

# Drawing Graphs within Restricted Area

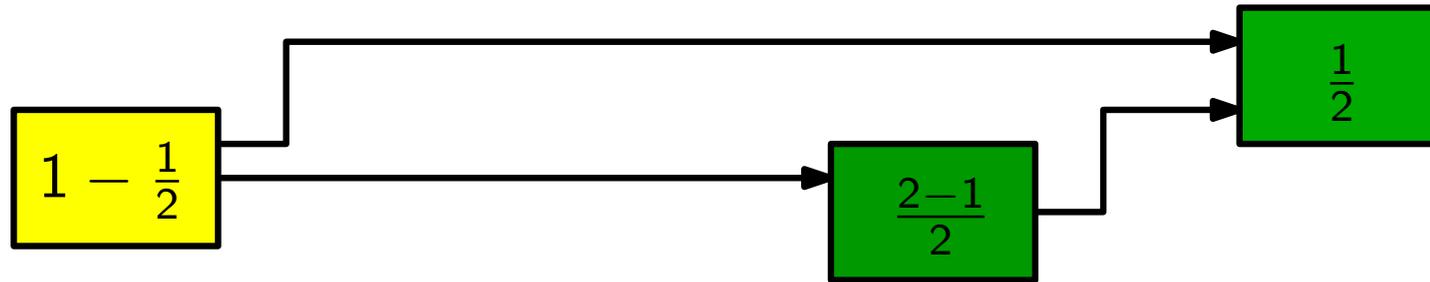
Martin Fink

Department of Computer Science  
University of California, Santa Barbara

Joint work with Maximilian Aulbach,  
Julian Schuhmann, and Alexander Wolff

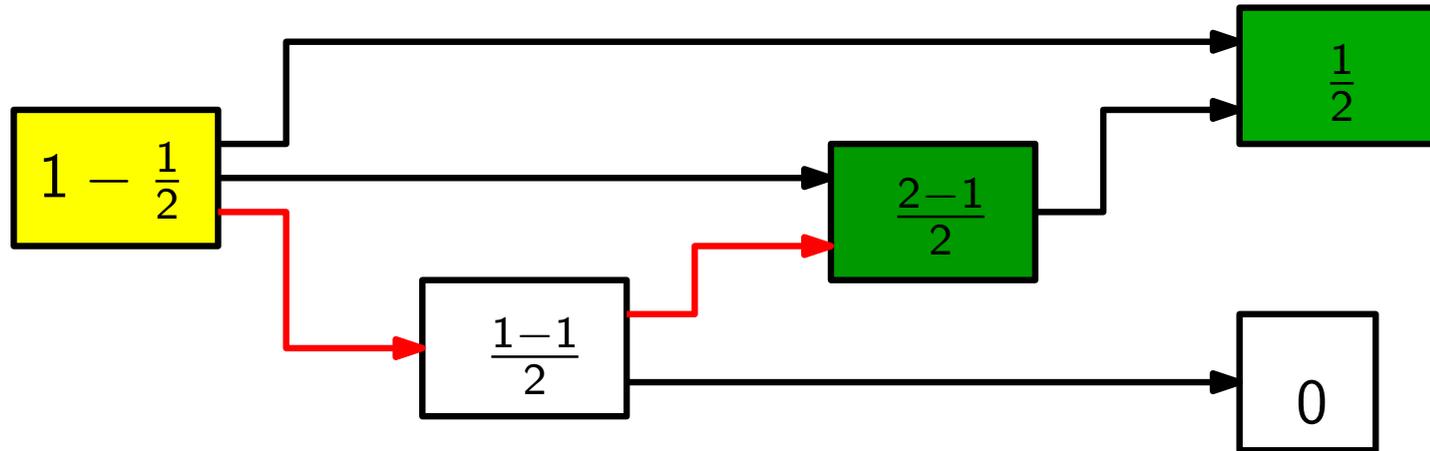
# Motivation – Calculation Graphs

- directed graph of calculation steps



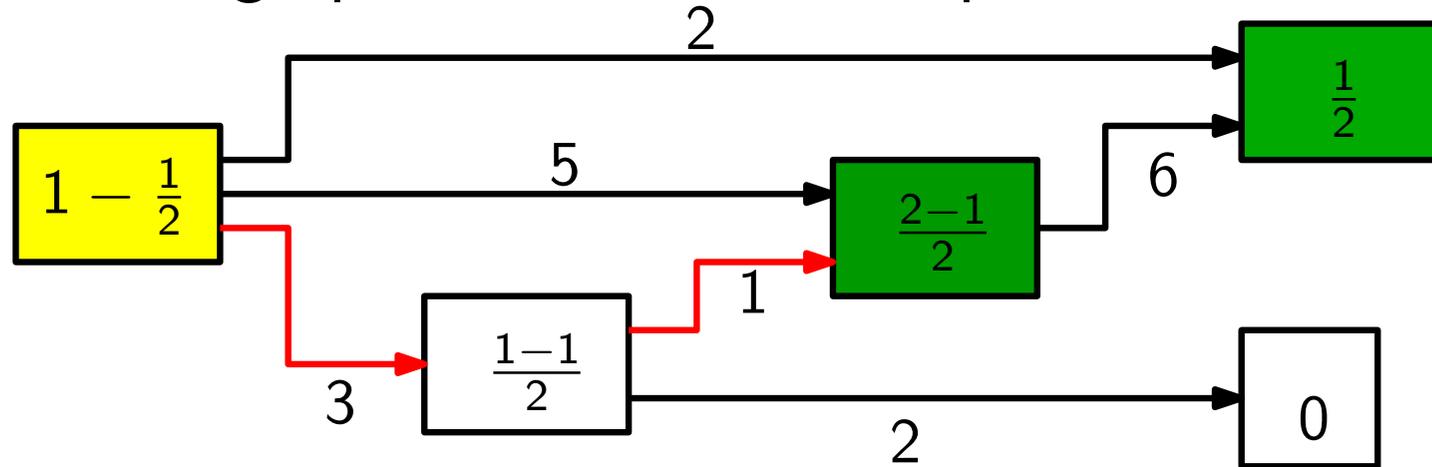
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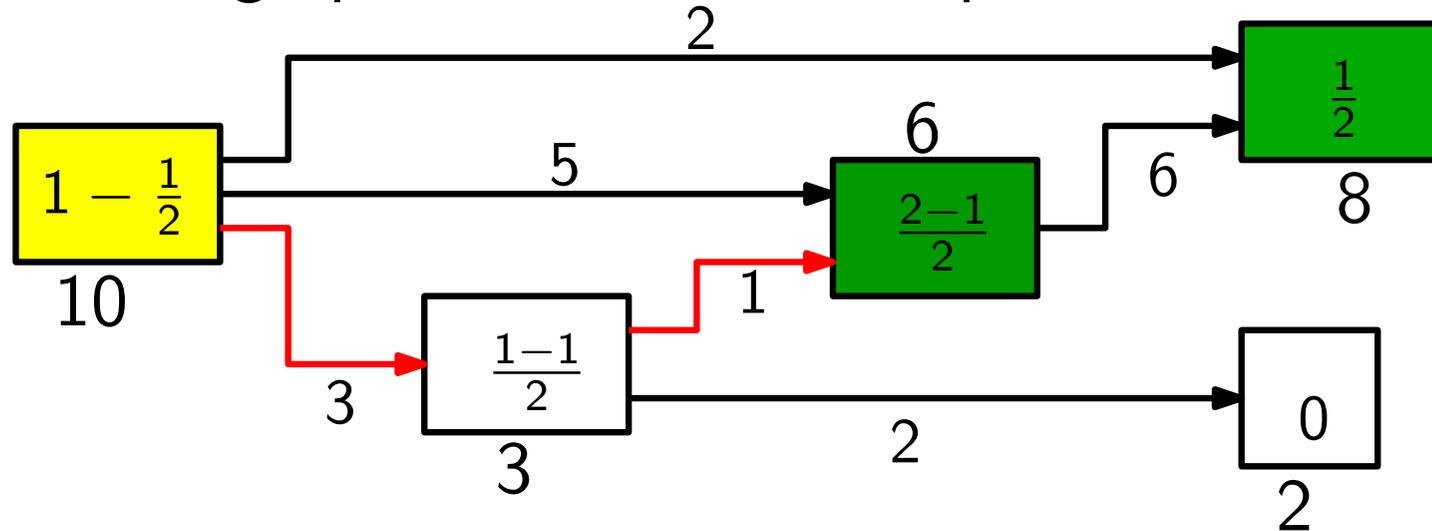
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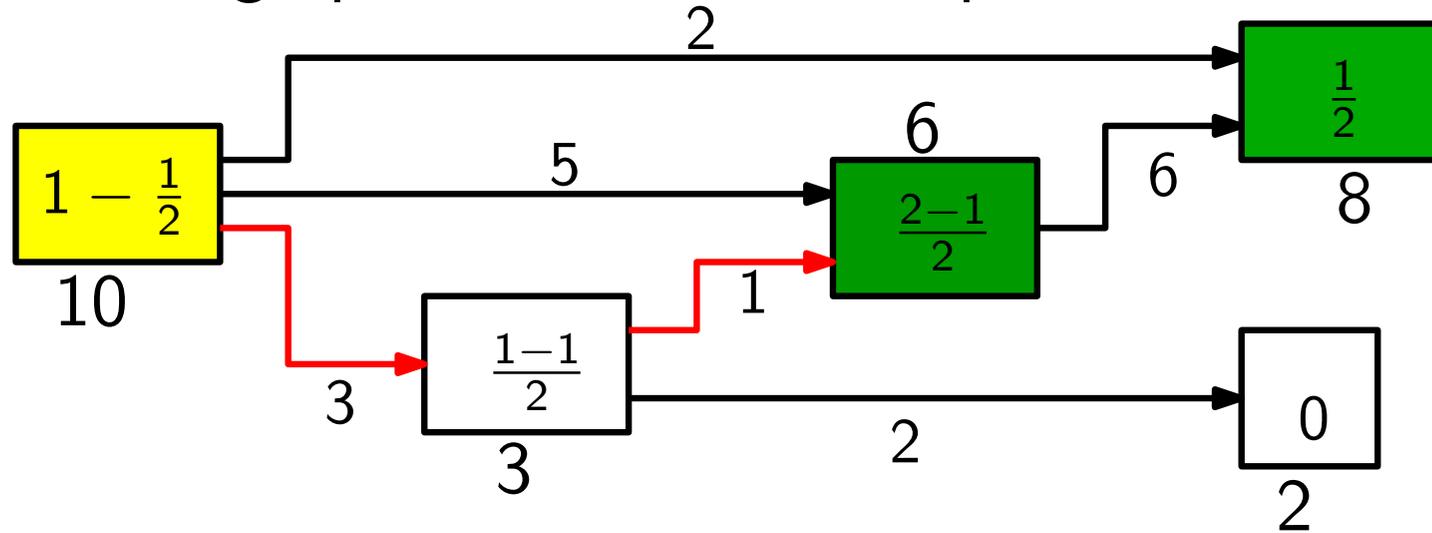
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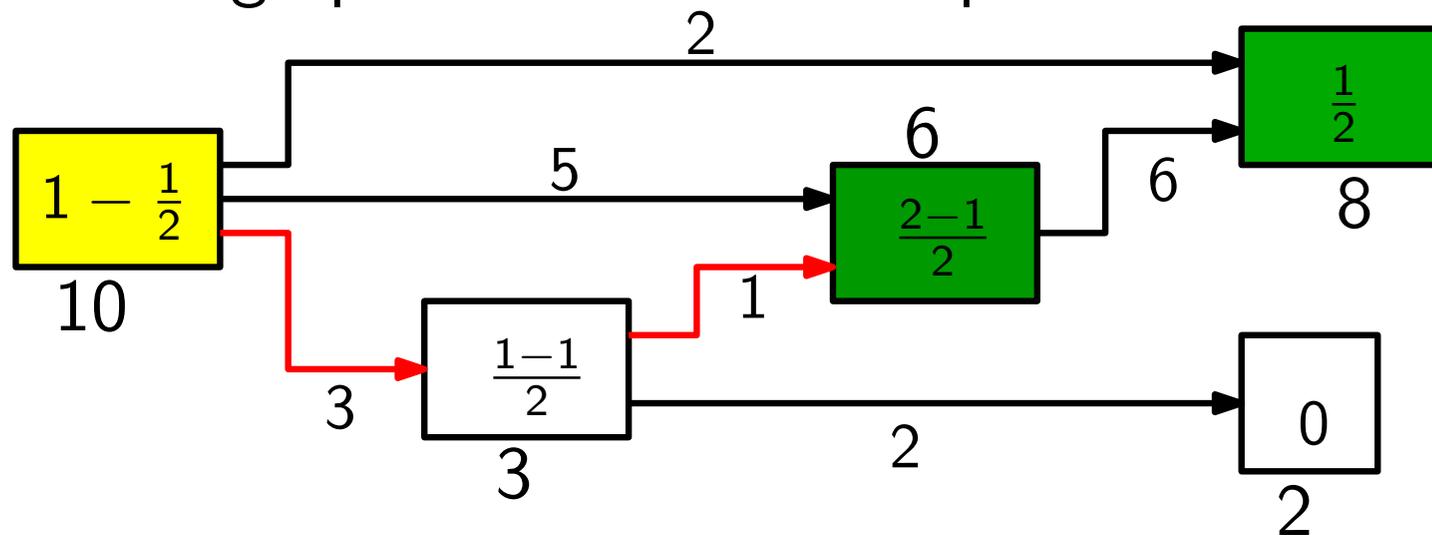
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- often very large (500 – 1000 vertices)

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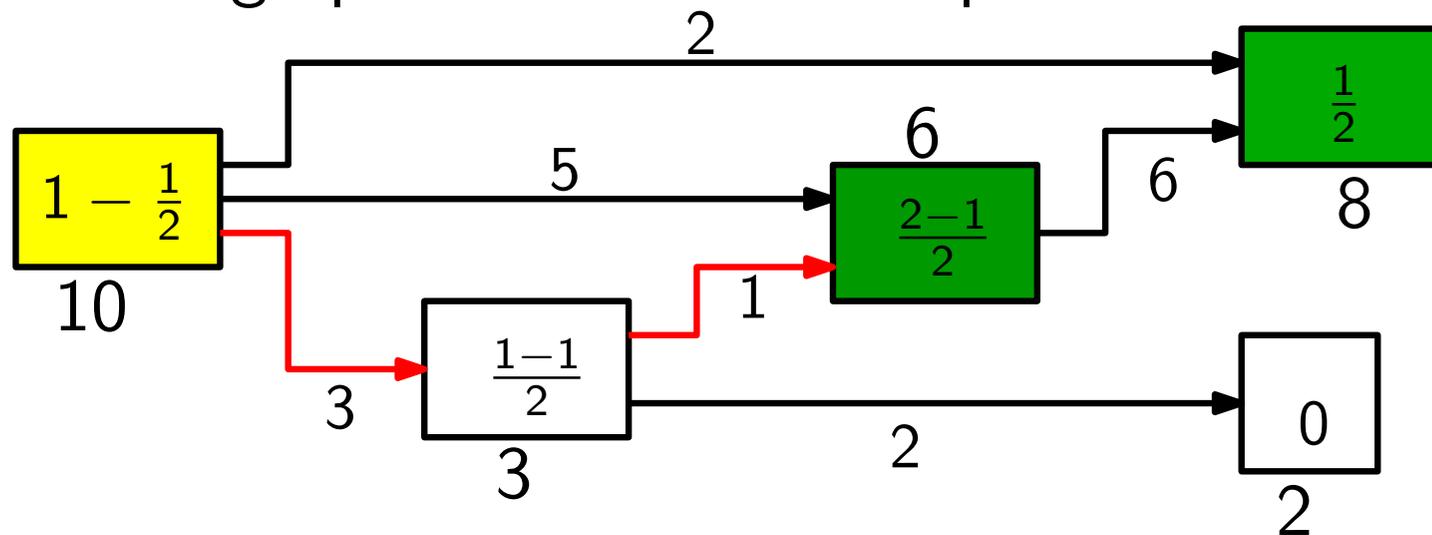


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task: allow human expert to analyze for typical calculation steps and frequent mistakes

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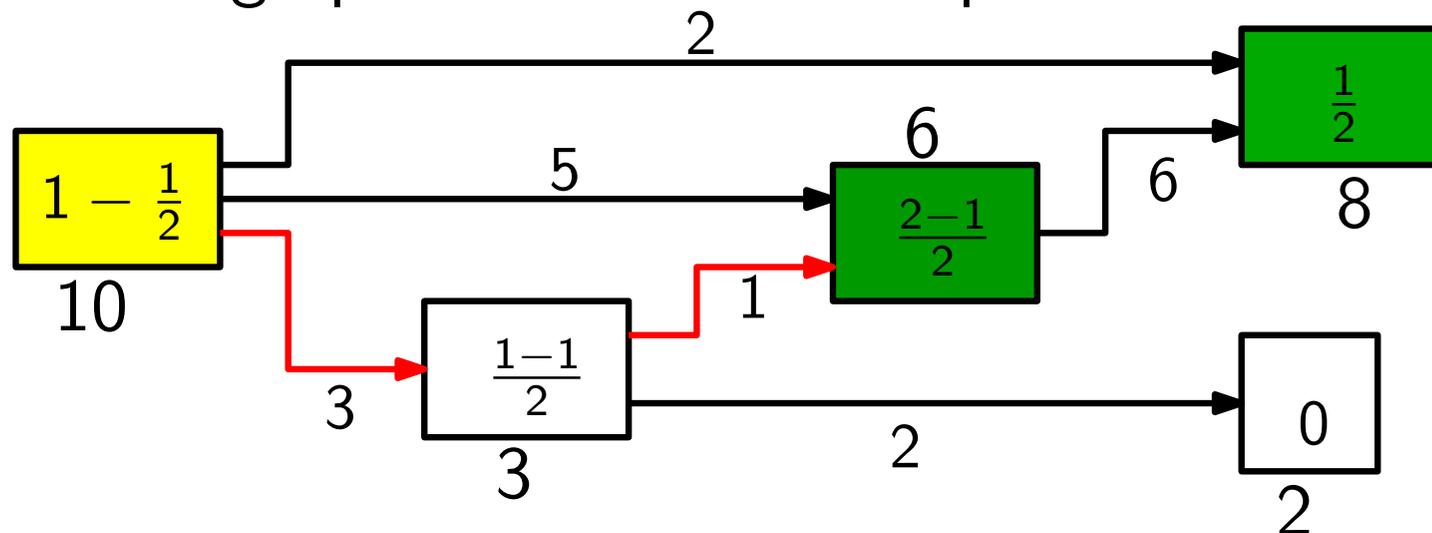


- source: studies with many students
- draw heavy subgraph in prescribed drawing area
- – given vertex sizes

