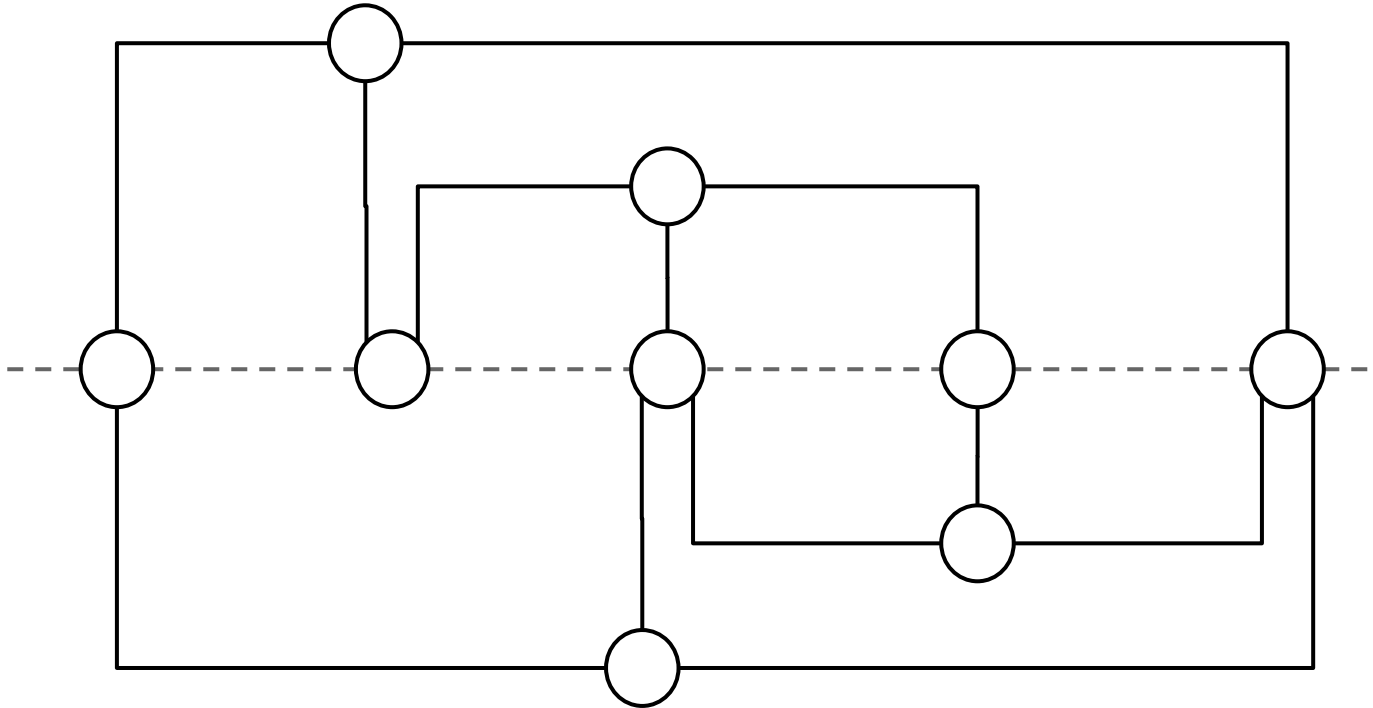
$$(x_1 \vee \neg x_2 \vee x_5) \wedge (x_2 \vee x_3 \vee \neg x_4) \wedge (x_1 \vee \neg x_3 \vee x_5) \wedge (x_3 \vee x_4 \vee x_5)$$