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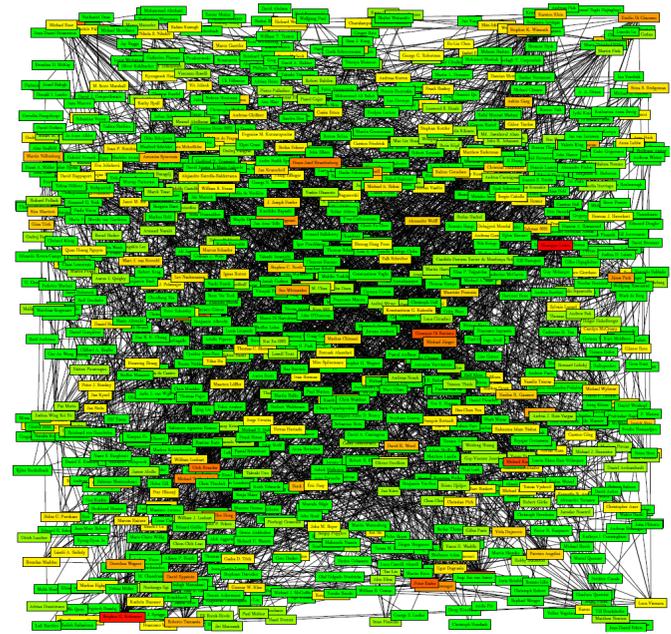
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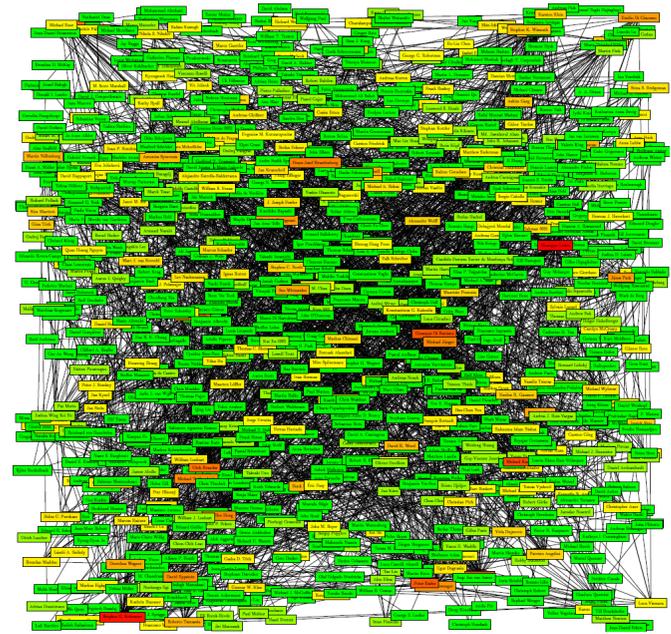
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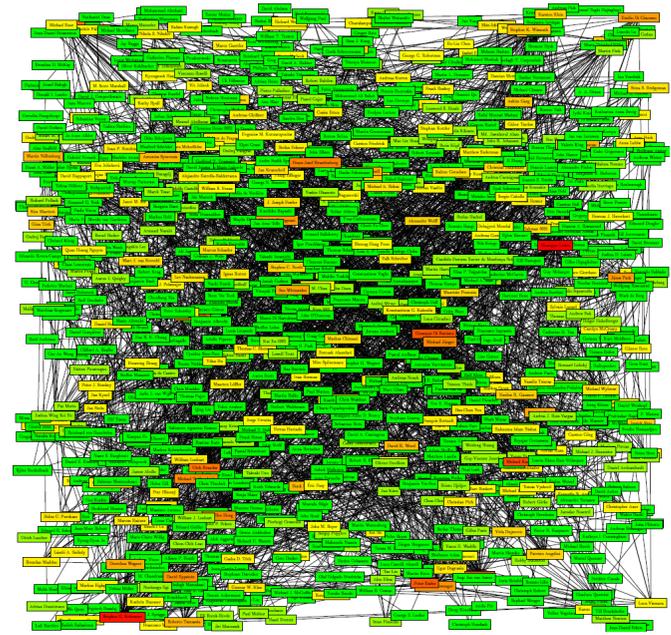
example: invited talk yesterday



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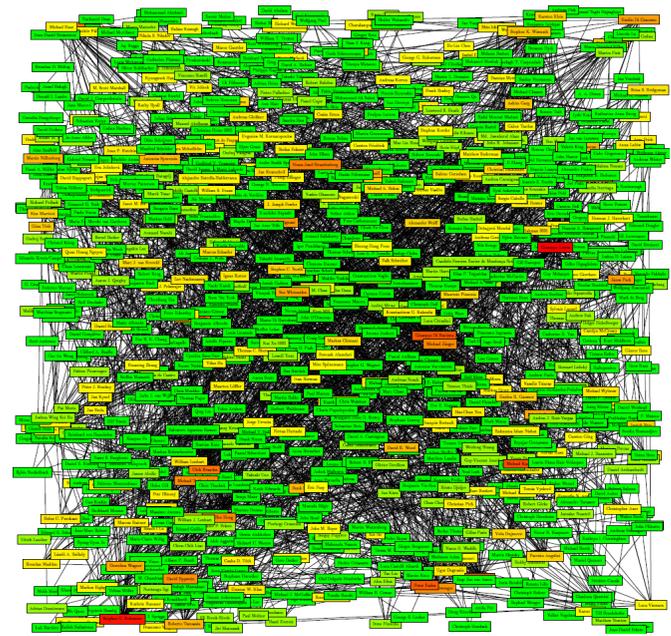
Input:

- weighted graph  $G = (V, E)$
- vertex sizes  $w(v)$  and  $h(v)$  for each  $v \in V$
- prescribed drawing area of width  $W$  and height  $H$

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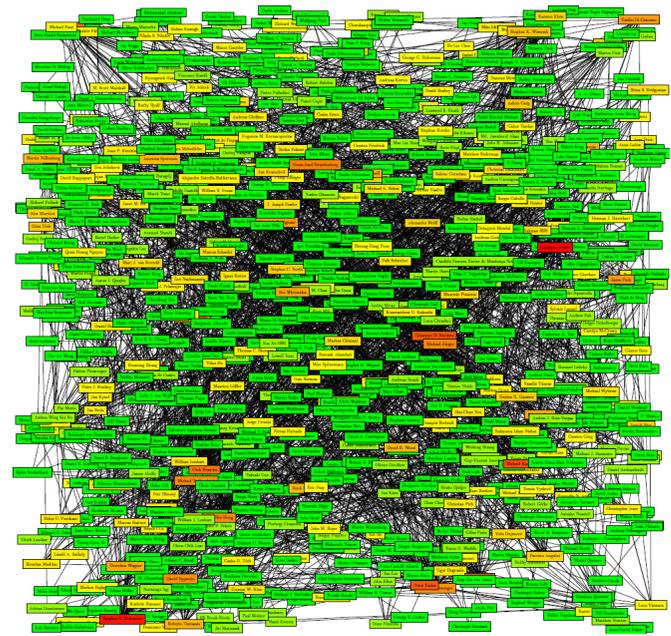
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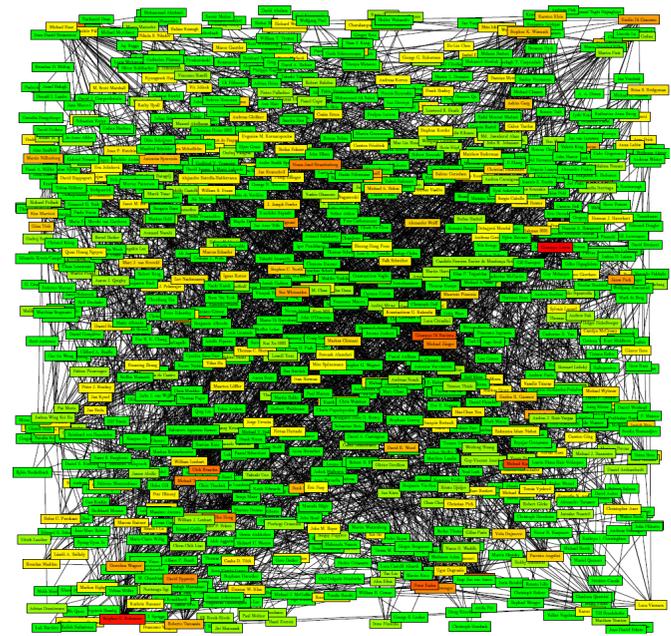
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We present heuristics for

- calculation graphs
- straight-line drawings of general weighted graphs

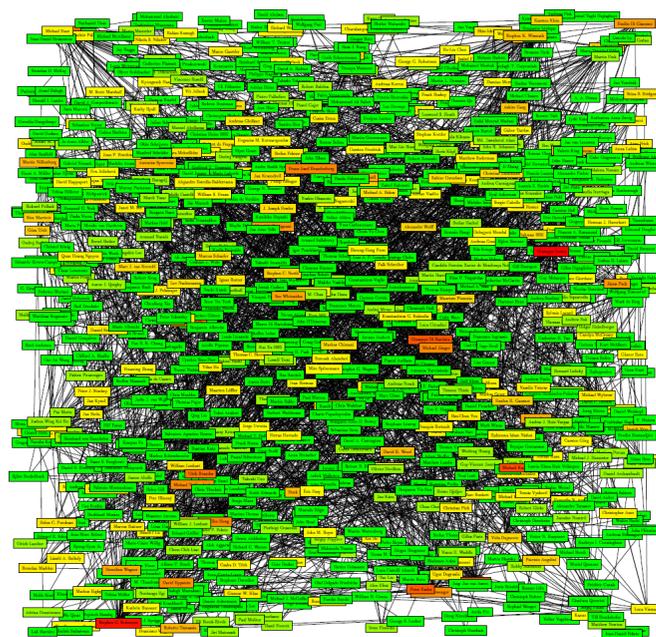
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# Related Work

- [Fruchterman, Reingold 1991]:  
prescribed rectangular drawing area  
but: vertices can be made arbitrarily small

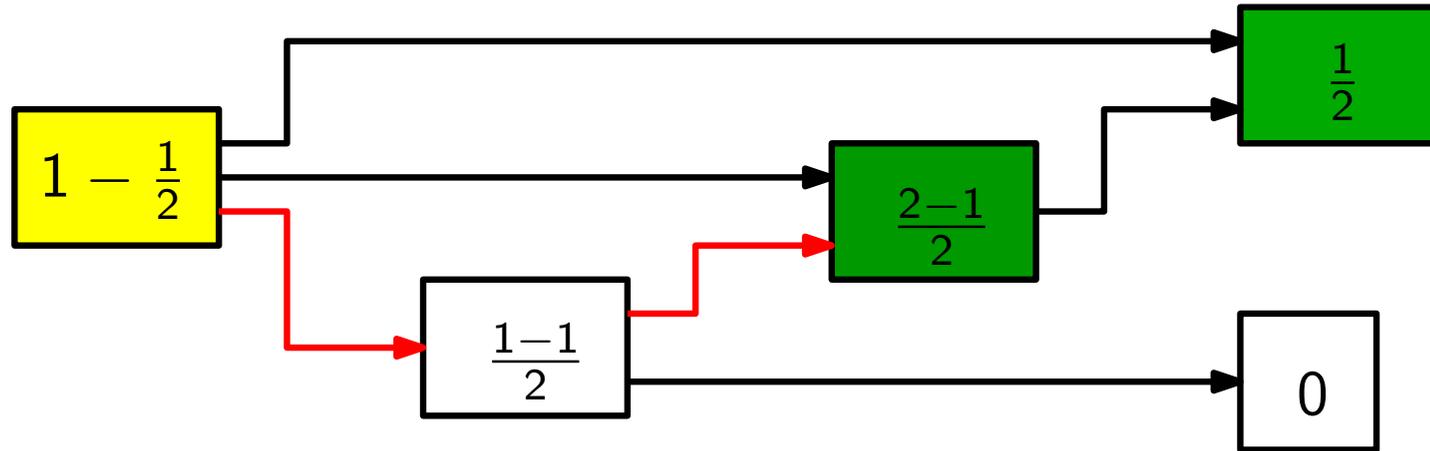
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- [Fruchterman, Reingold 1991]:  
prescribed rectangular drawing area  
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- constrained graph layout, e.g., [Dwyer et al. 2006]:  
constrain vertex position to prescribed rectangle  
but: no strategy for dropping vertices

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constrain vertex position to prescribed rectangle  
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- interactive methods for graph exploration:
  - [Dwyer et al. 2008]: overview+detail
  - [Da Lozzo et al. 2011]: graph exploration on smartphone

# Drawing Calculation Graphs



- hierarchical drawing (left to right)
- start vertex left
- orthogonal edges

# Calculation Graphs – Our Approach

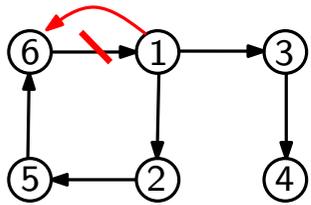
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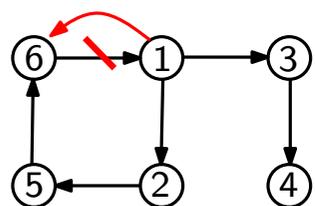
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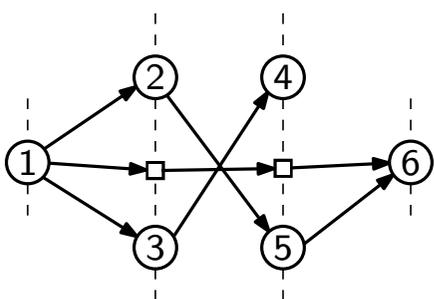
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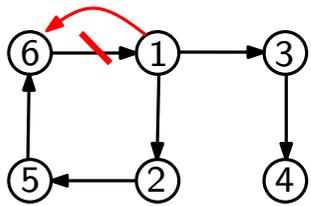
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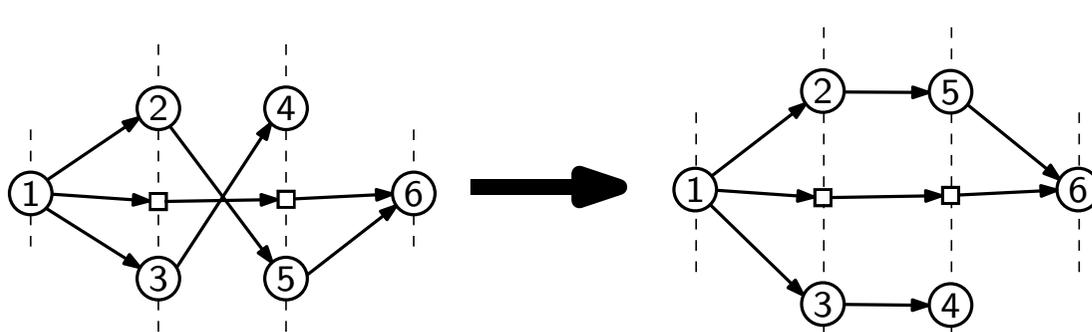
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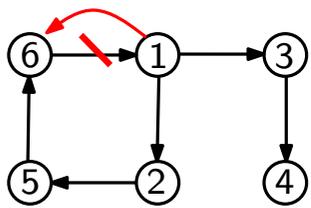


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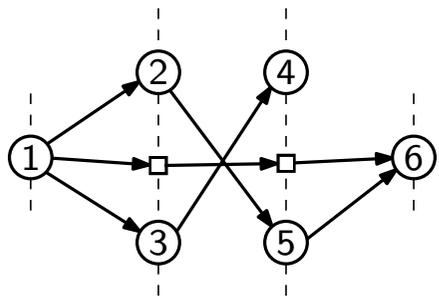
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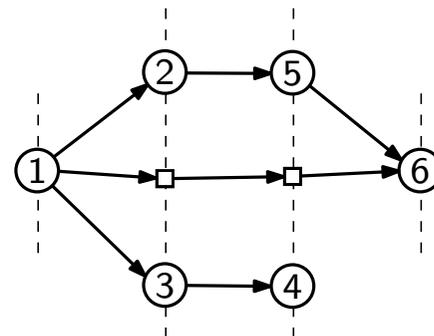
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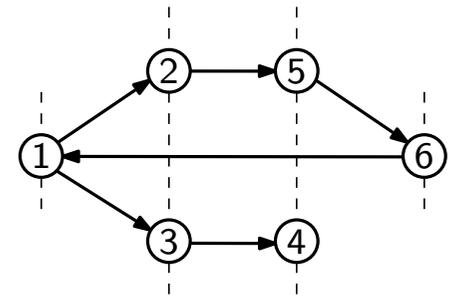
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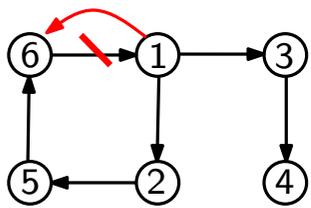


edge routing

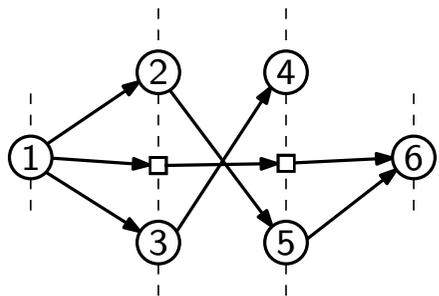


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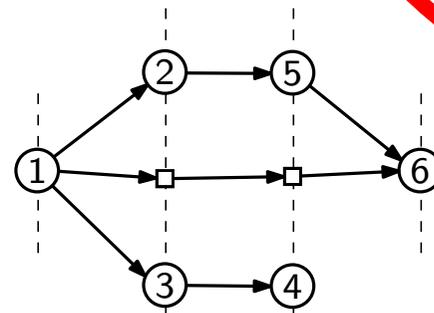
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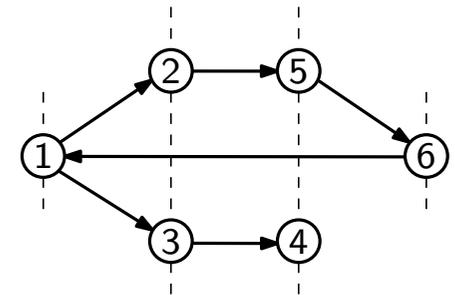
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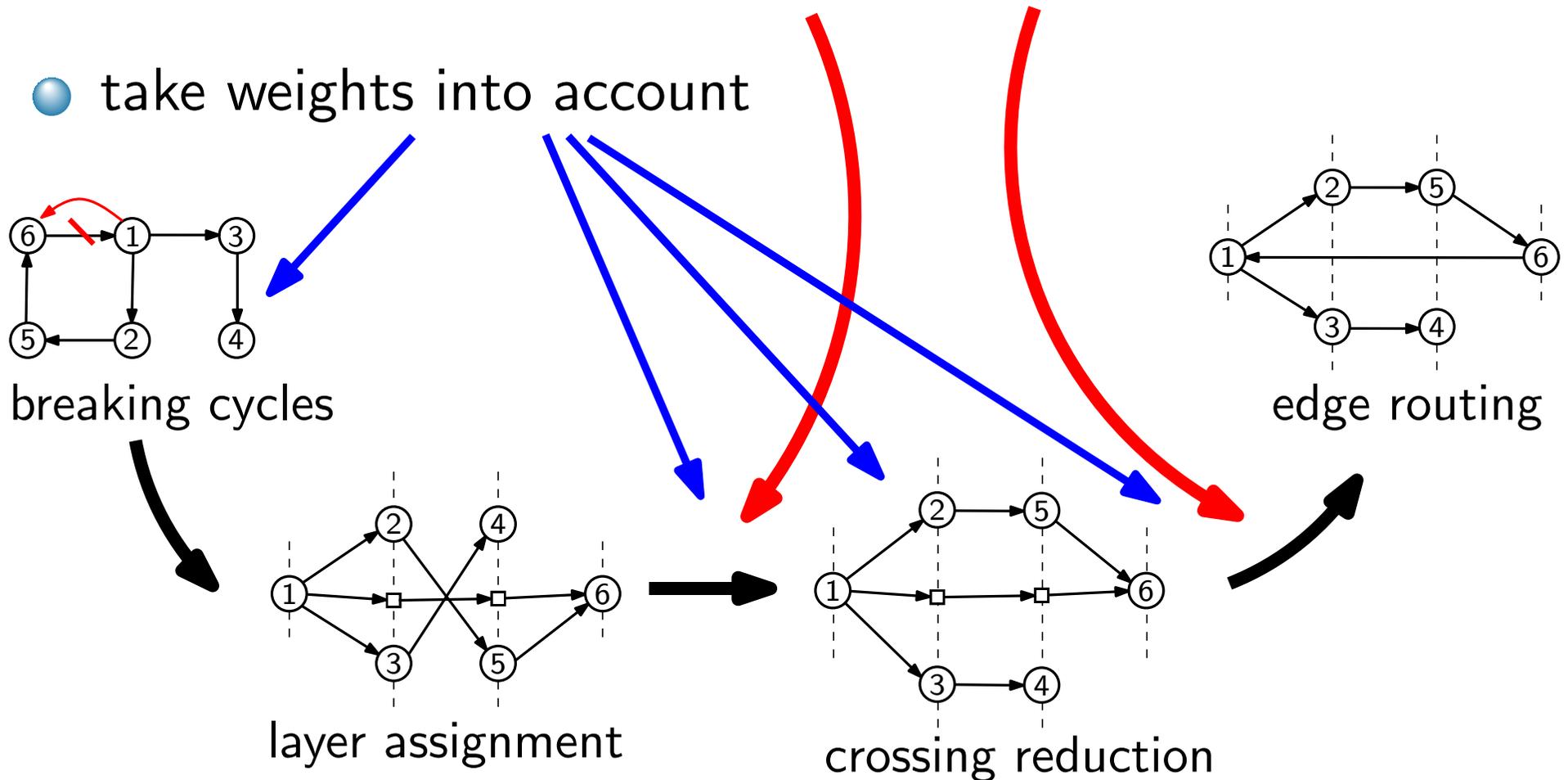
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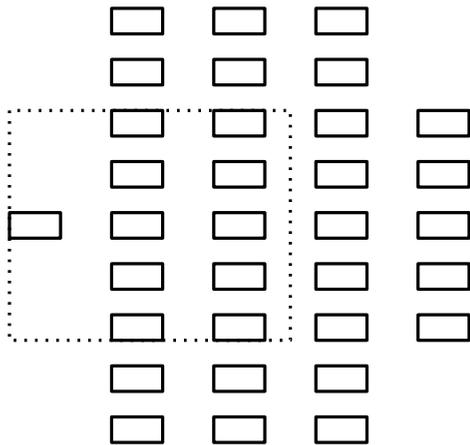


# Our Adjustments

- breaking cycles: minimize **weight** of reverted edges  
can afford ILP solution

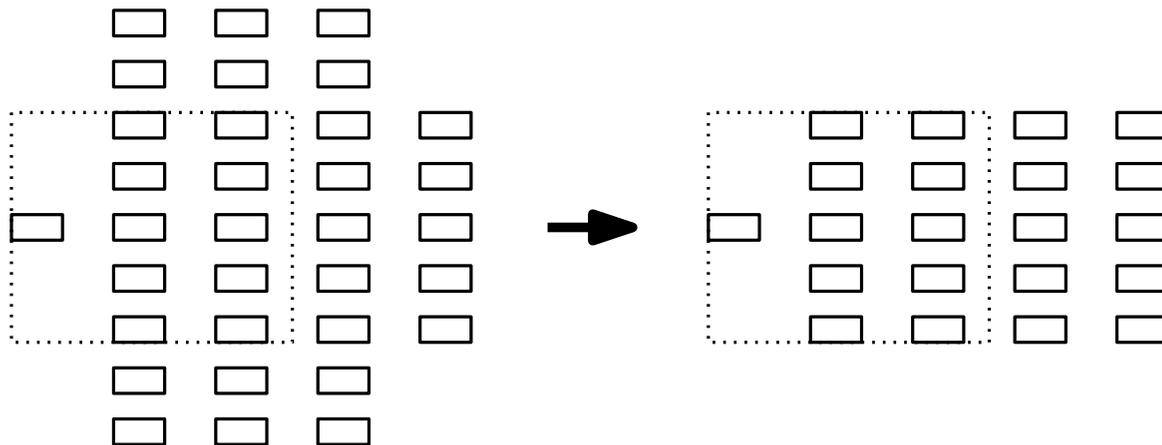
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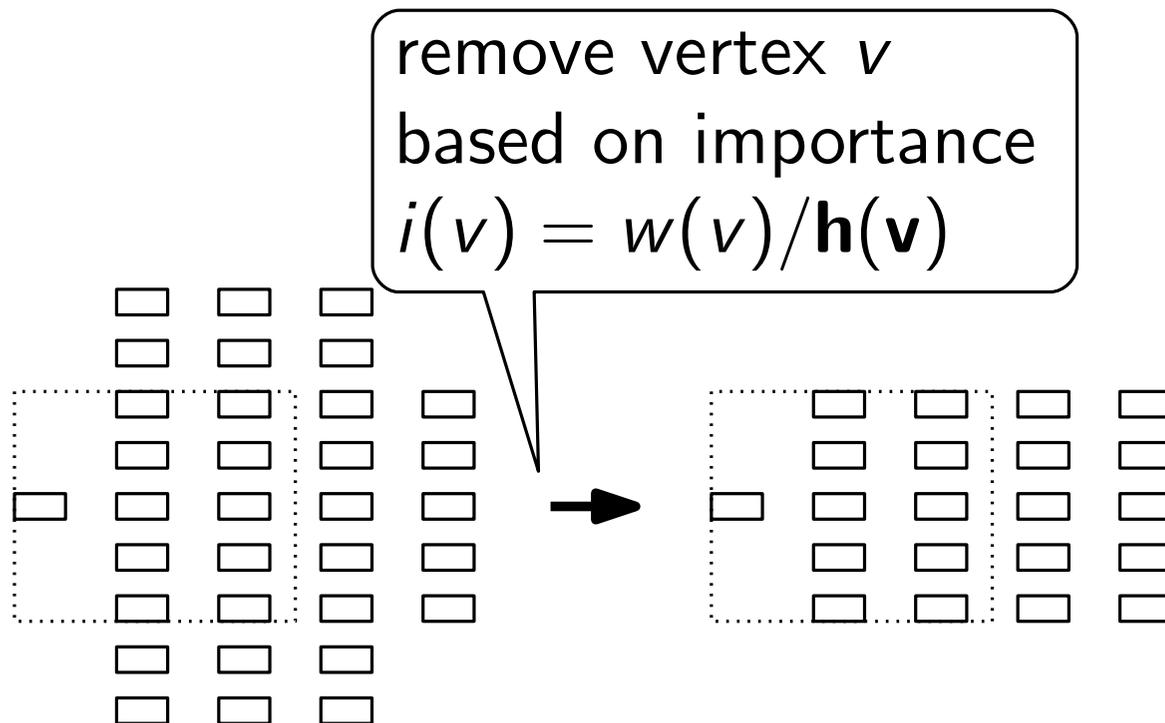
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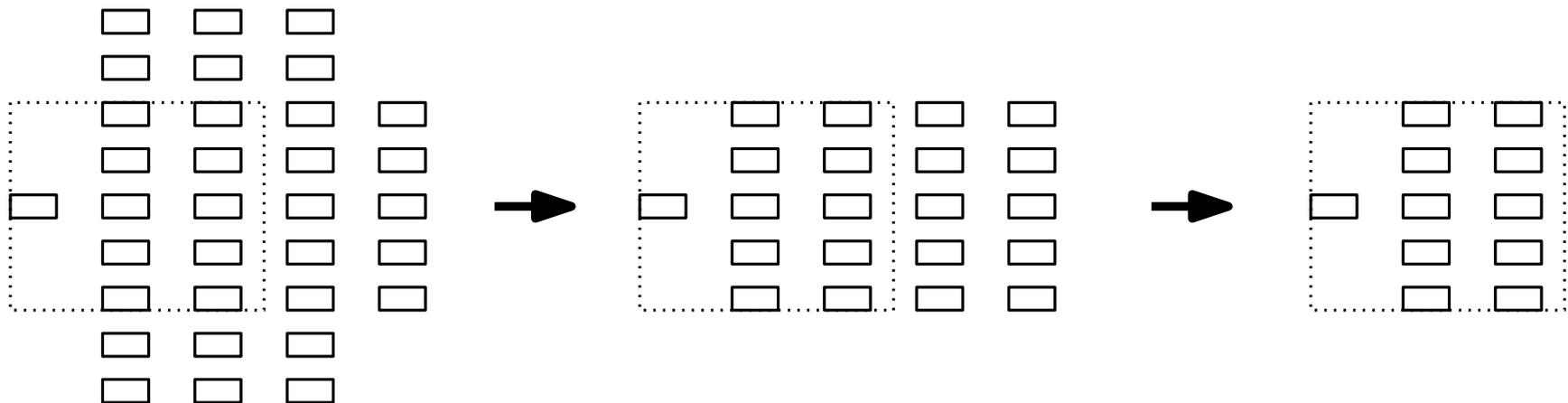
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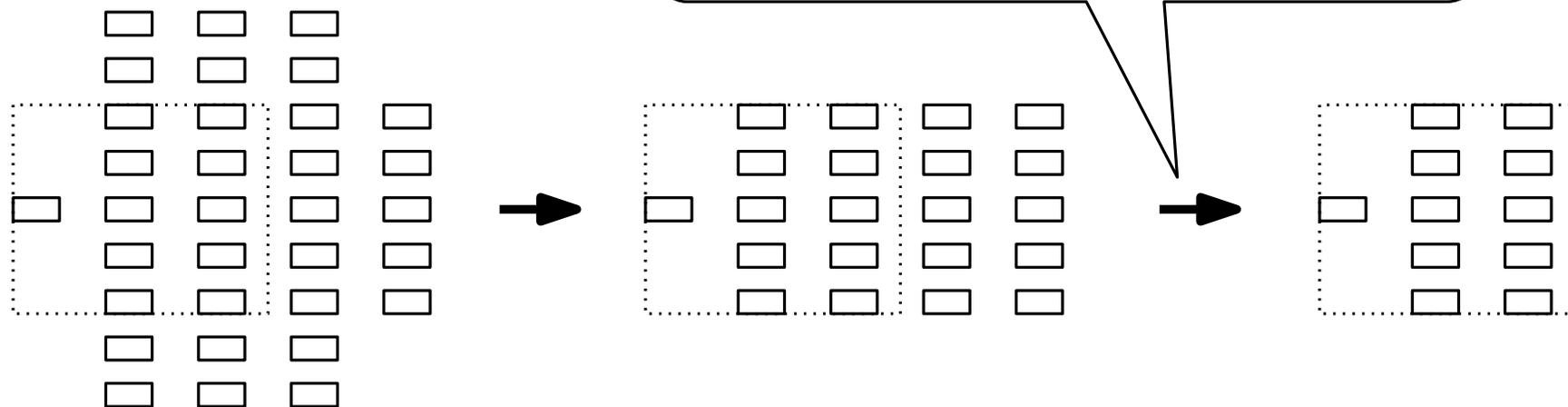


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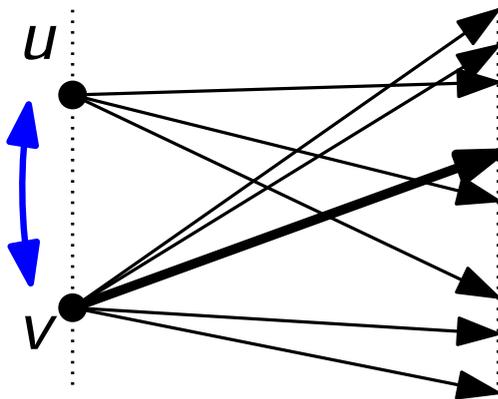
remove layer  $L$  based on importance

$$i(L) = \sum_{v \in L} w(v) / \text{width}(L)$$



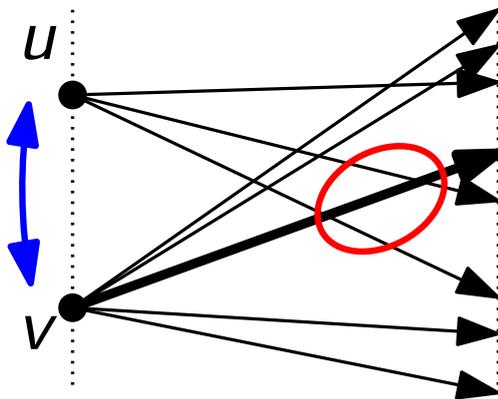
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higher cost for crossing heavy edge

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- too many crossings: remove edge  $e$  based on importance

$$i(e) = \frac{w(e)}{\text{total weight of edges crossing } e}$$

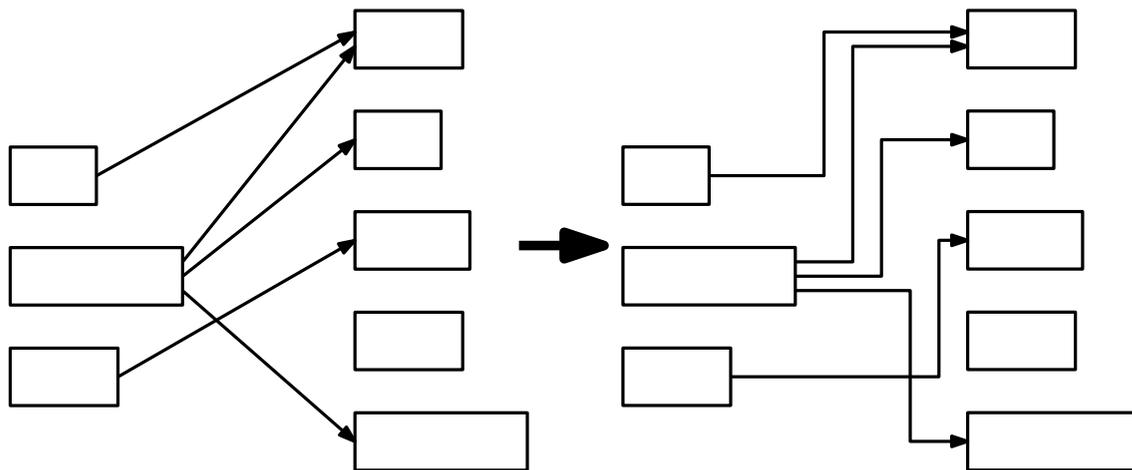
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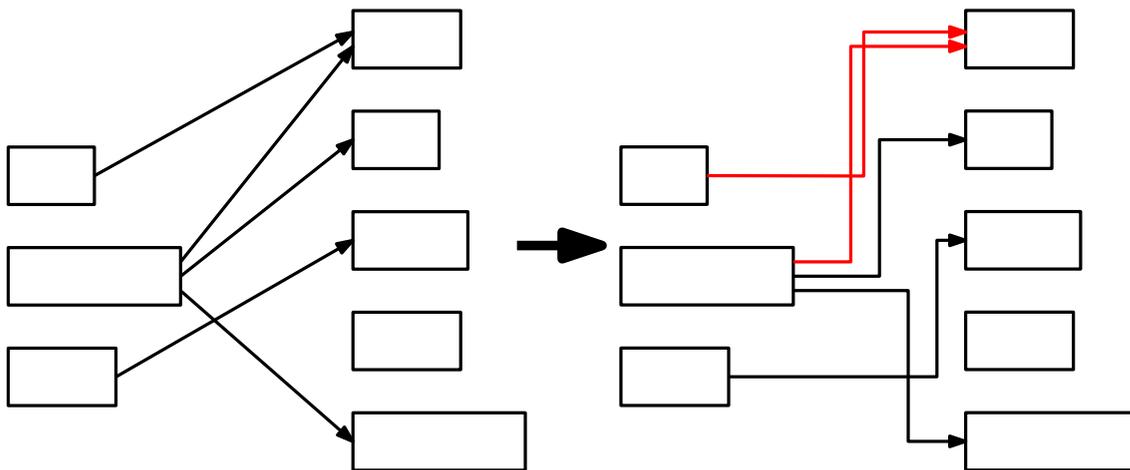
# Edge Routing

- place vertical segments between consecutive layers



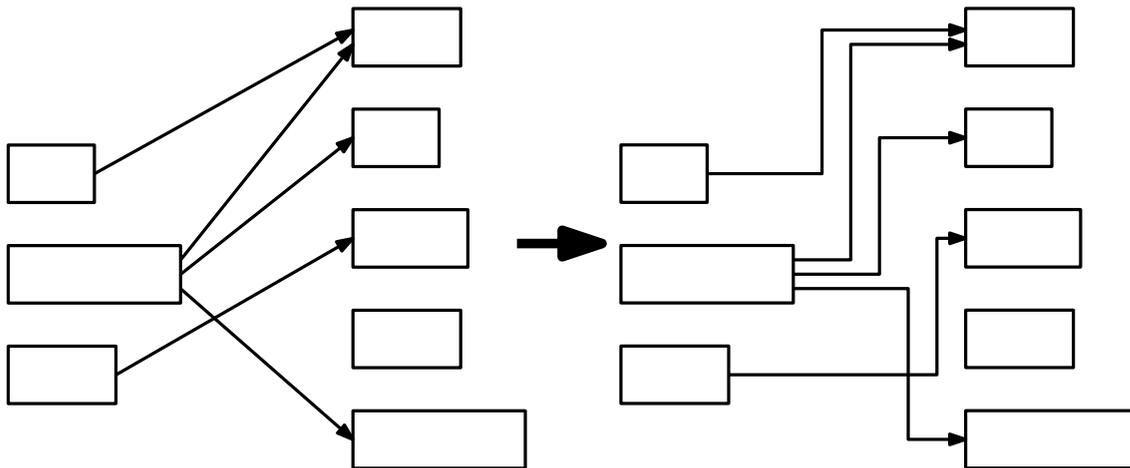
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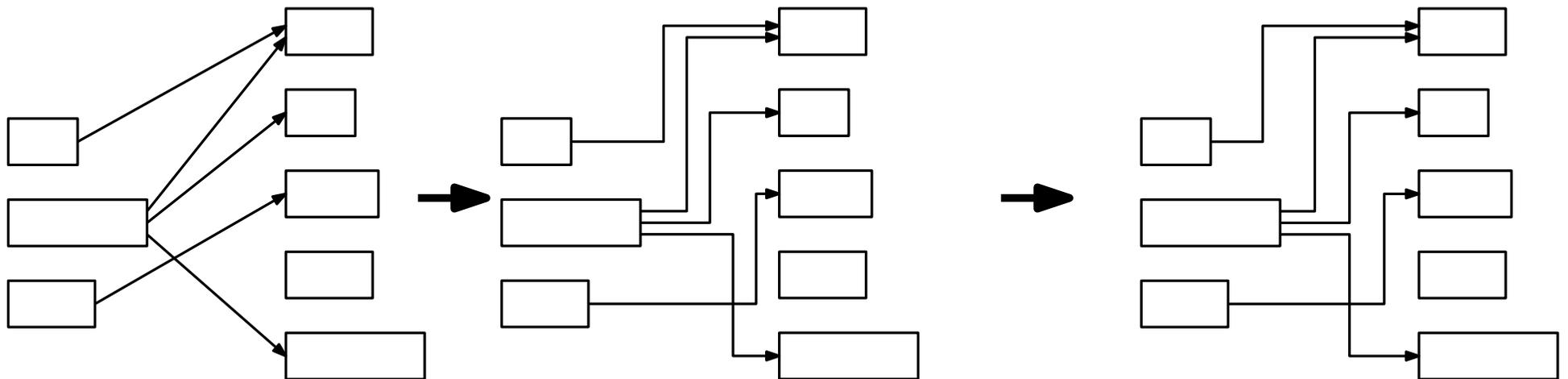
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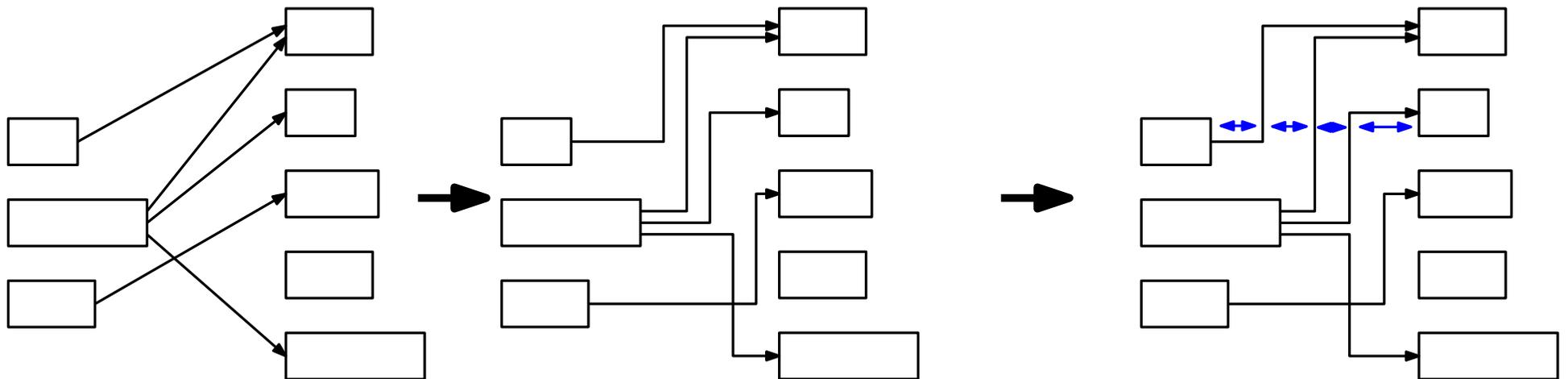
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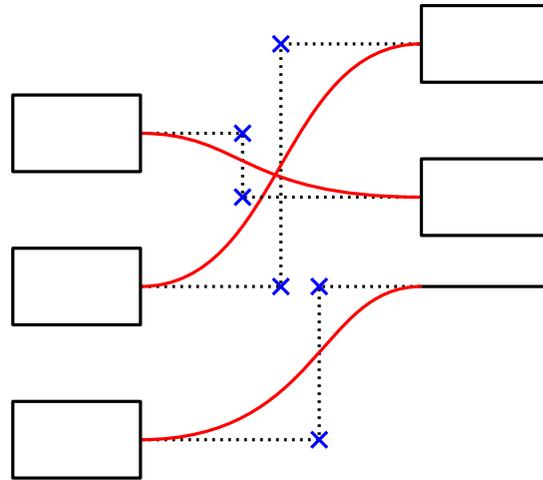
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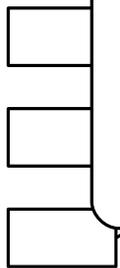