$C_1$                        $C_2$                        $C_3$                        $C_4$

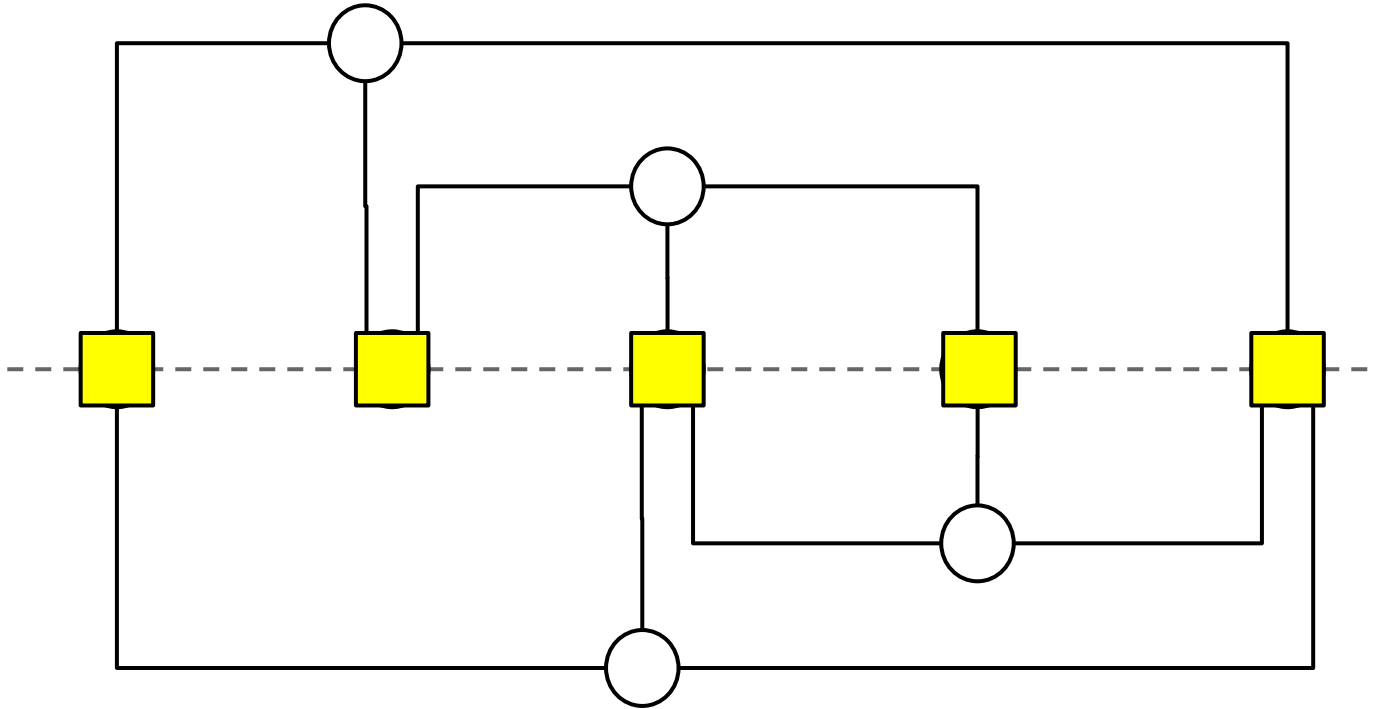




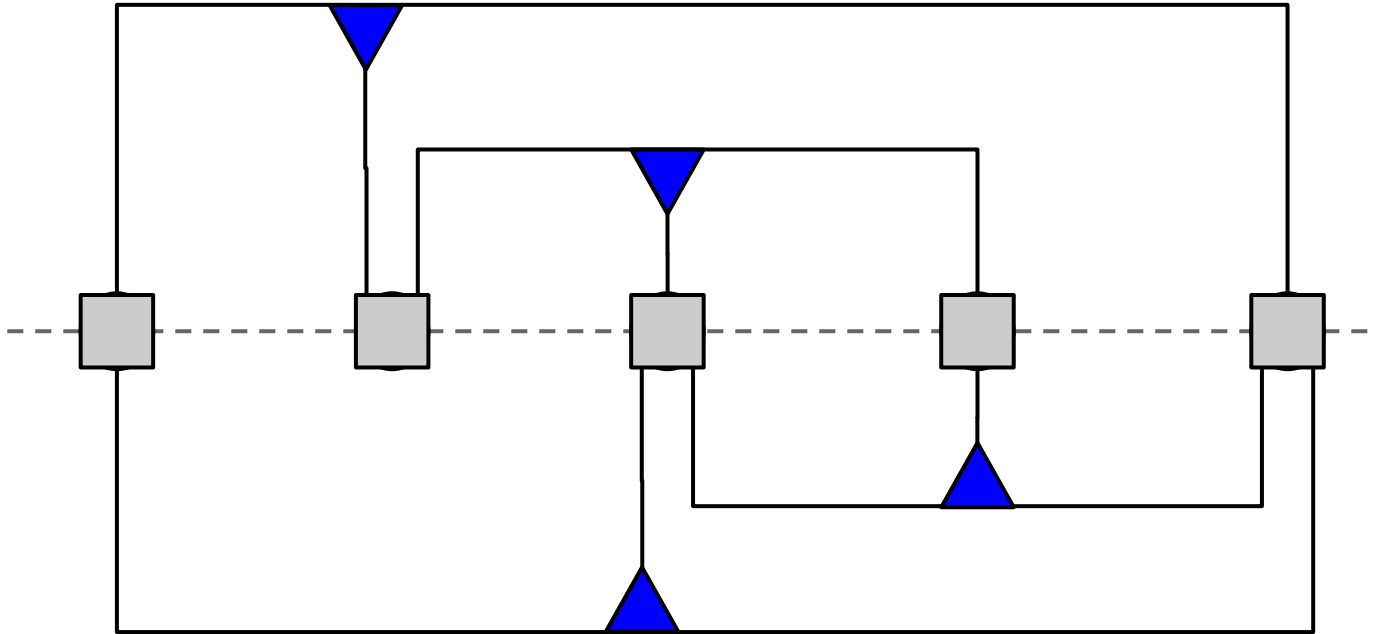
# Planar 3-SAT - Gadgets



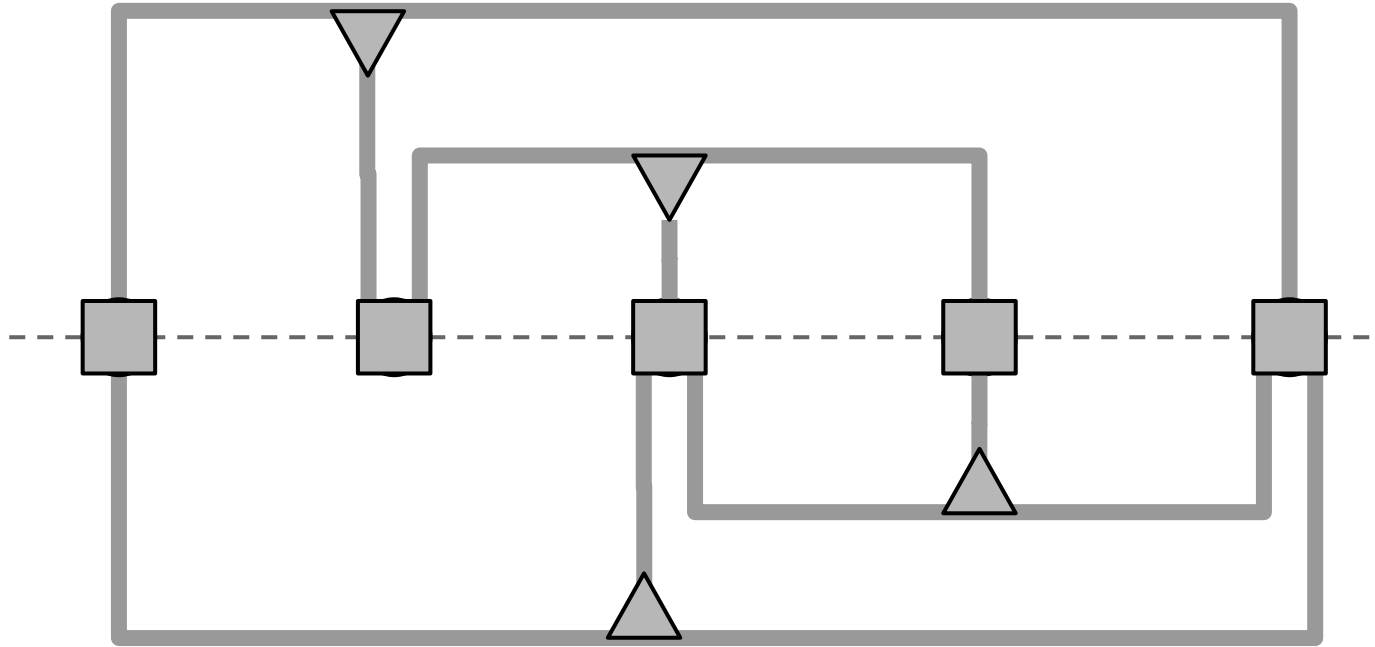
# Planar 3-SAT - Variable Gadget



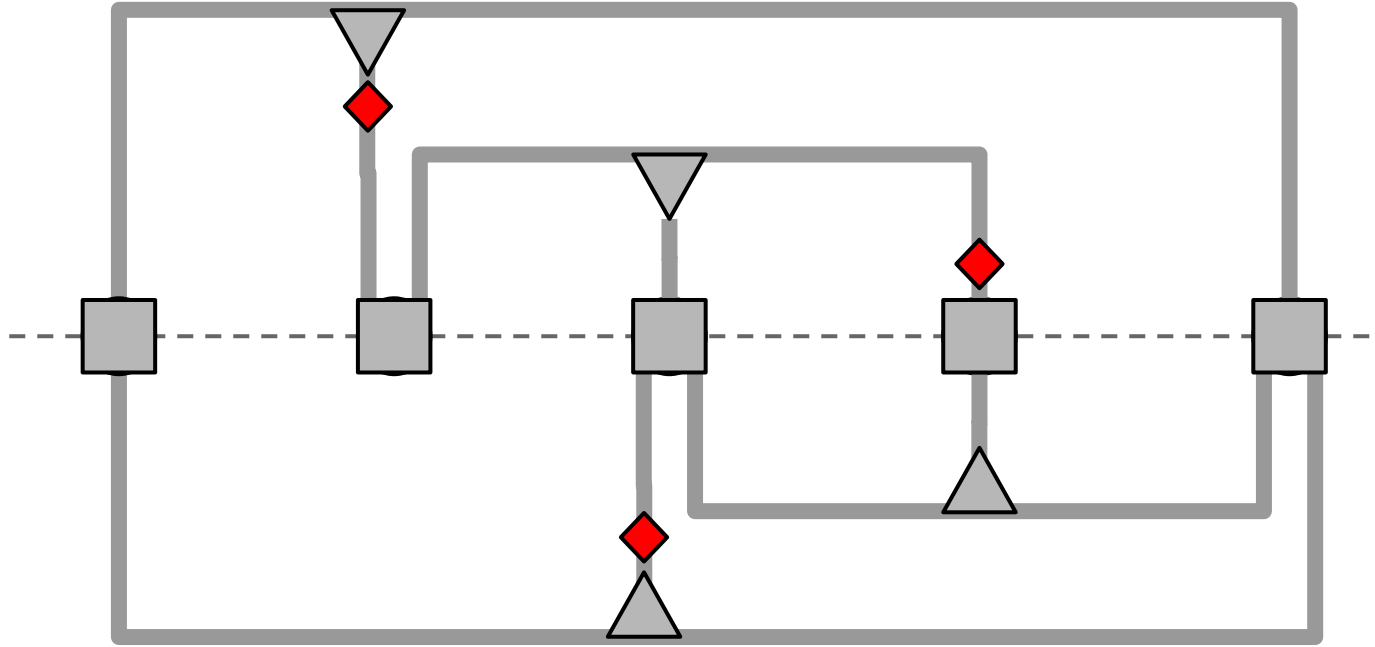
# Planar 3-SAT - Clause Gadget



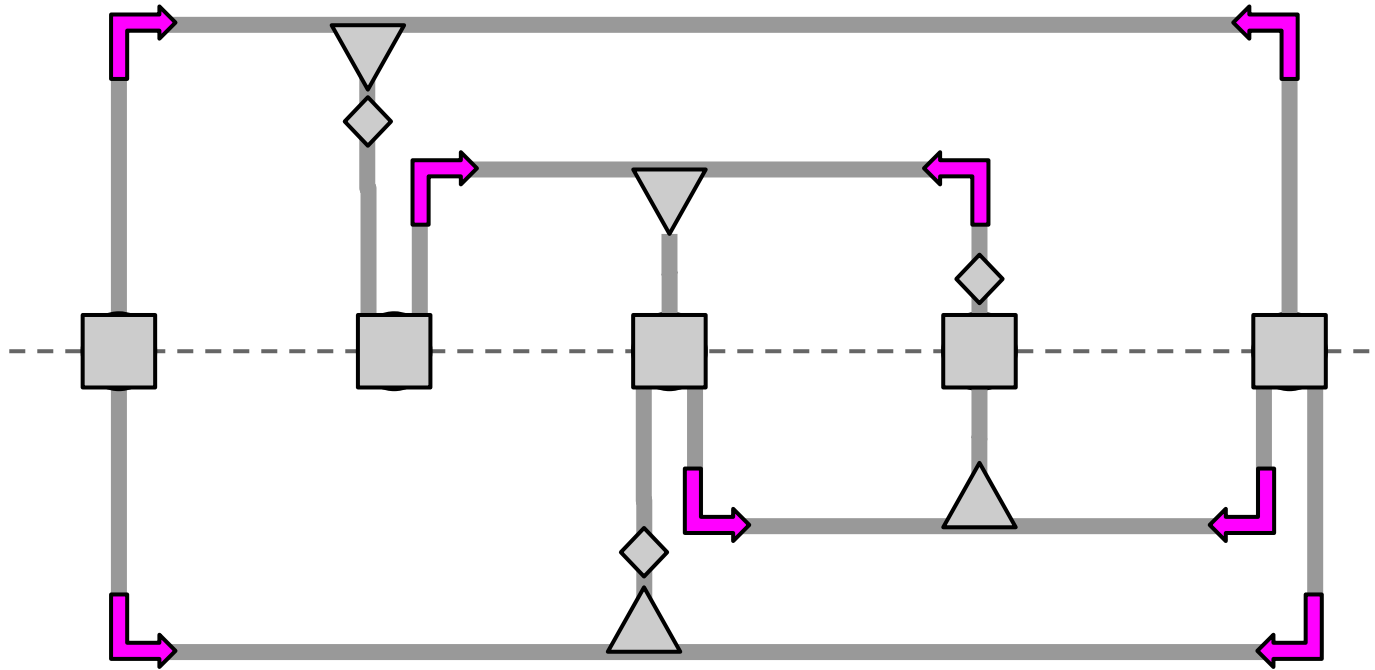
# Planar 3-SAT - Truth Propagation



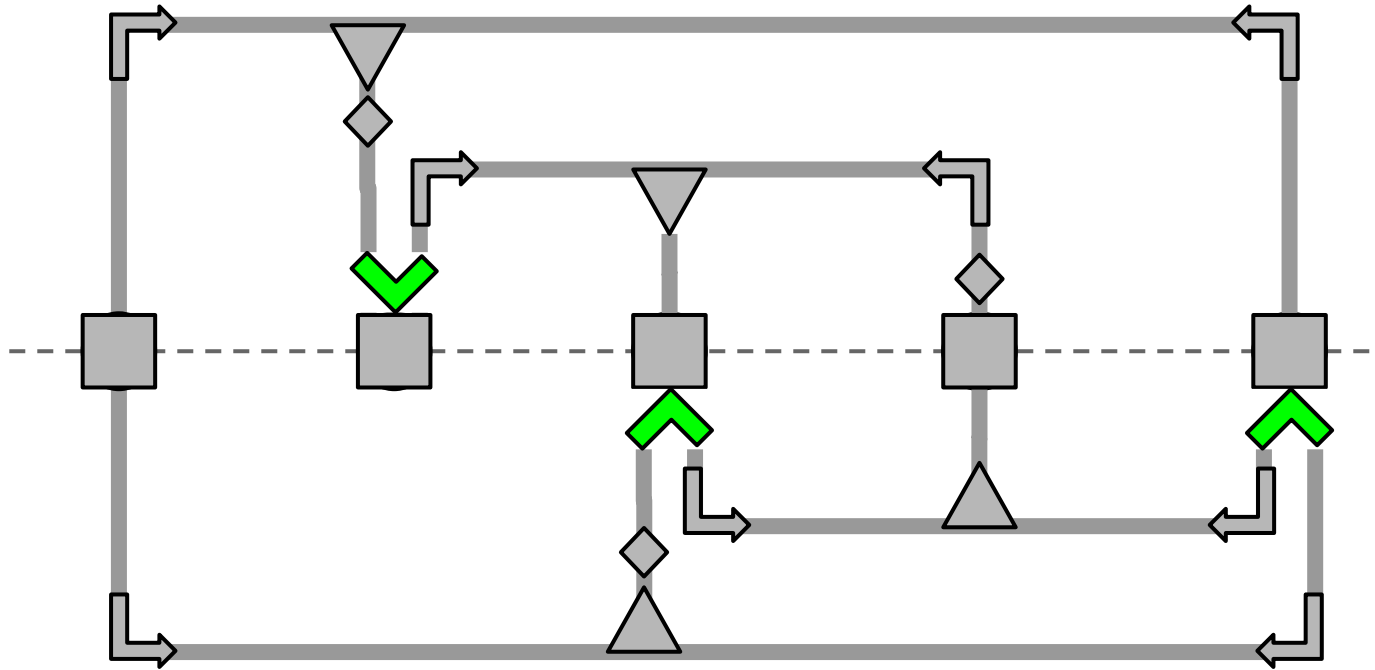
# Planar 3-SAT - *Not* Gadget



# Planar 3-SAT - *Turn* Gadget

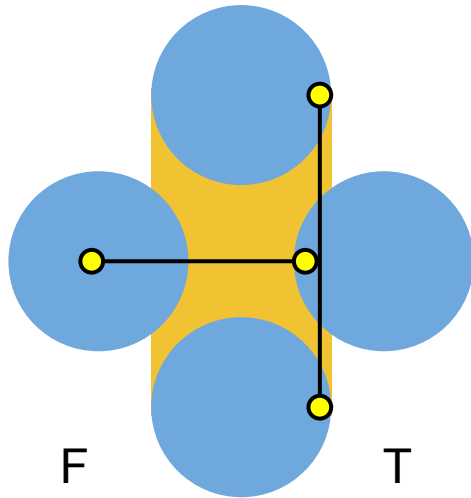