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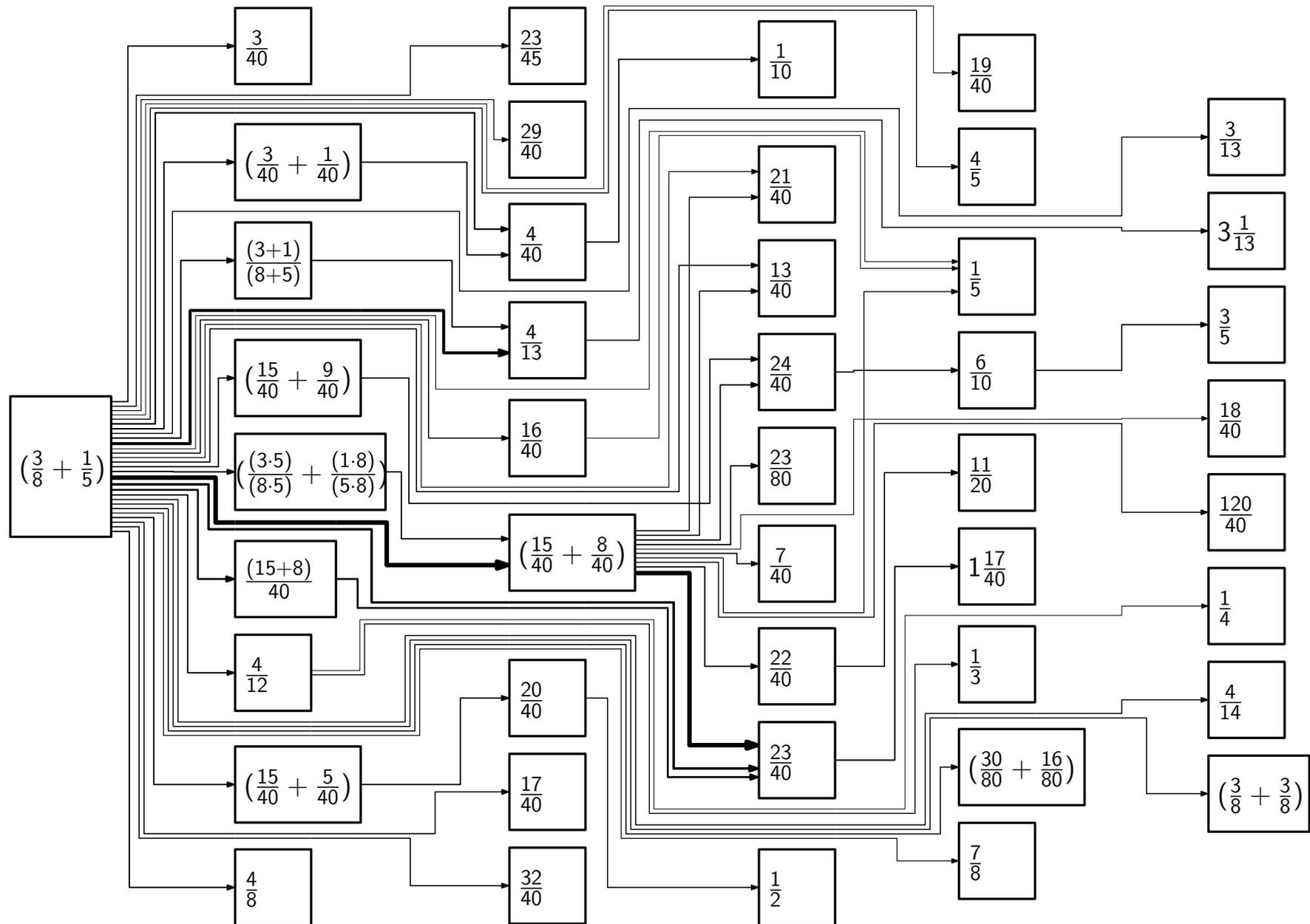
- Extension: Bézier Curves



## Improved Routing

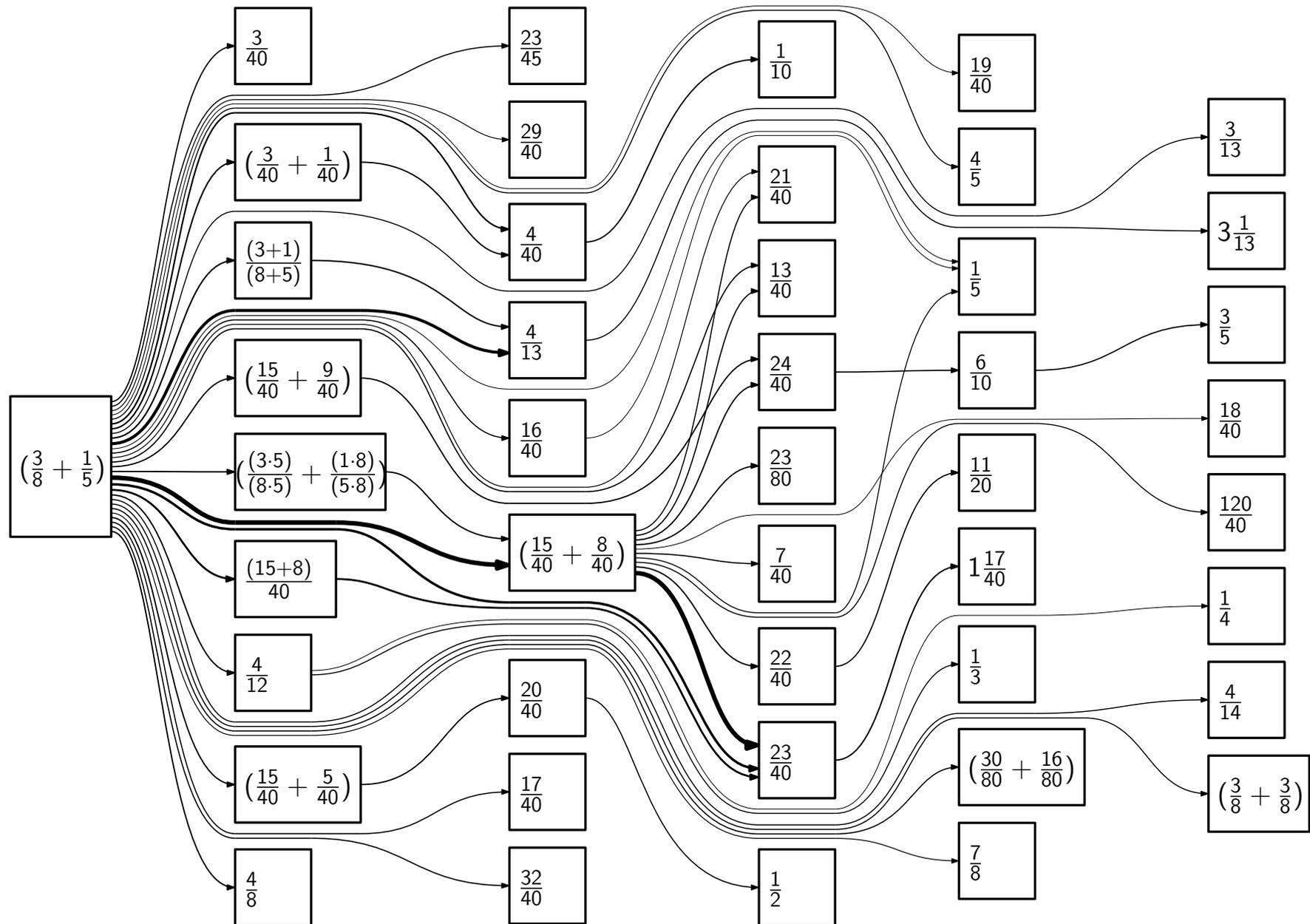


# Example



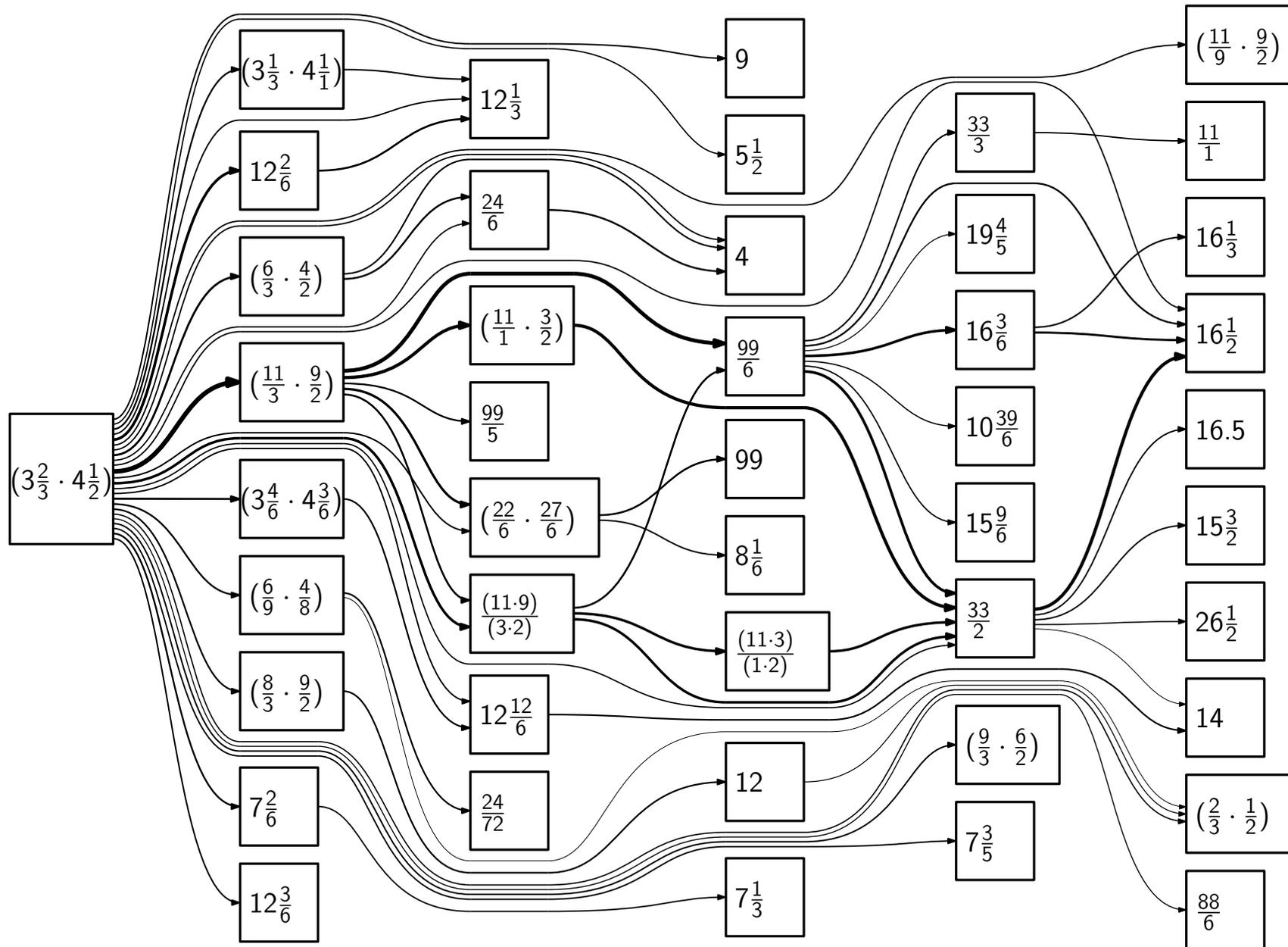
38 of 358 vertices (10.6 %); 91.1 % of the vertex weight

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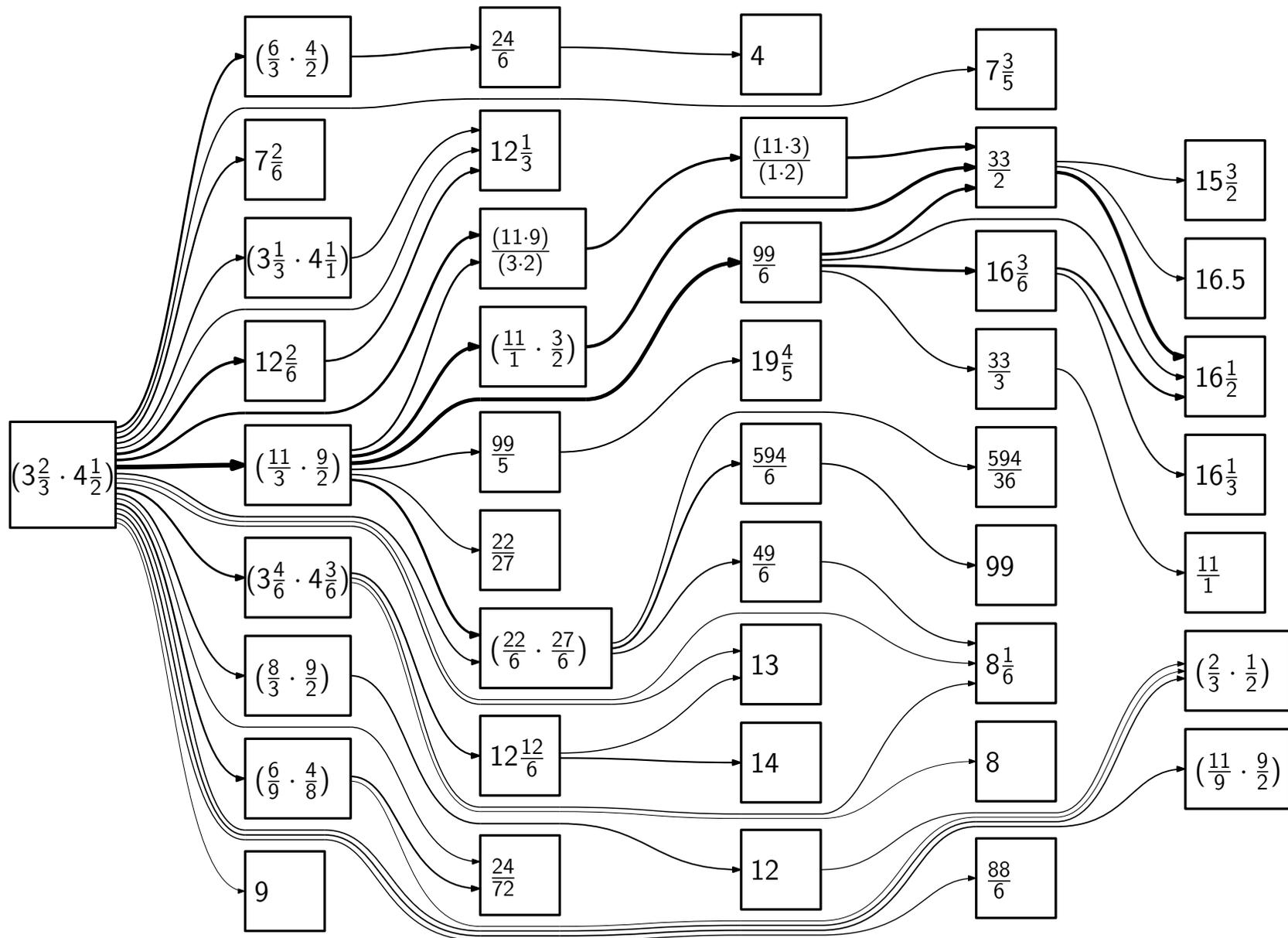
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# Example 2



4.7 % of 1031 vert.; 75.9 % vertex weight; 74.1 % edge weight

# Example 2 – Planar Output



4.3 % of 1031 vert.; 76.6 % vertex weight; 70.2 % edge weight

# Remarks

- runtime for graph with 1031 vertices and 1549 edges to A4 paper:  $\approx 3s$

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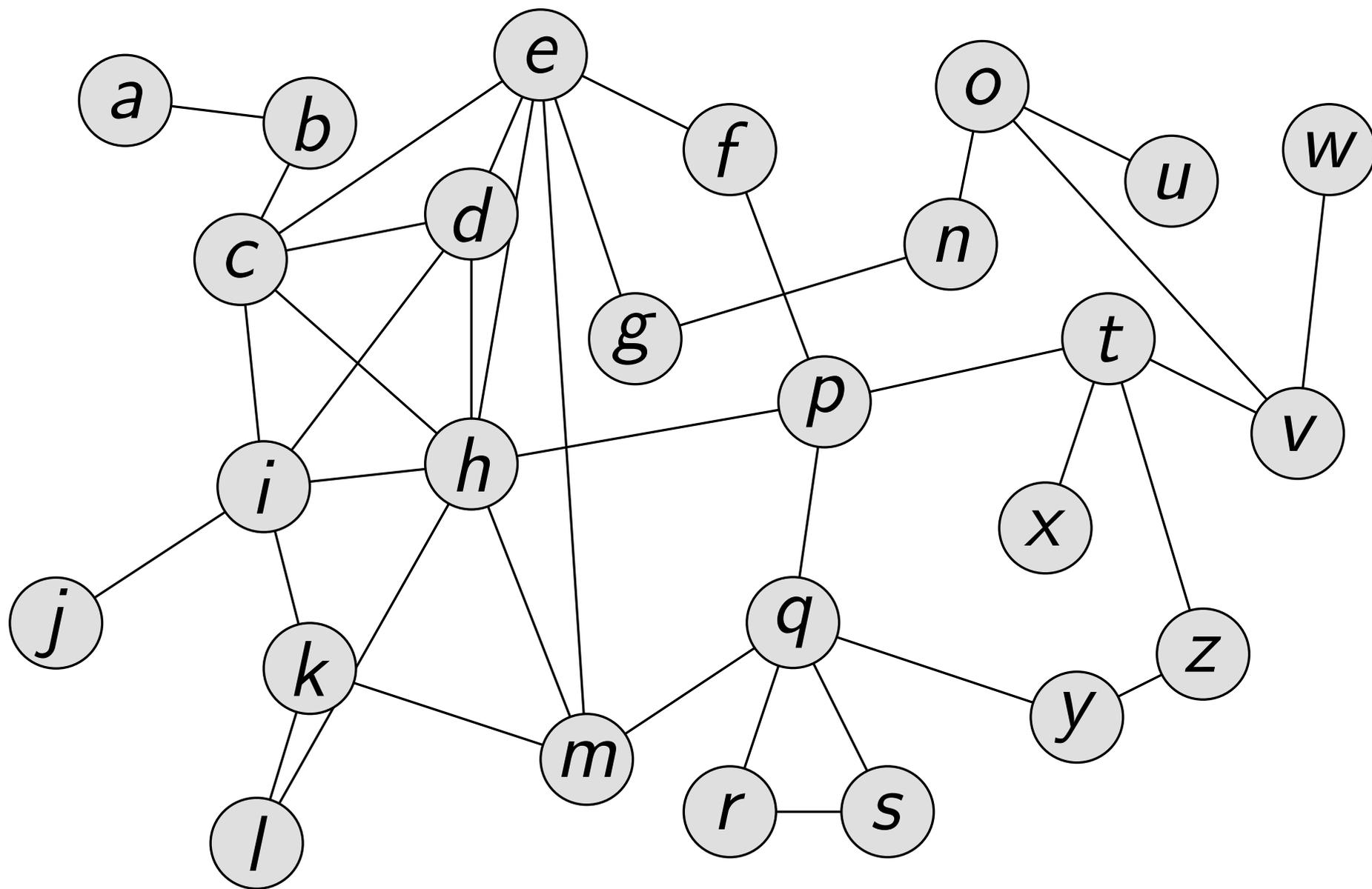
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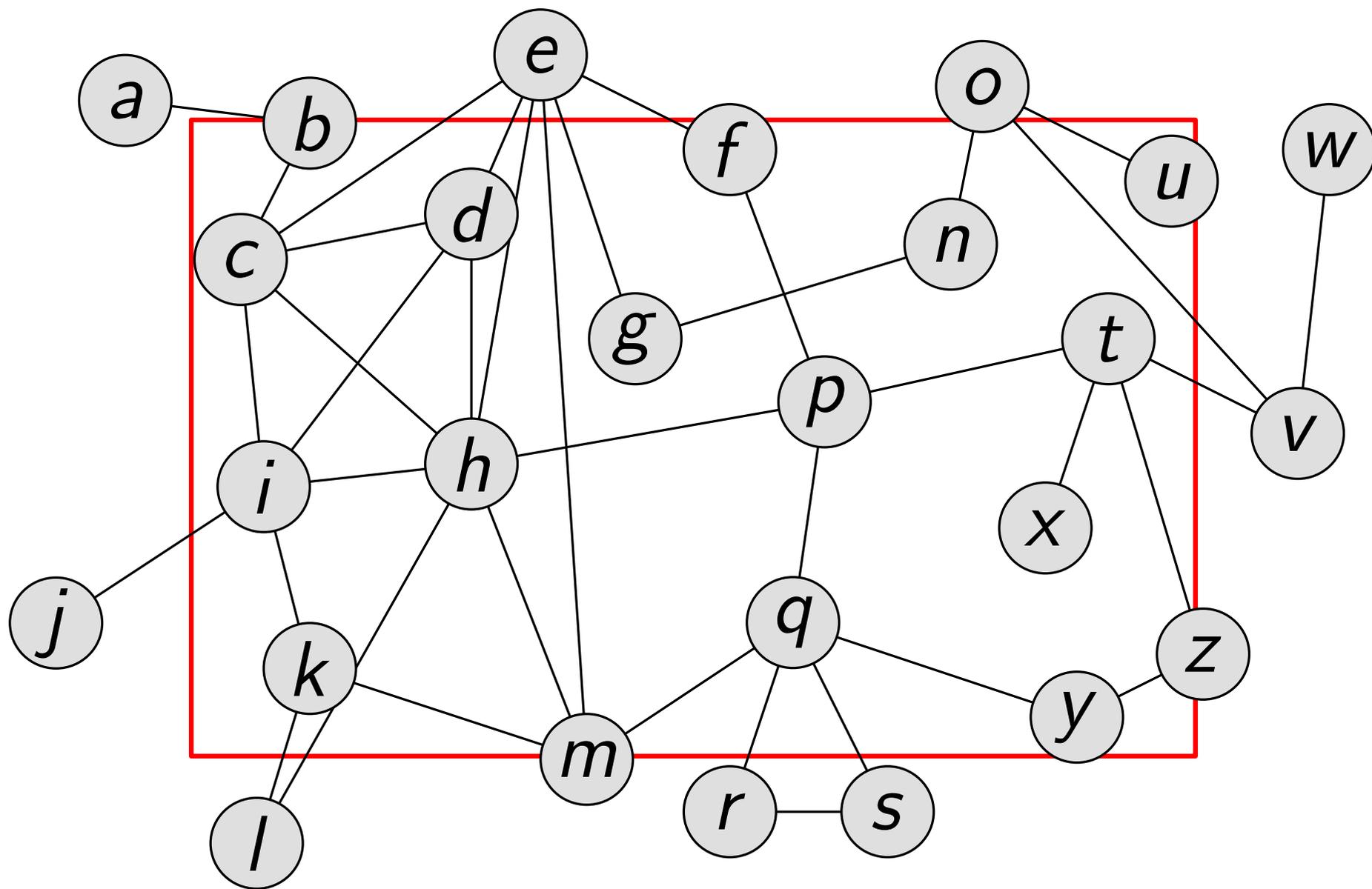
most of it for edge routing

- preprocessing removing very light vertices yielded speedup + heavier outputs
- especially with vertex/edge reinsertion: no significant influence of layer assignment algorithm

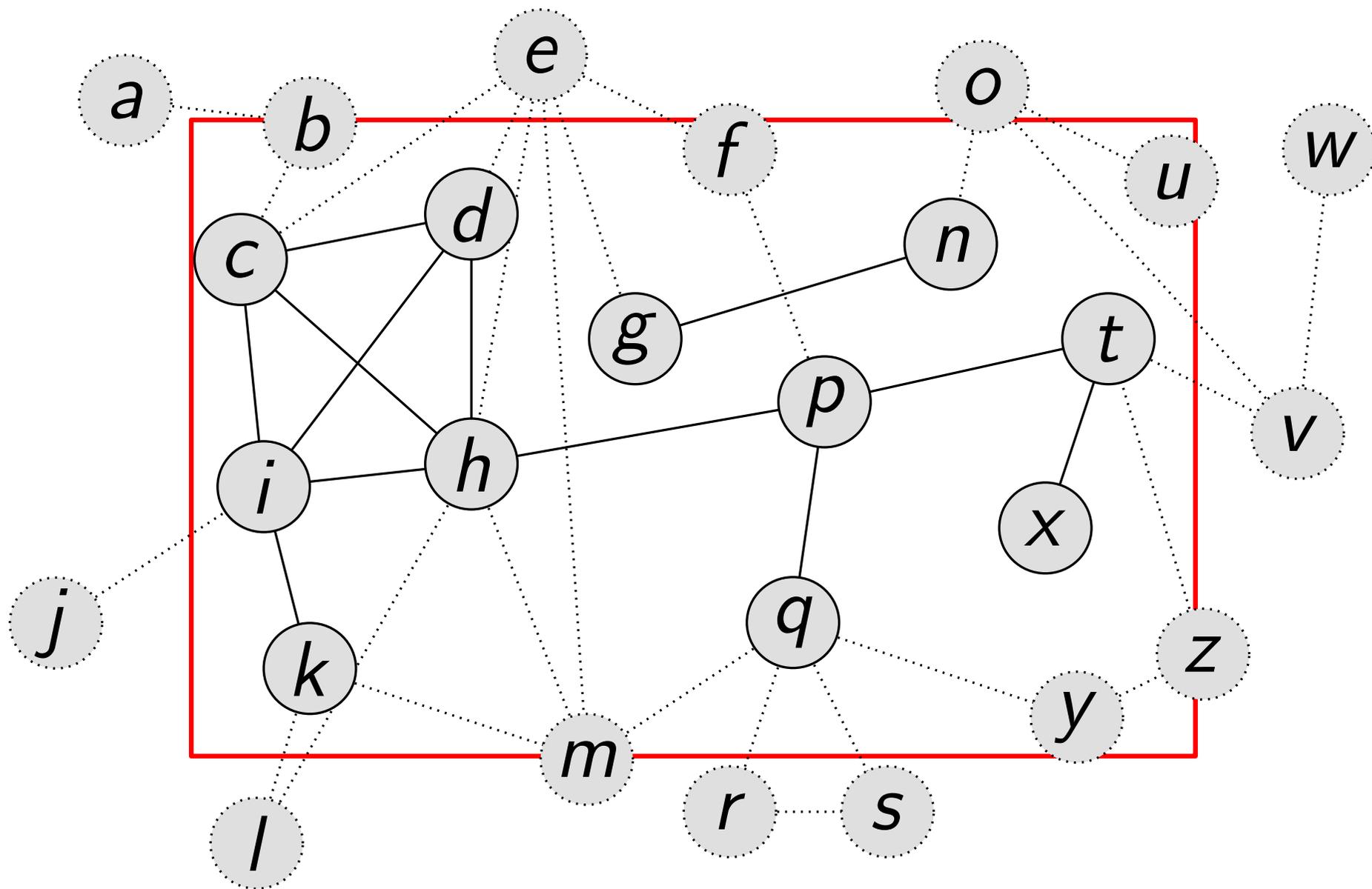
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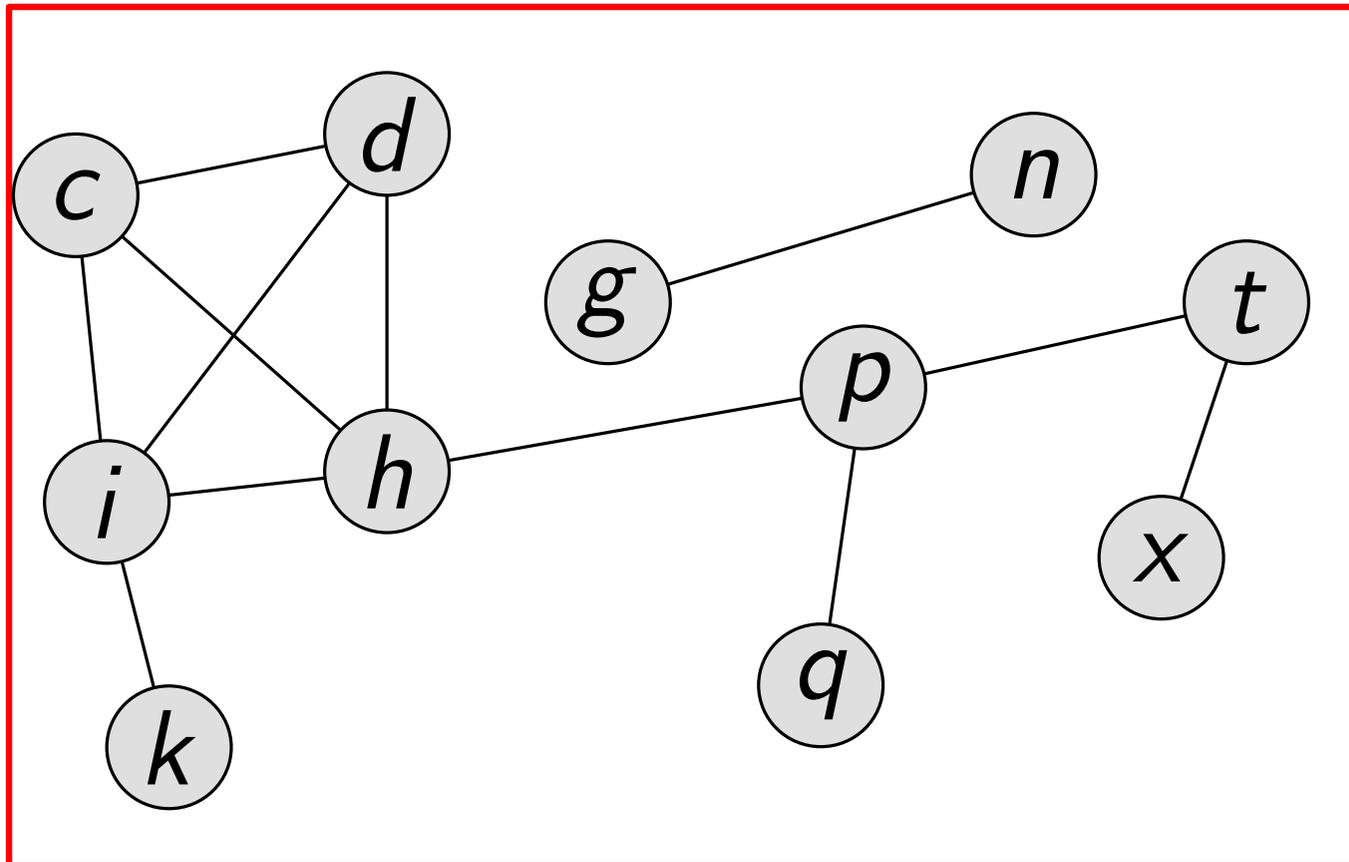
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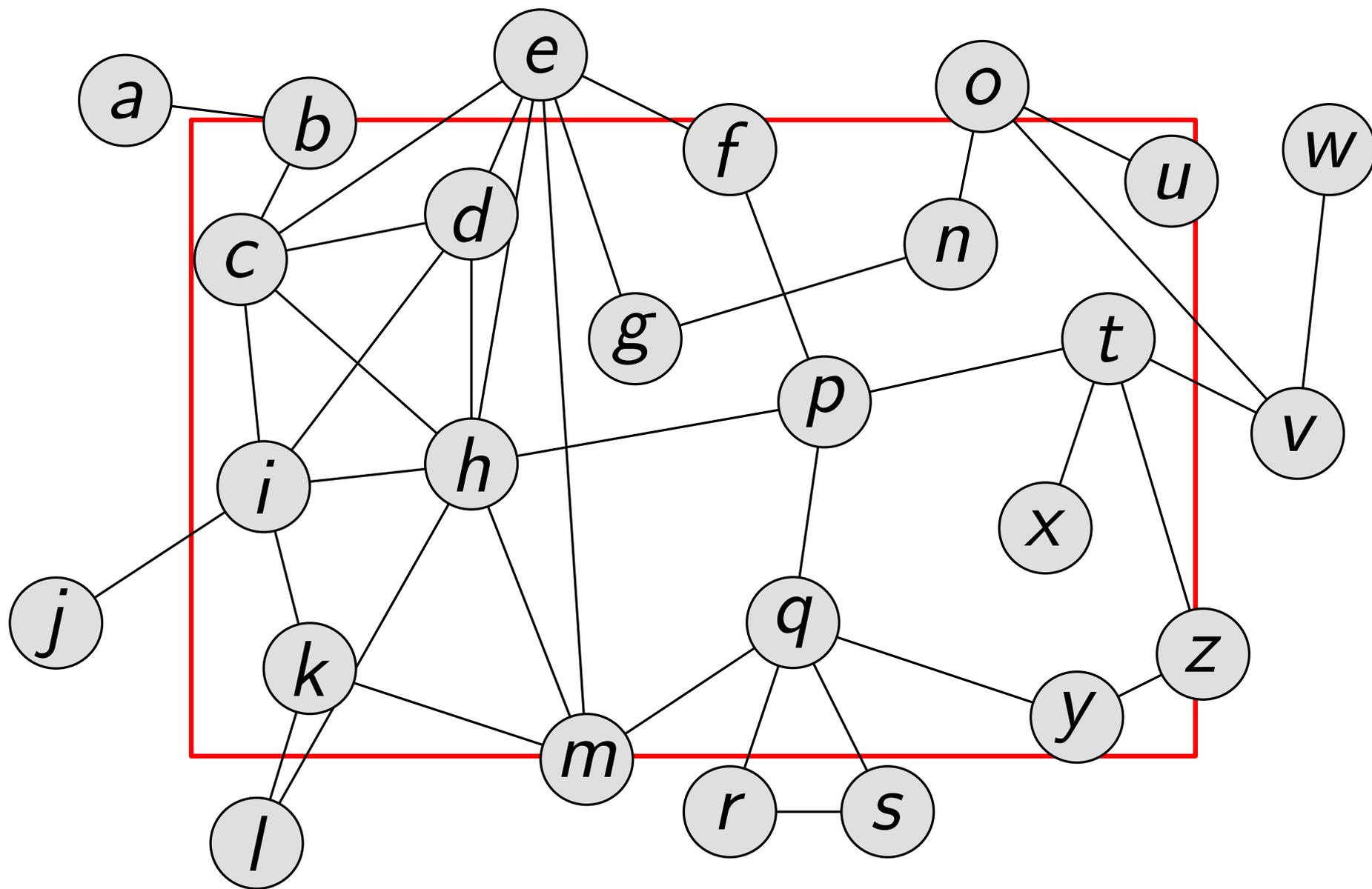
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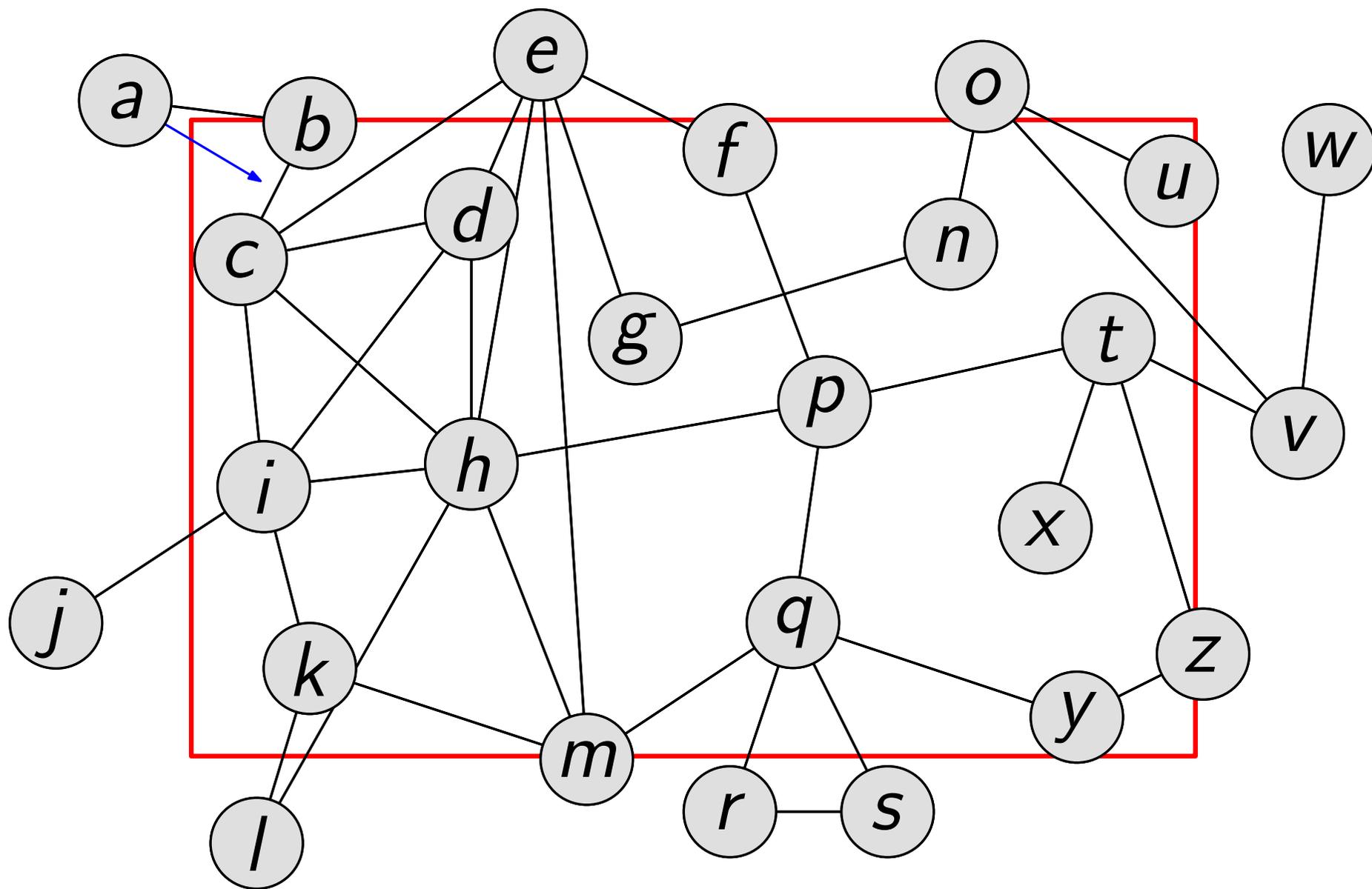
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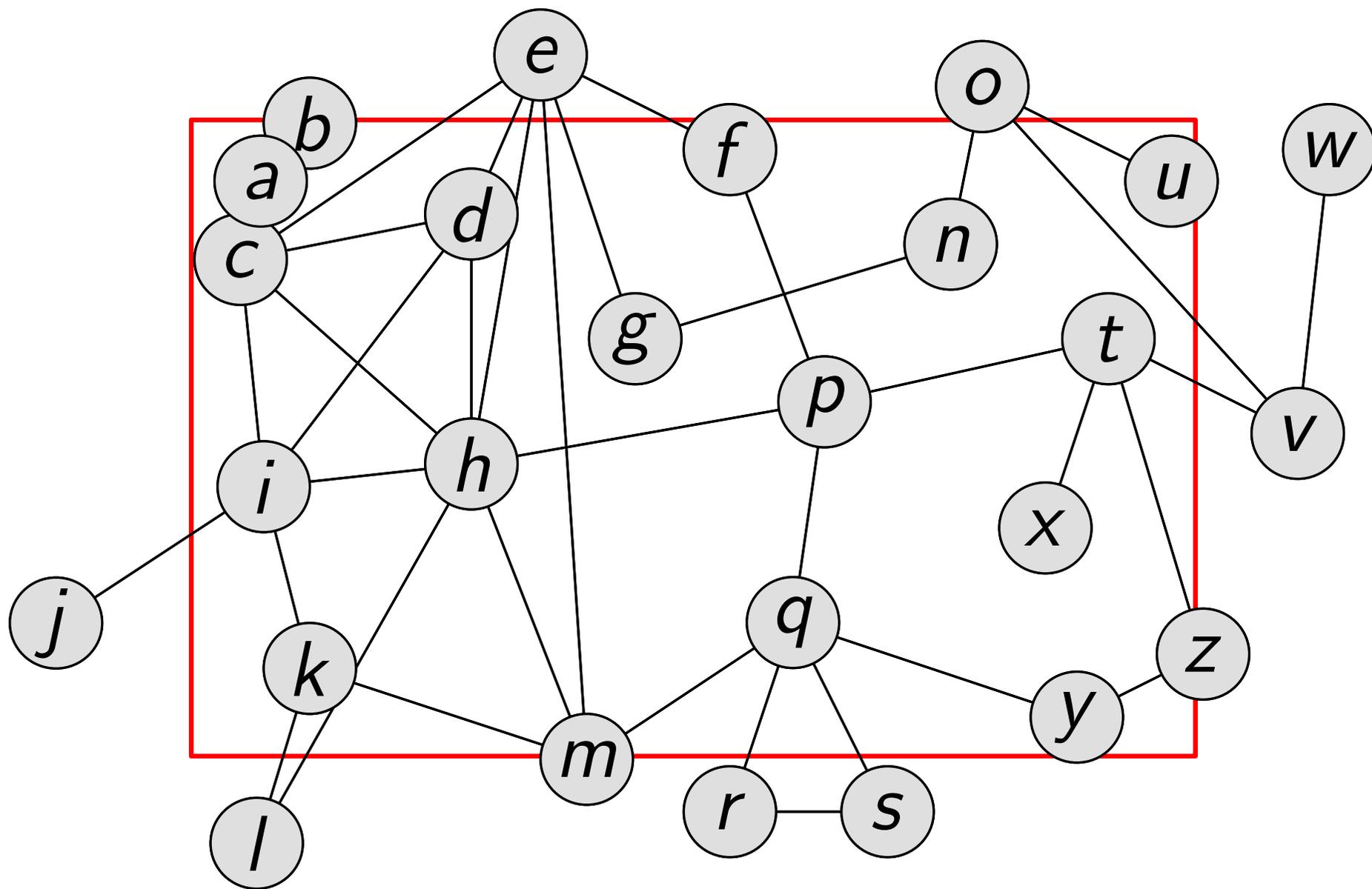
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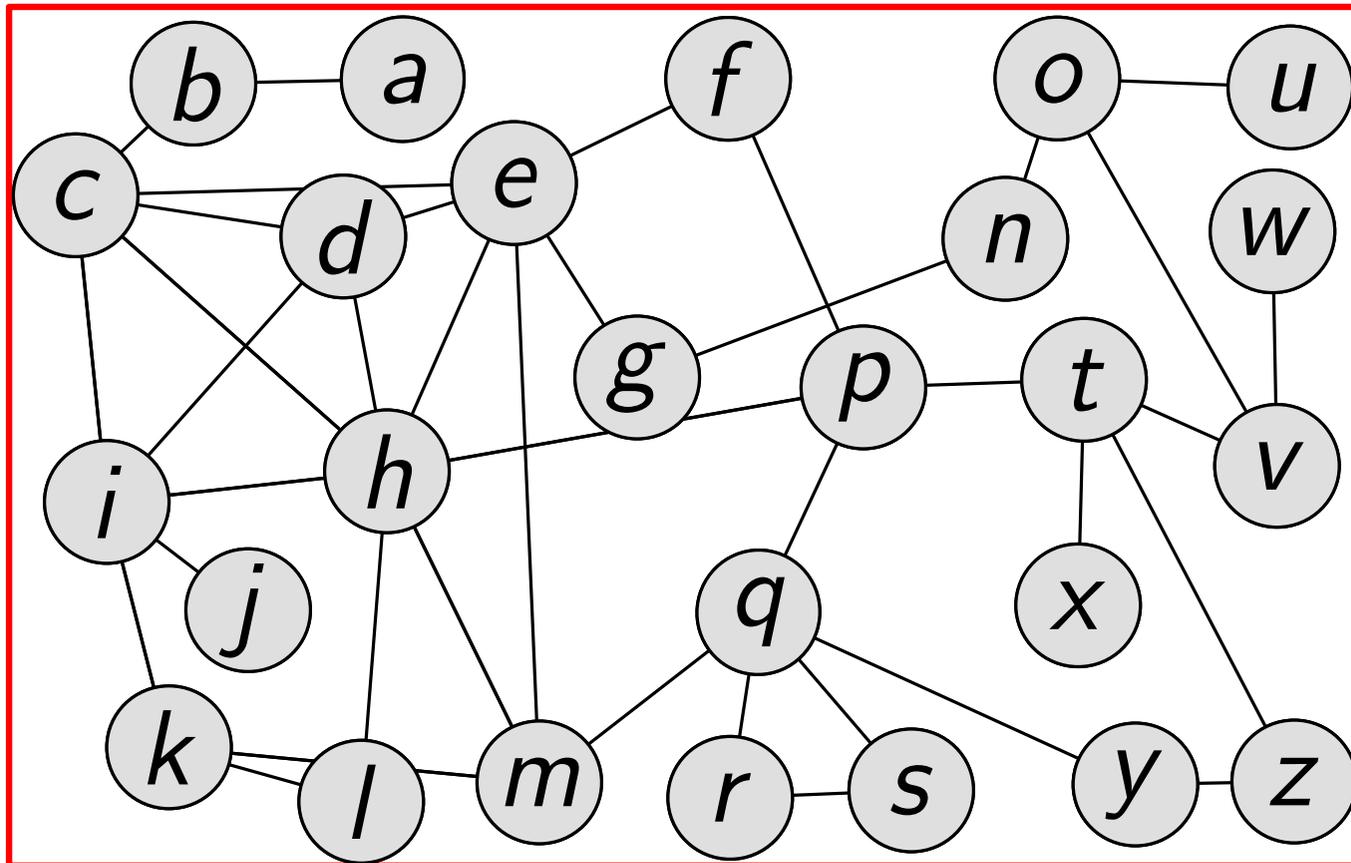
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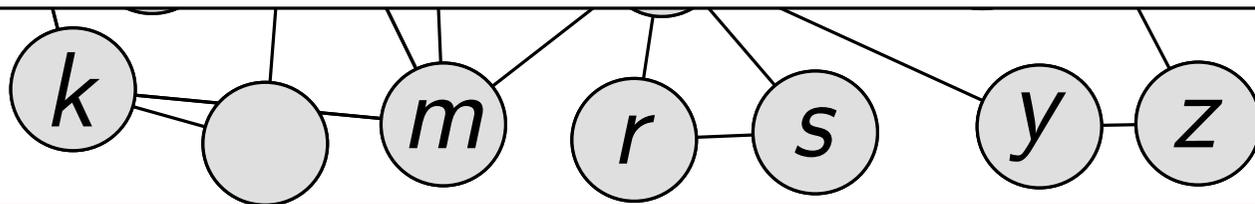