# Planar 3-SAT - *Split* Gadget

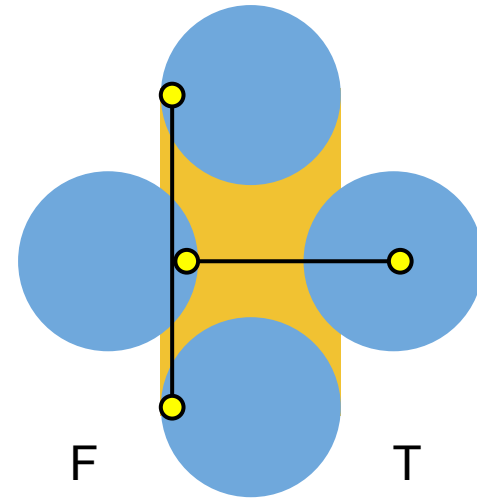


# Variable Gadget

*True* configuration

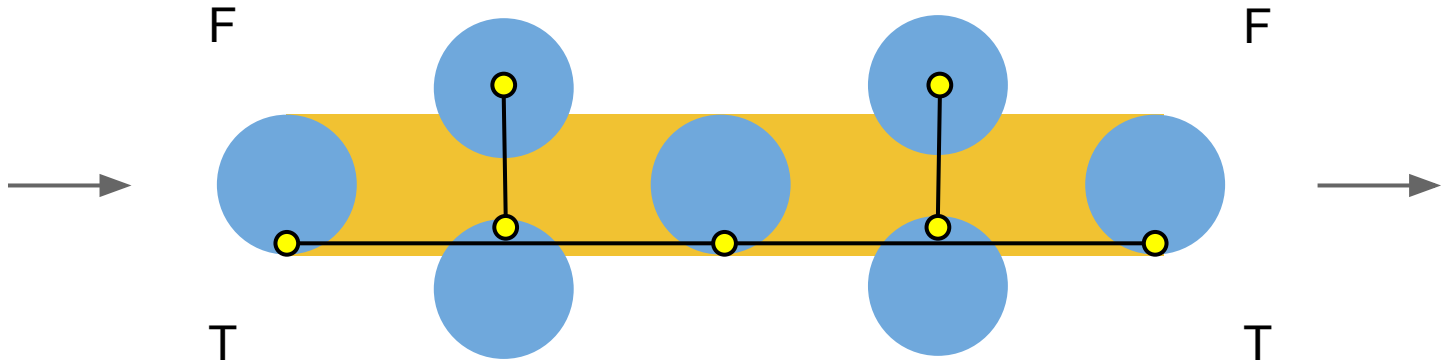


*False* configuration

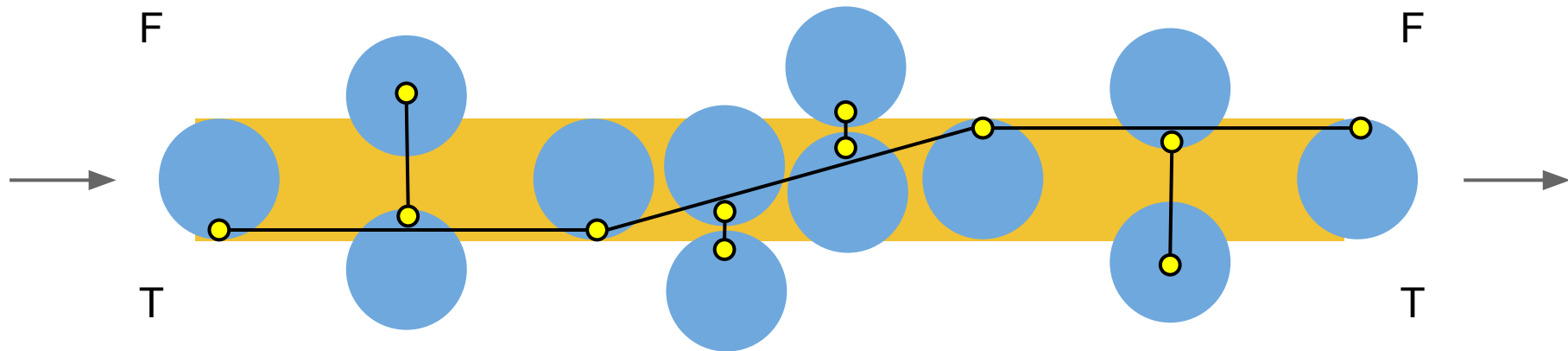




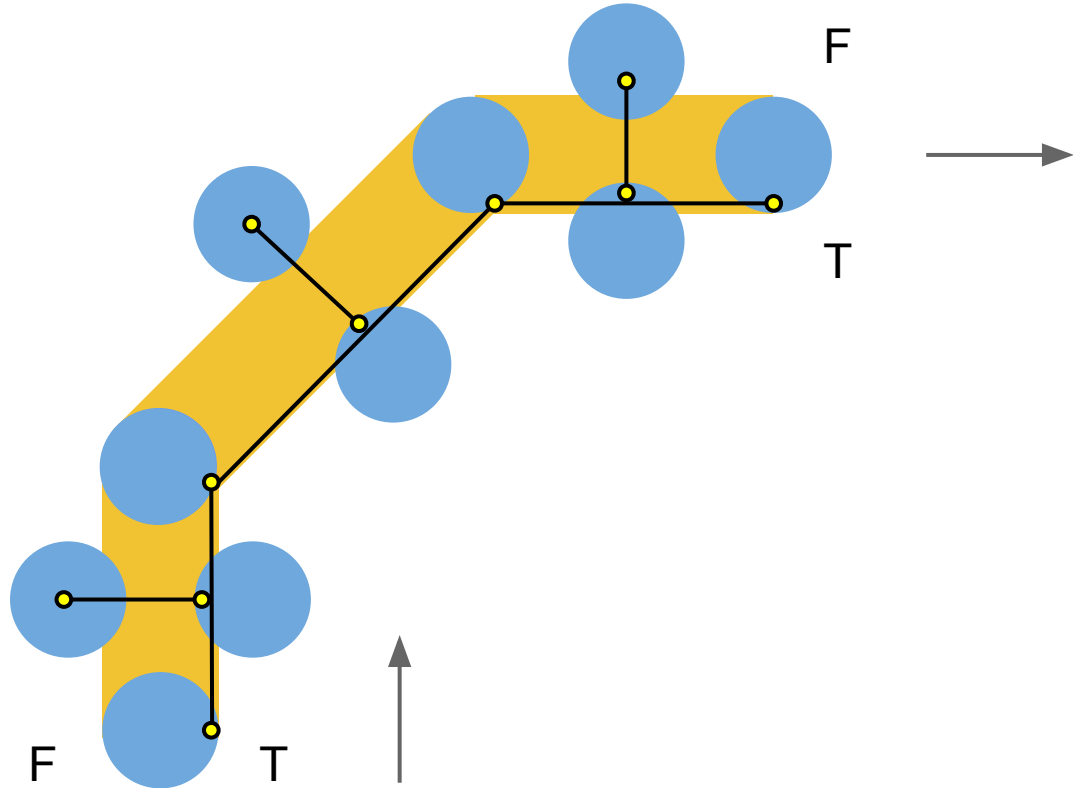
# Truth Propagation



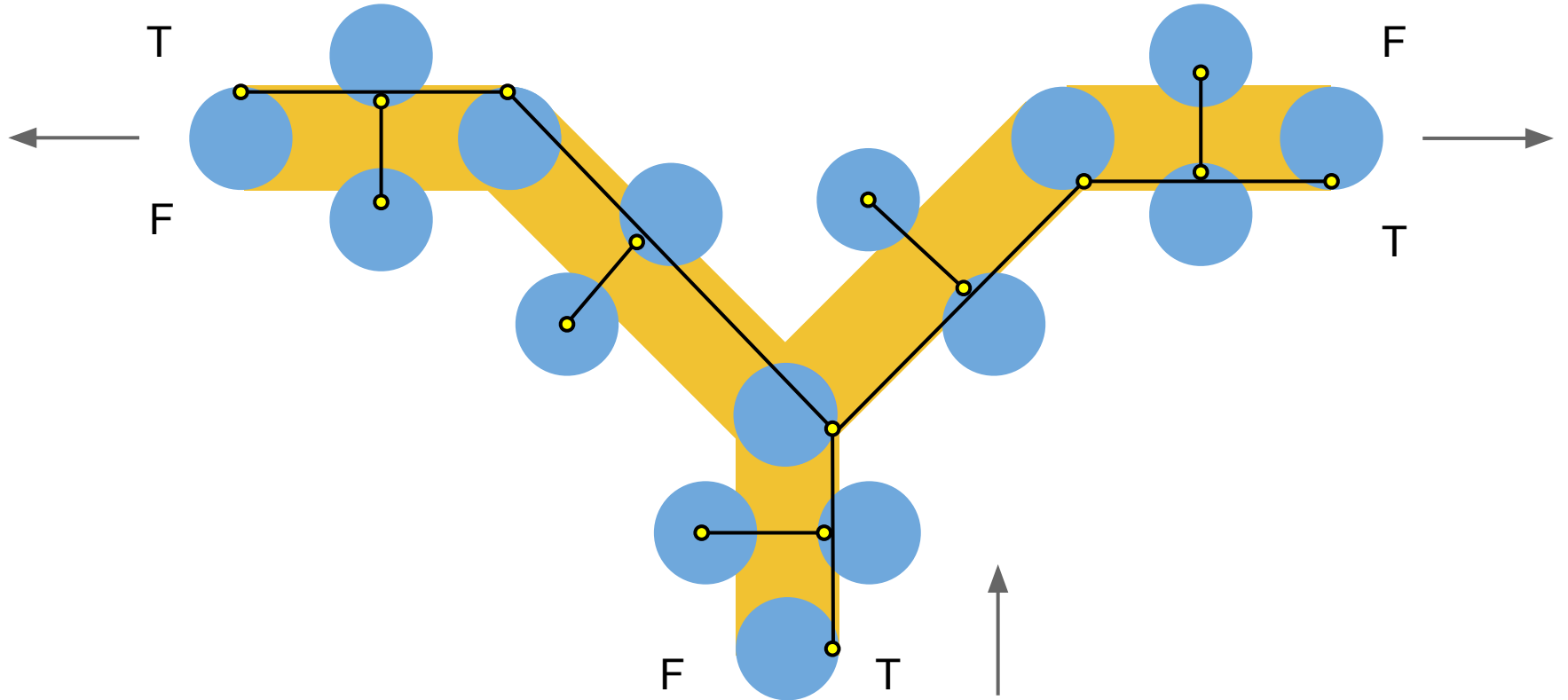
# Not Gadget



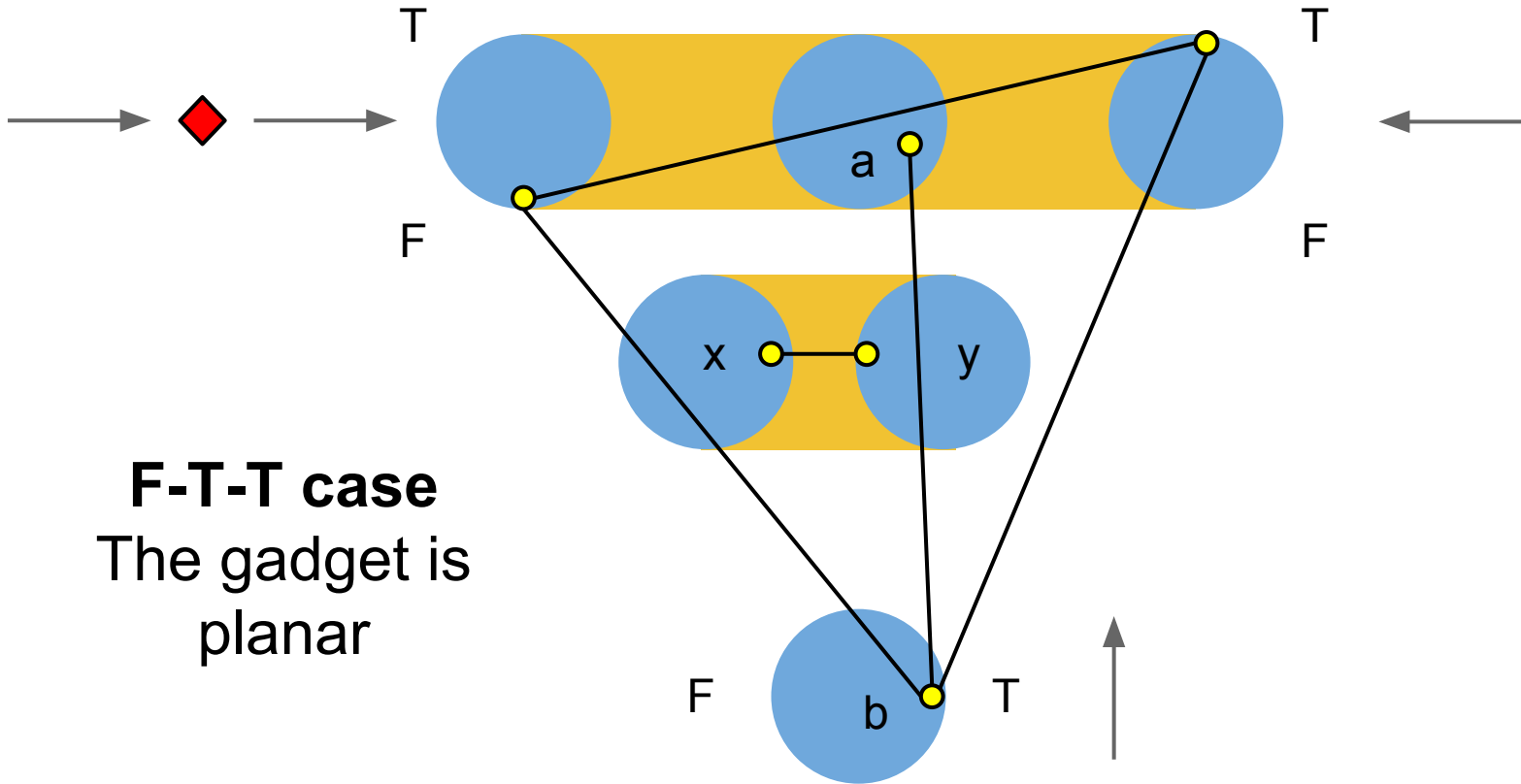
# Turn Gadget



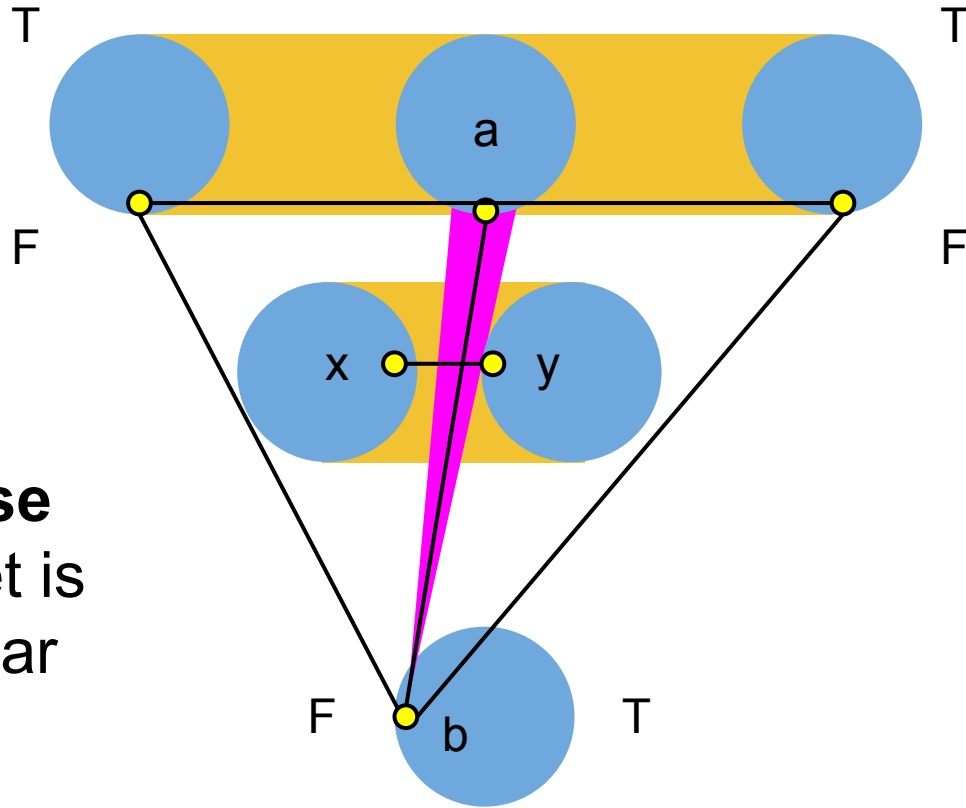
# Split Gadget



# Clause Gadget

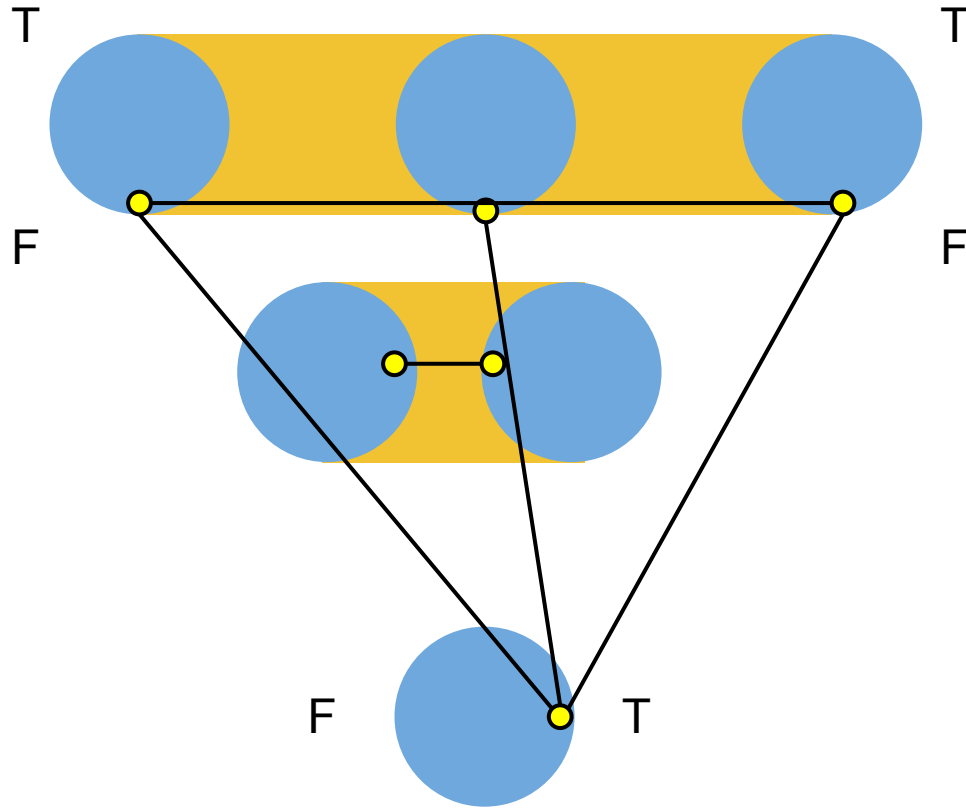


# Clause Gadget

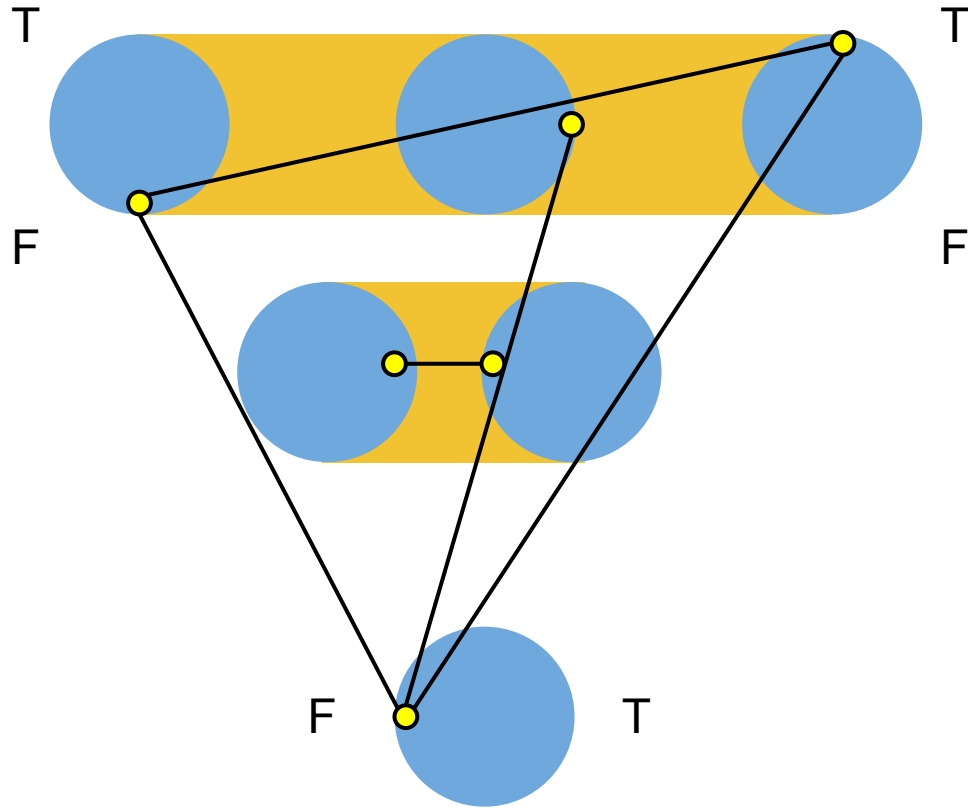