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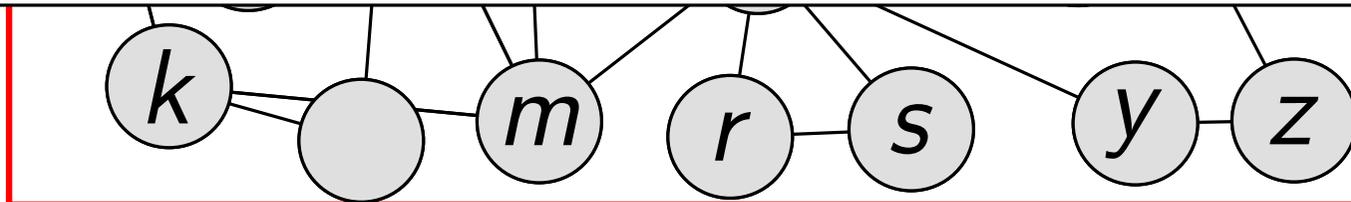
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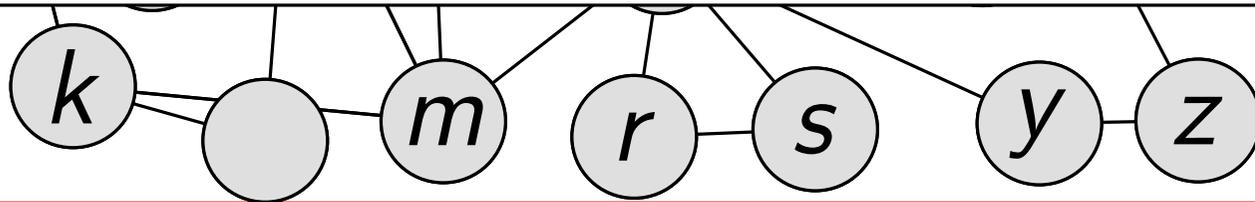
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compare [Fruchterman, Reingold '91]



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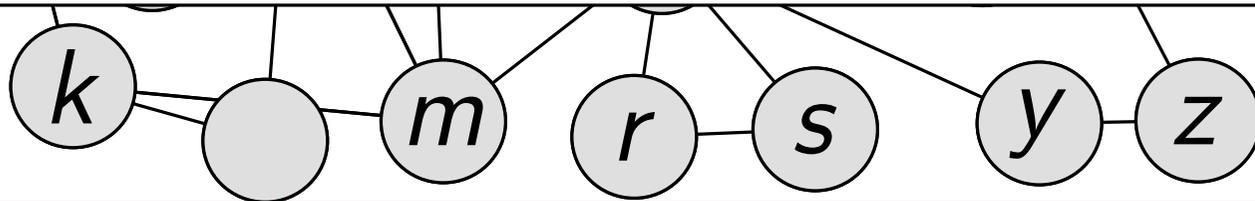
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● keep drawing in *frame*

● slowly shrink frame

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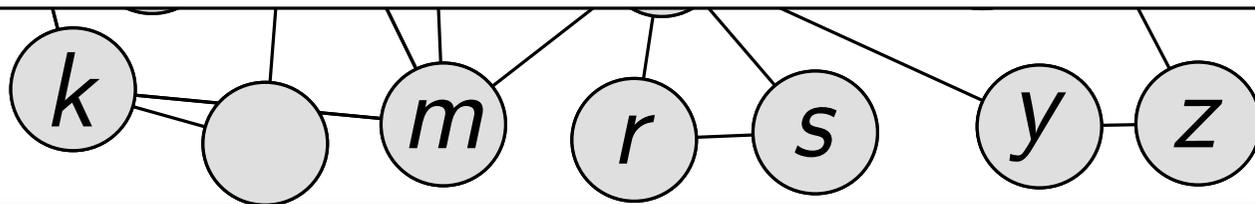
- keep drawing in *frame*

- slowly shrink frame

- remove vertices/edges if necessary after shrinking

- find new equilibrium

compare [Fruchterman, Reingold '91]



# General Graphs – Outline

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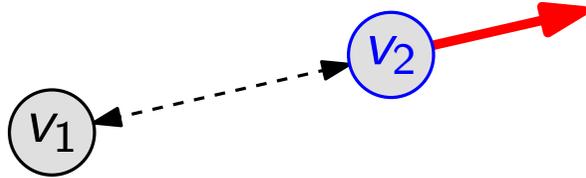
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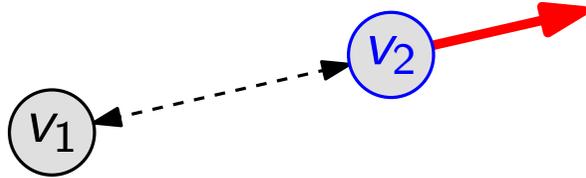
# Forces

- repulsion between vertices

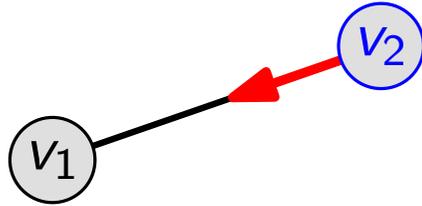


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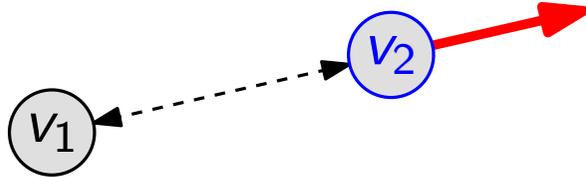


- attraction between *adjacent* vertices

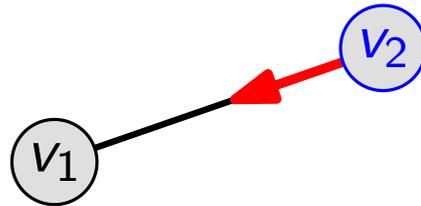


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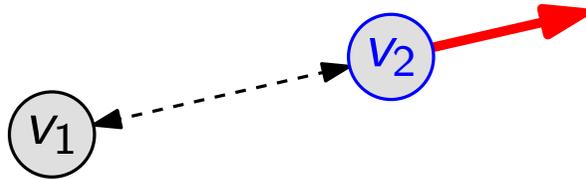
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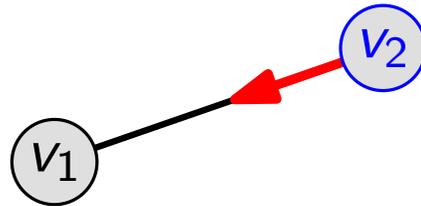
[Fruchterman,  
Reingold 1991]  
parameterized by  
**desired edge length**

# Forces

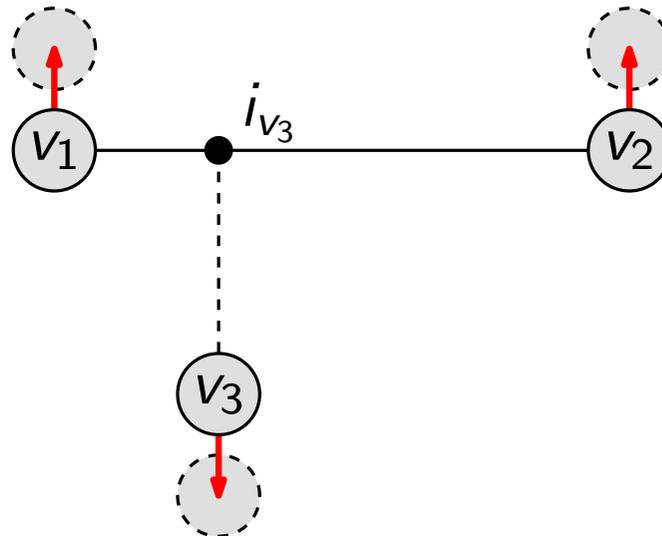
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- edge-vertex repulsion

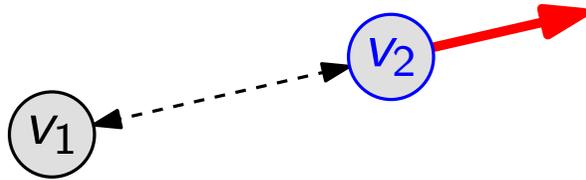


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[Bertault, 2000]

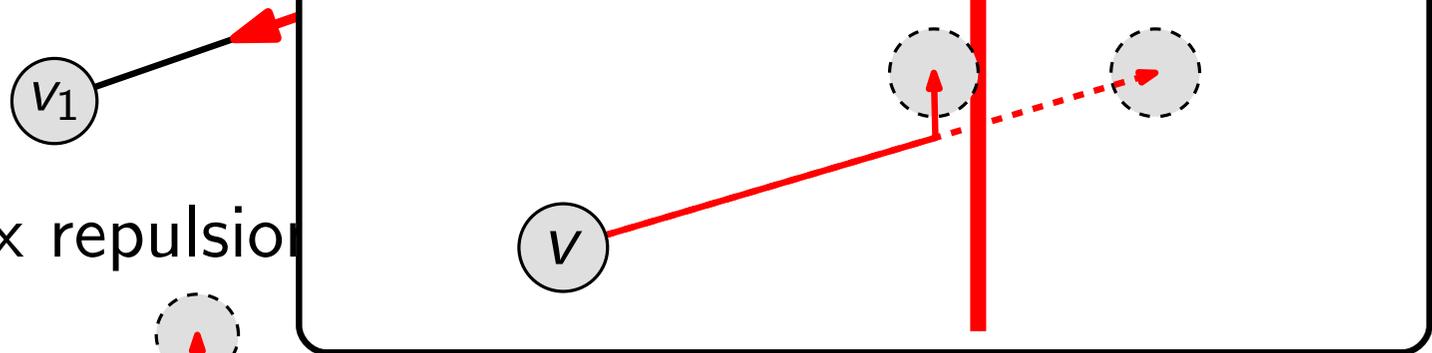
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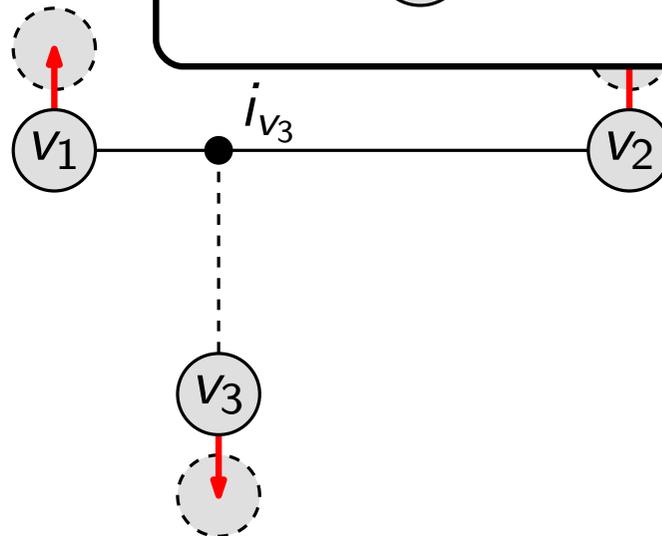


[Fruchterman, Reingold 1991]  
parameterized by

- attraction between a vertex and a frame boundary: cut off movement length

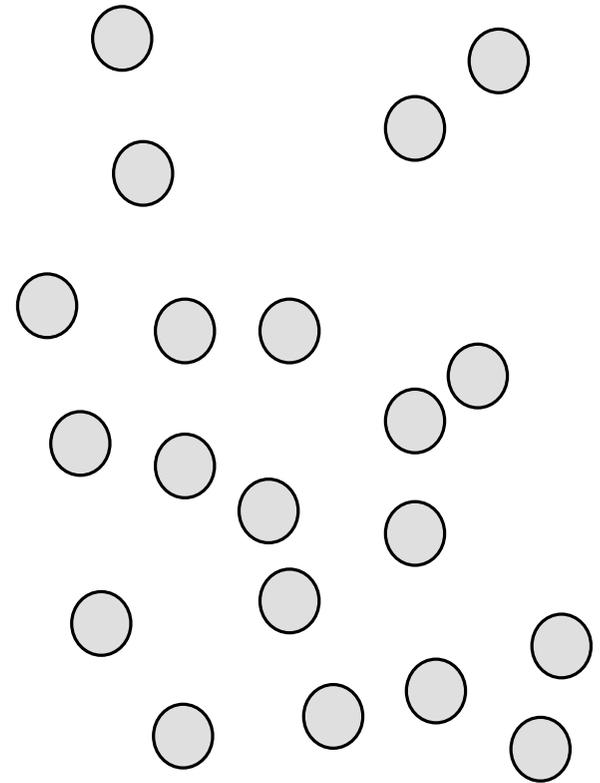


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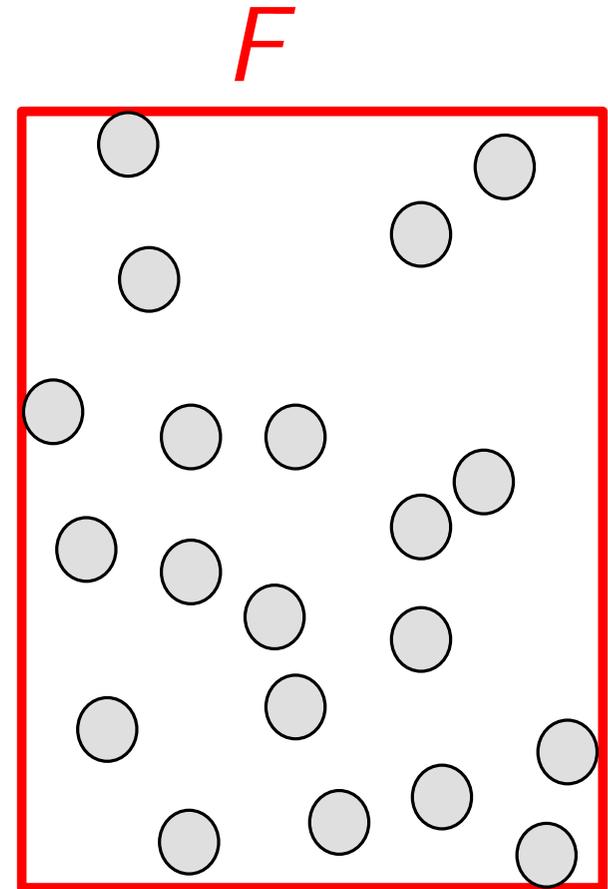