**F-F-F case**  
The gadget is  
NOT planar

# Clause Gadget

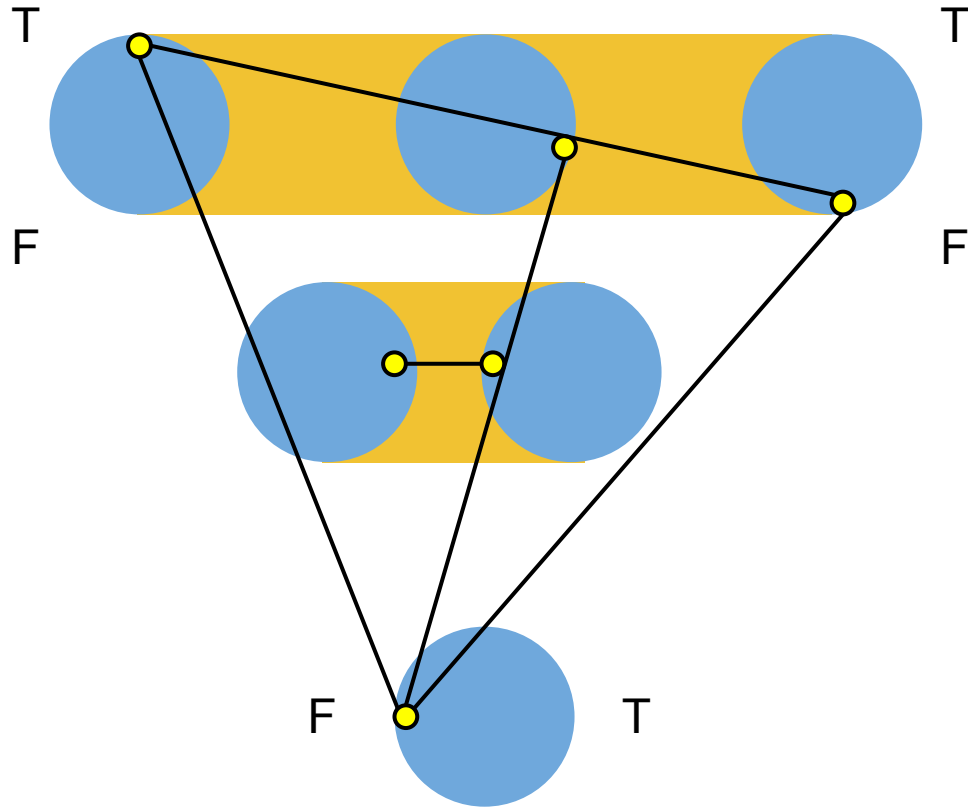


# Clause Gadget

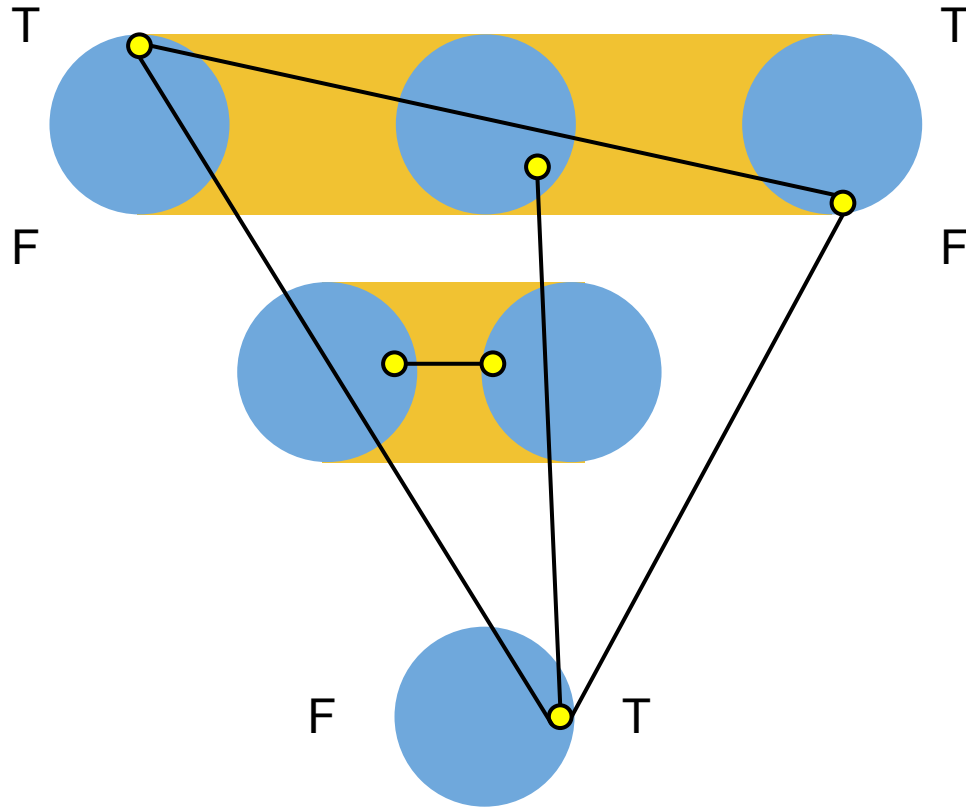




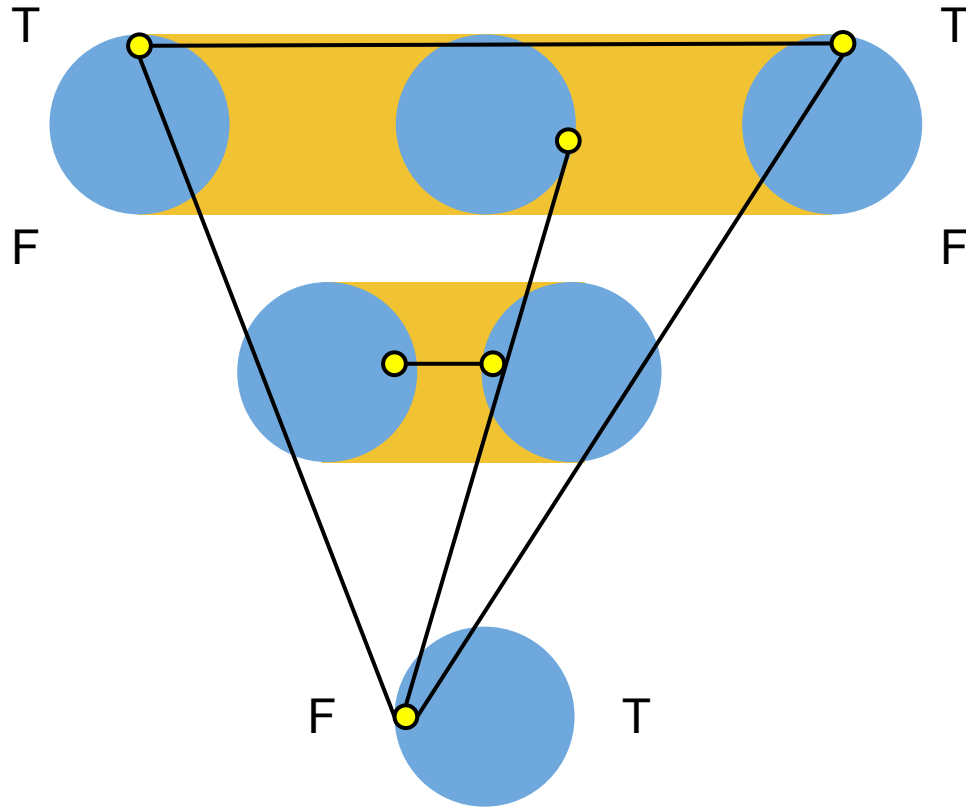
# Clause Gadget



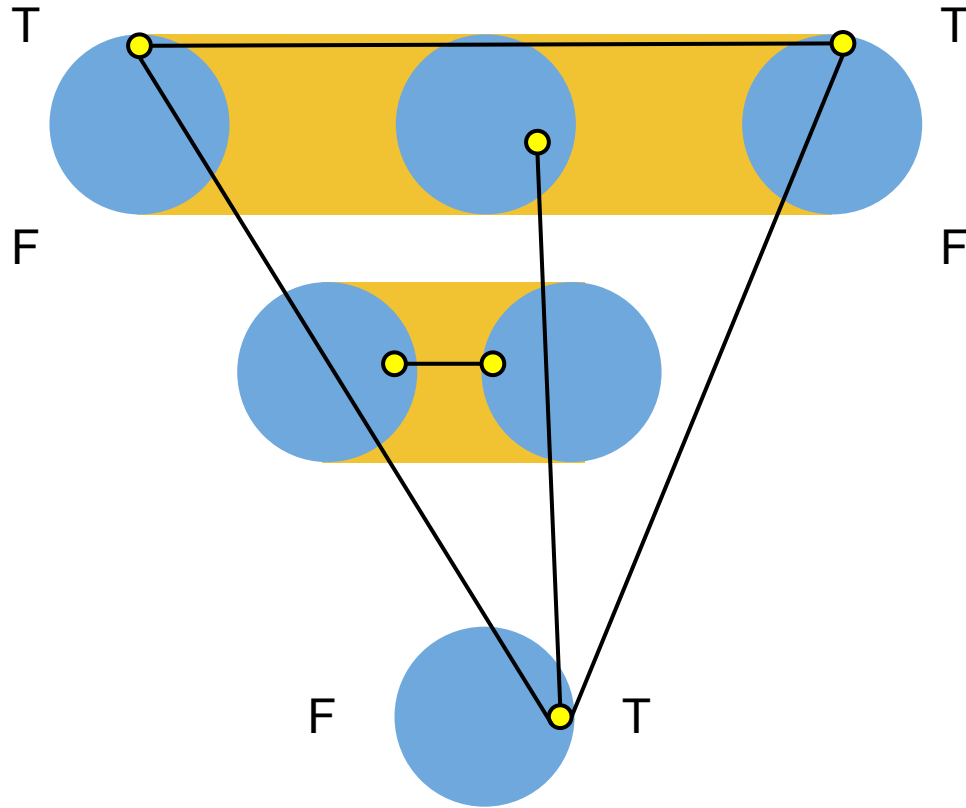