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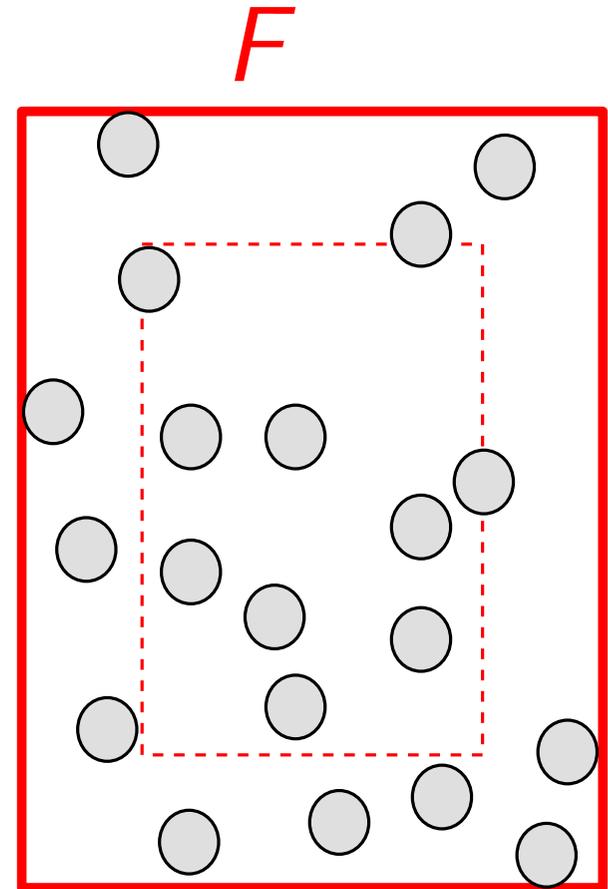
# Handling the Frame



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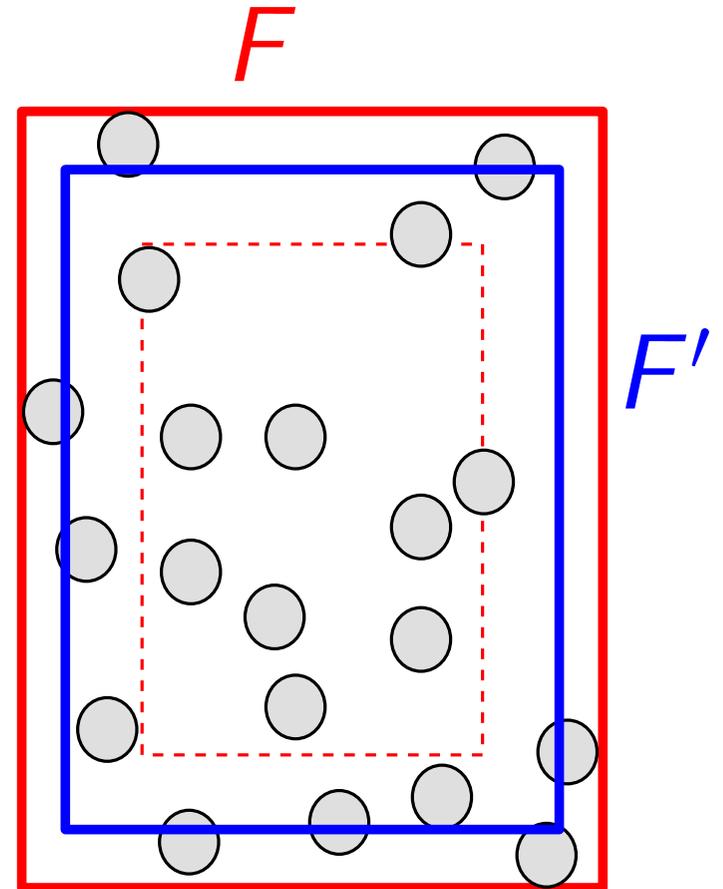


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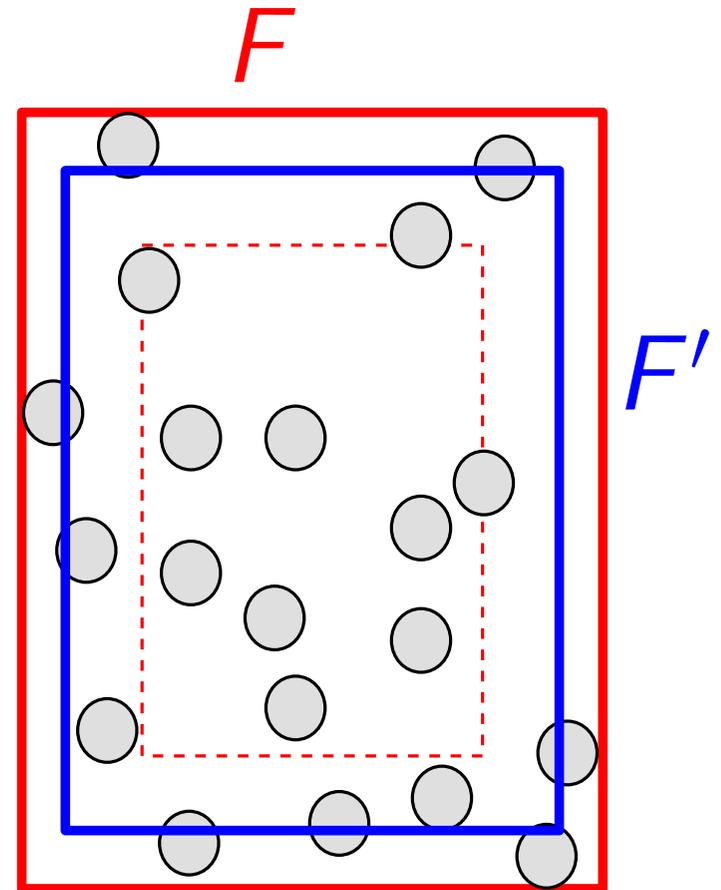
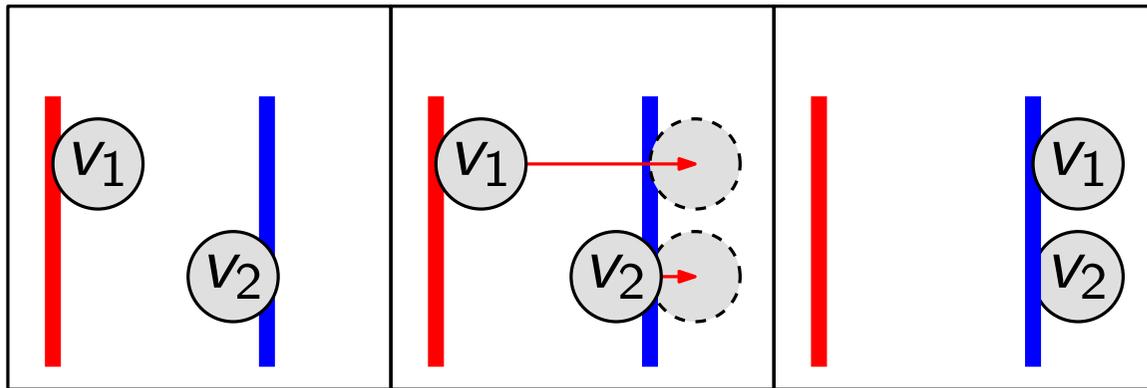
# Handling the Frame

- iteratively shrink frame



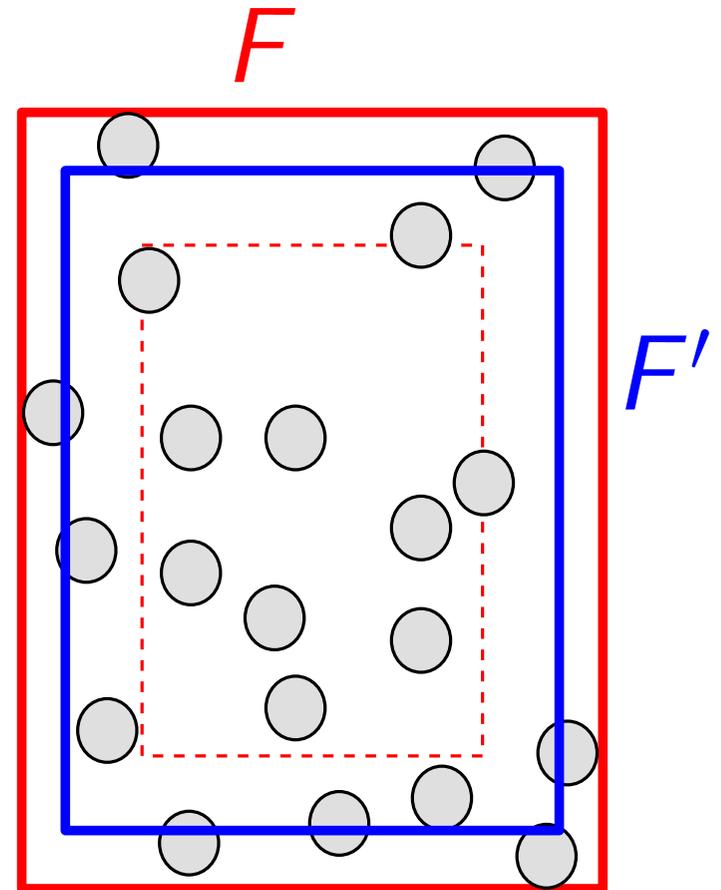
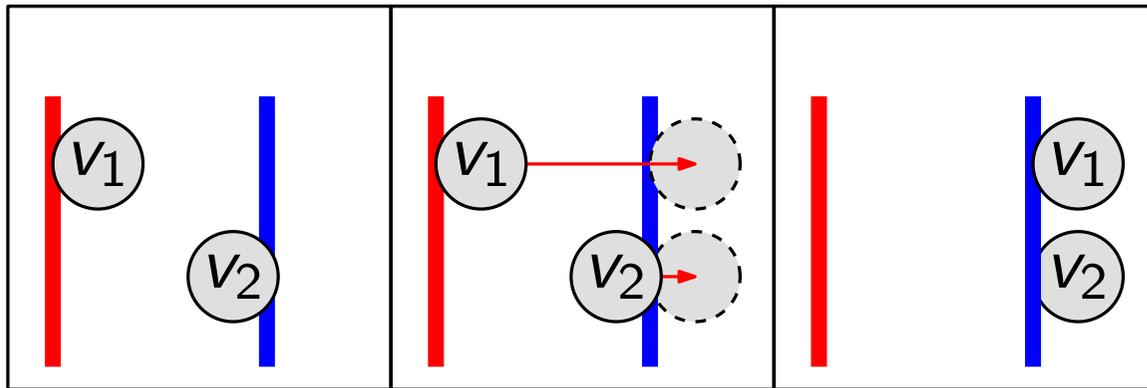
# Handling the Frame

- iteratively shrink frame
- push vertices into frame



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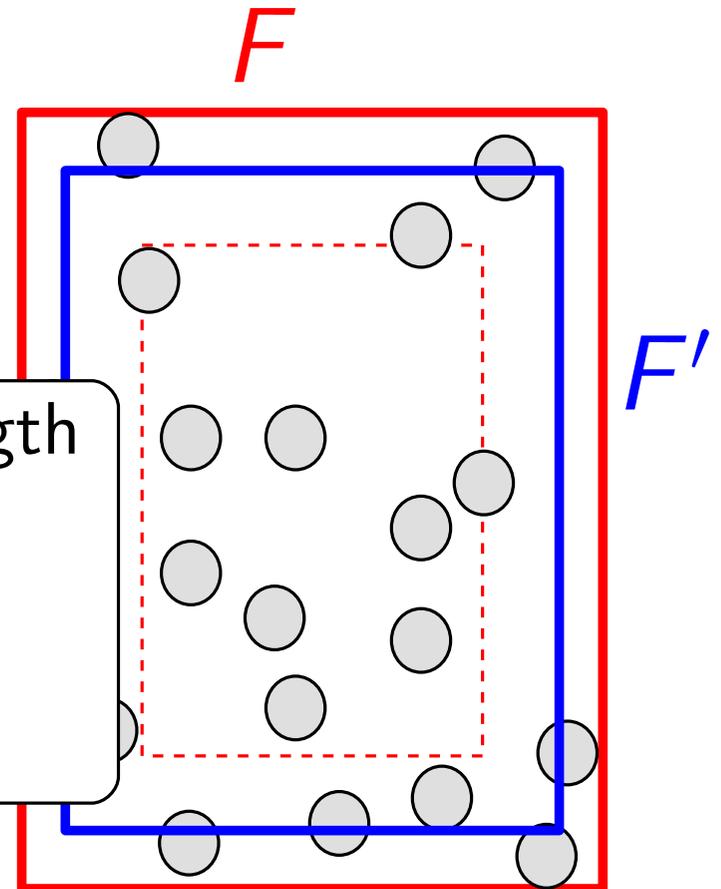
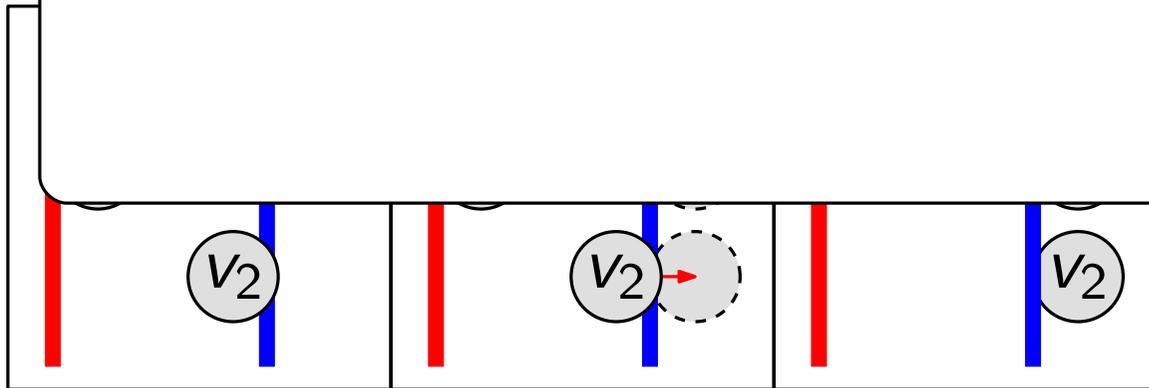
- iteratively shrink frame
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- compute new equilibrium layout



# Handling the Frame

- iteratively shrink frame
- push vertices into frame
- compute new equilibrium layout
- remove vertices/edges if *necessary*

distances too short  $\leftrightarrow$  desired edge length

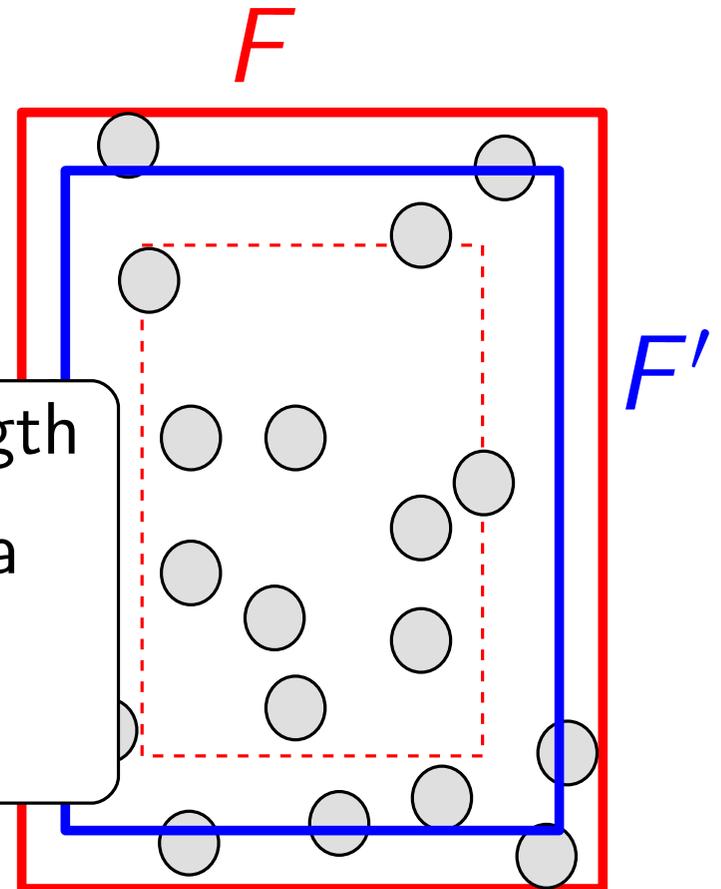
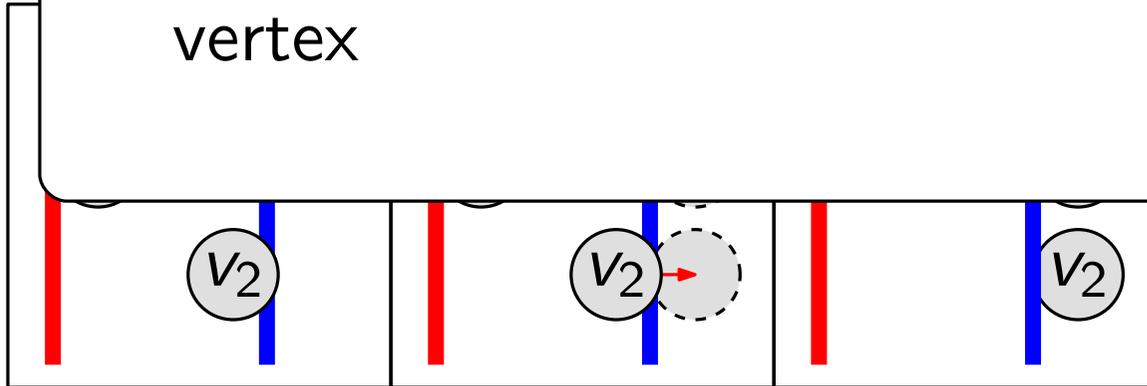