# Clause Gadget



# Clause Gadget



# Clause Gadget



# Open Problems

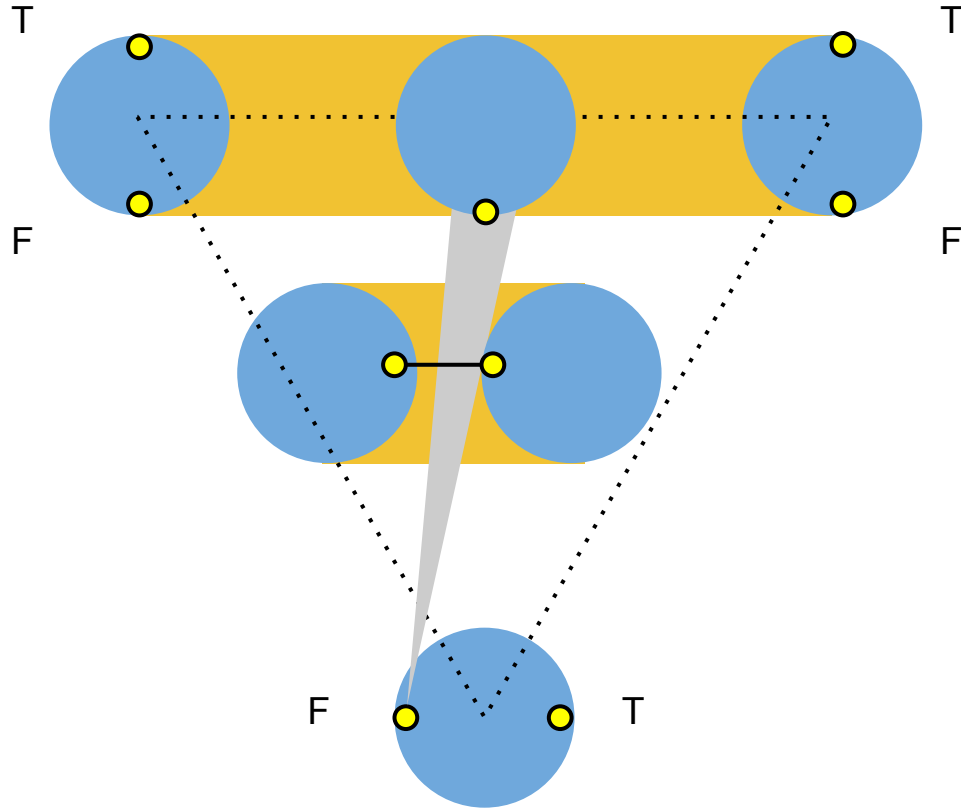
- Do the hard problems belong to NP?
- Still hard with biconnected gadgets. What if triconnected?
- What if we allow regions to partially overlap?
- What if we allow some crossings?

# Applicative Context

- Drawing a graph on a geographical map
- Vertices have fixed positions



# Clause Gadget (master slide)



# Challenges

- Vertex cluttering, edge crossings
- Techniques exist to mitigate cluttering
- However, crossings are still an issue