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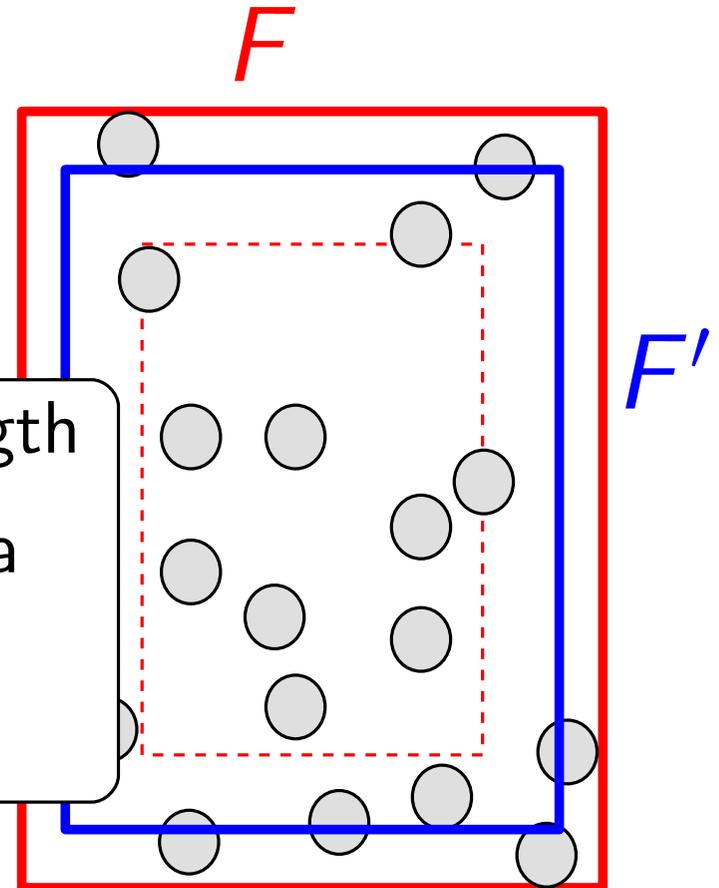
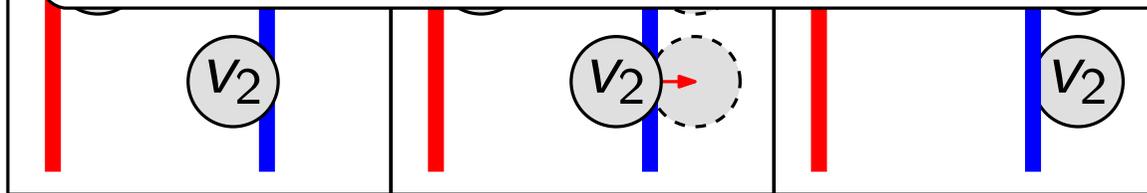


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# Removing vertices – Pressure and Stress

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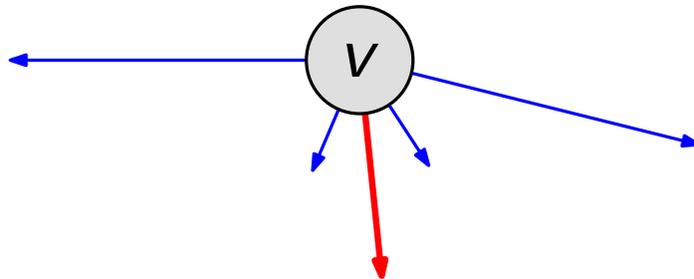
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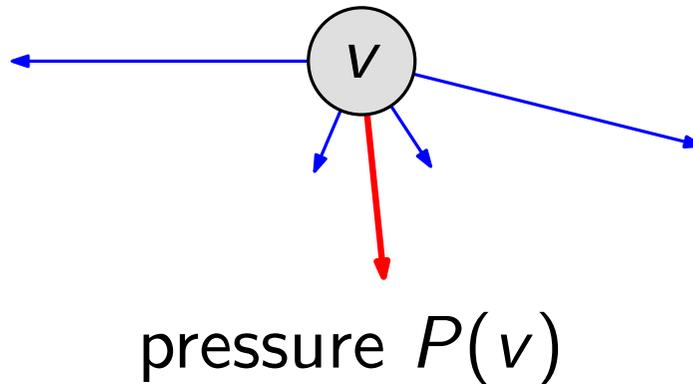
idea:



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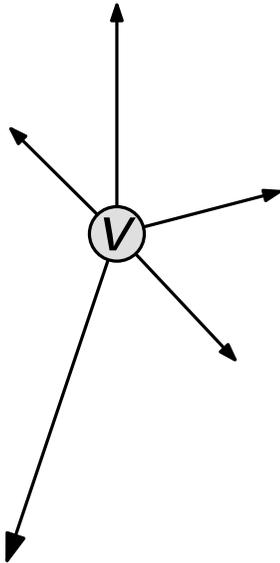
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idea: forces in opposite directions



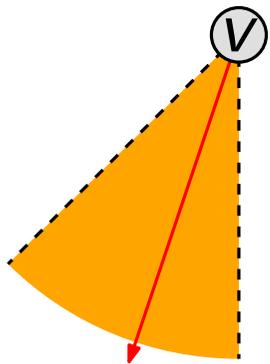
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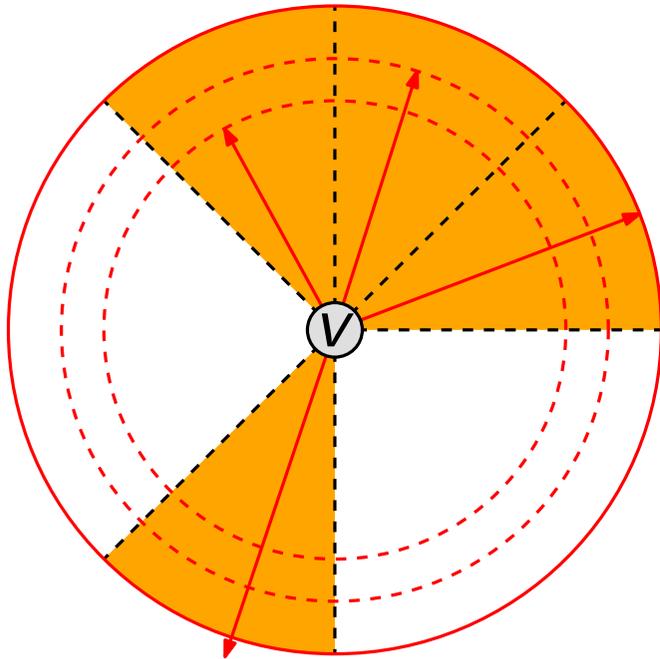
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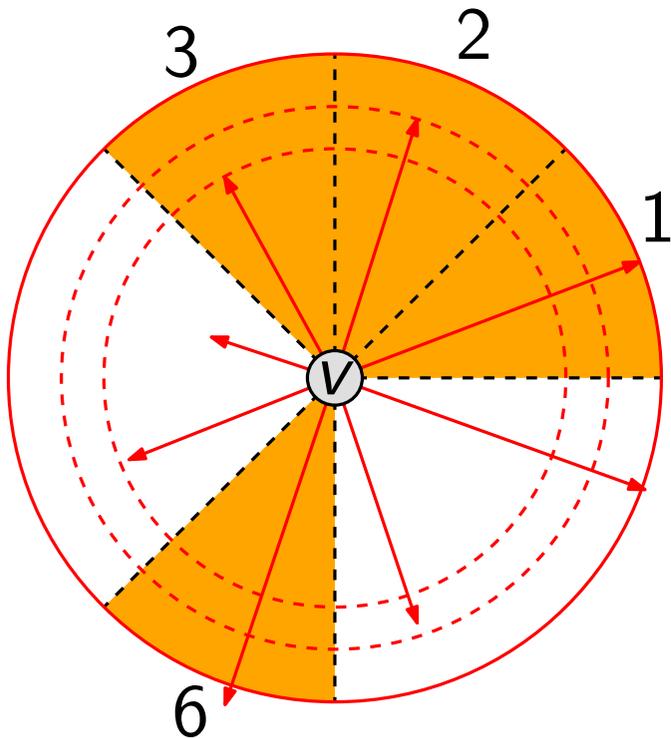
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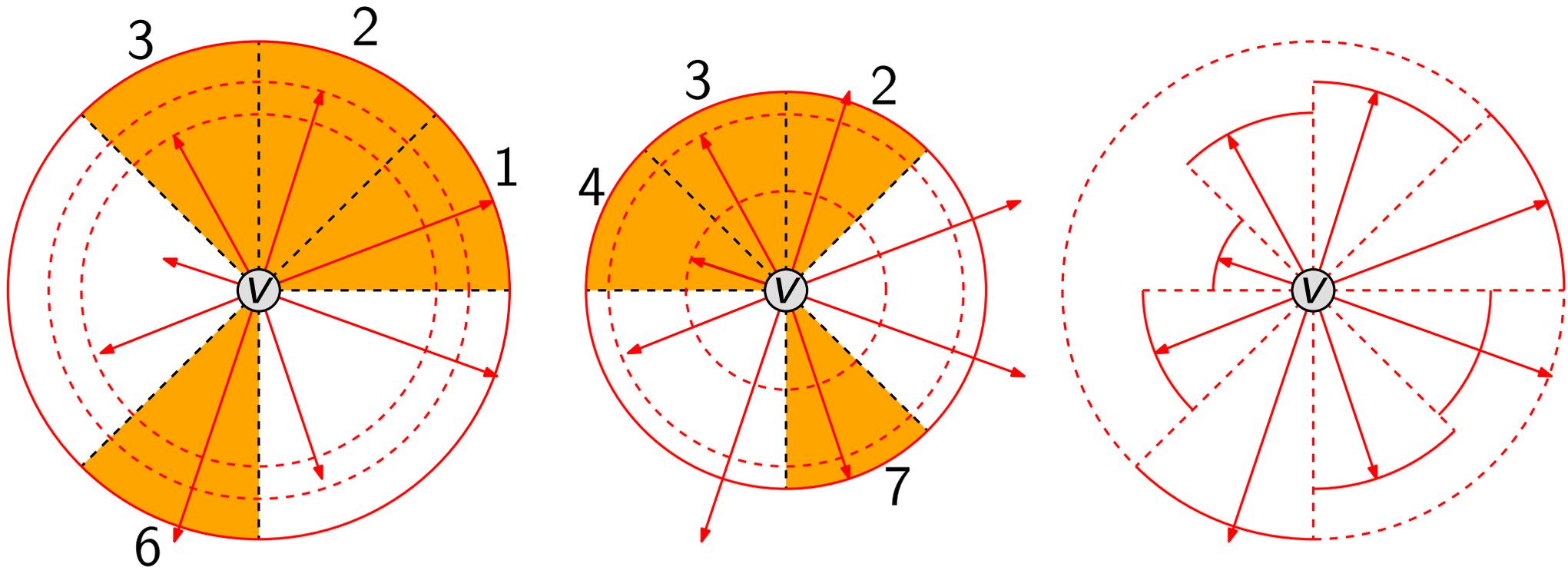
- remove lightest vertex ~~X~~
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- compare with opposite octants
- worst pair  $\rightarrow$  pressure

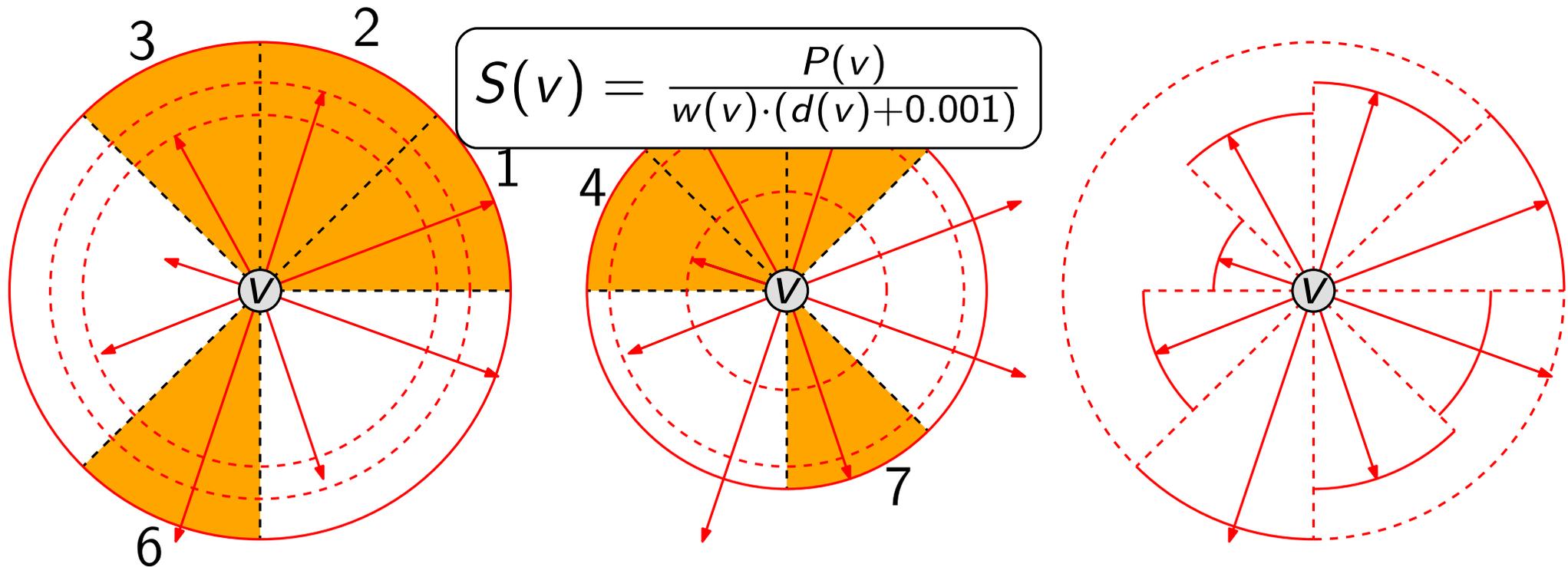
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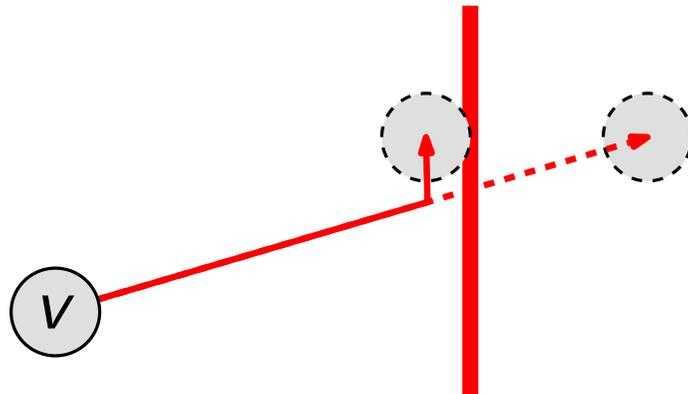
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- remove lightest vertex ~~X~~
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- also take current drawing into account:  
compute **pressure** based on forces
- remove vertex with highest **stress** value



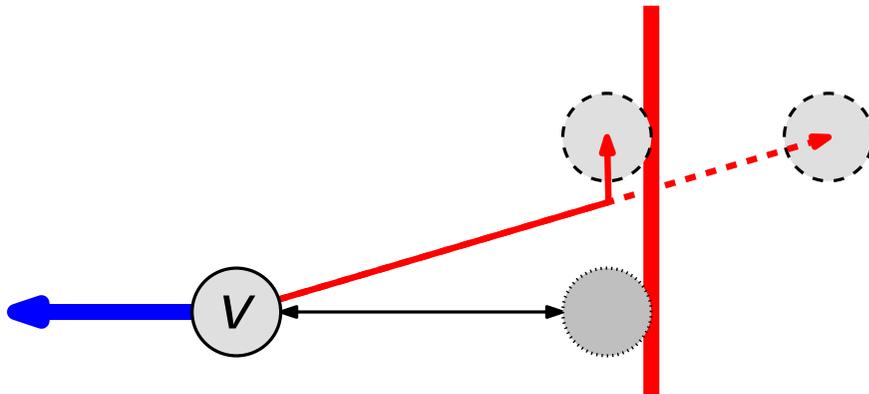
# Remark: Boundary Vertices

- movement cut off



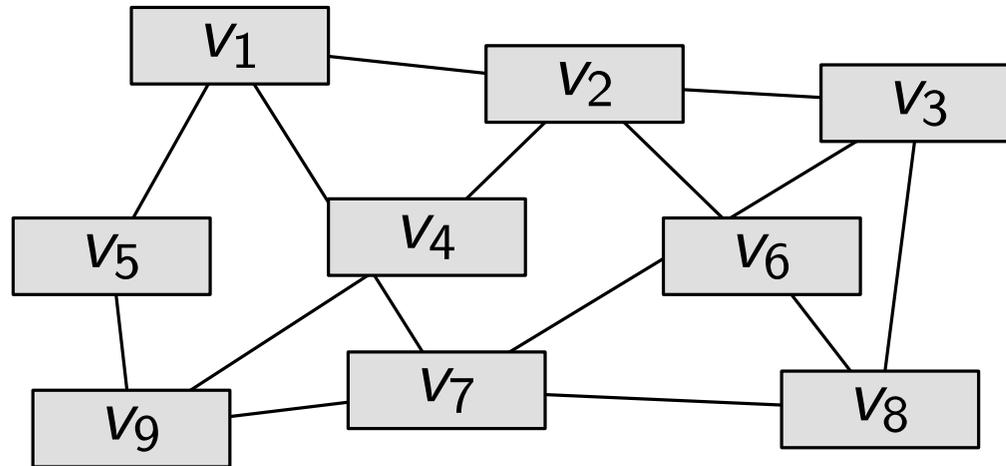
# Remark: Boundary Vertices

- movement cut off
- model as force
- only considered for pressure computation



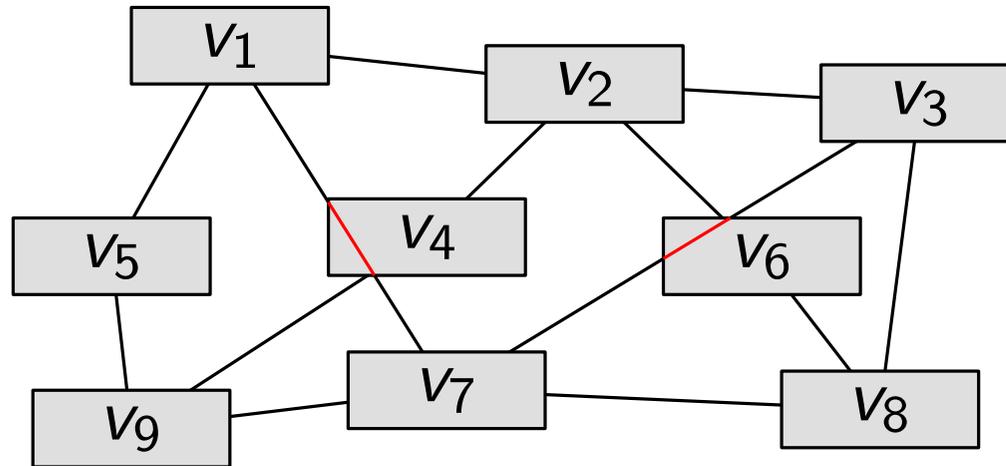
# Postprocessing: Curved Edges

- avoid edge-vertex intersections



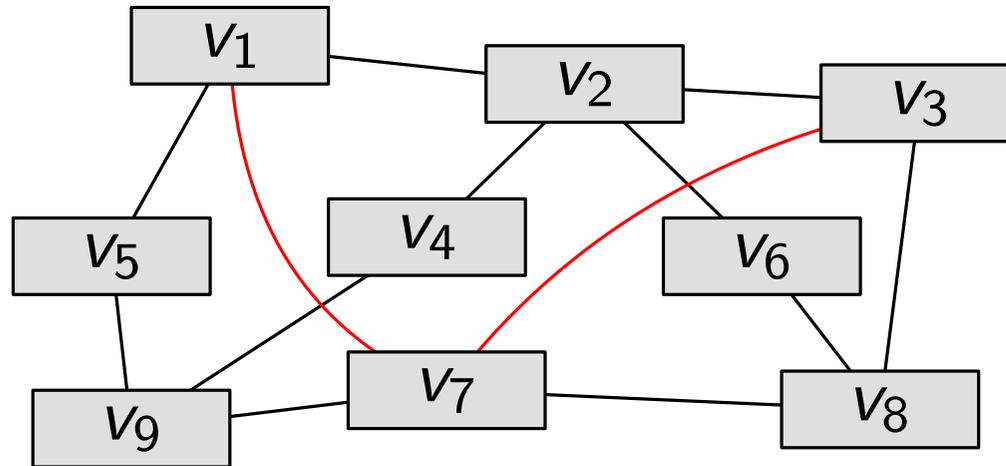
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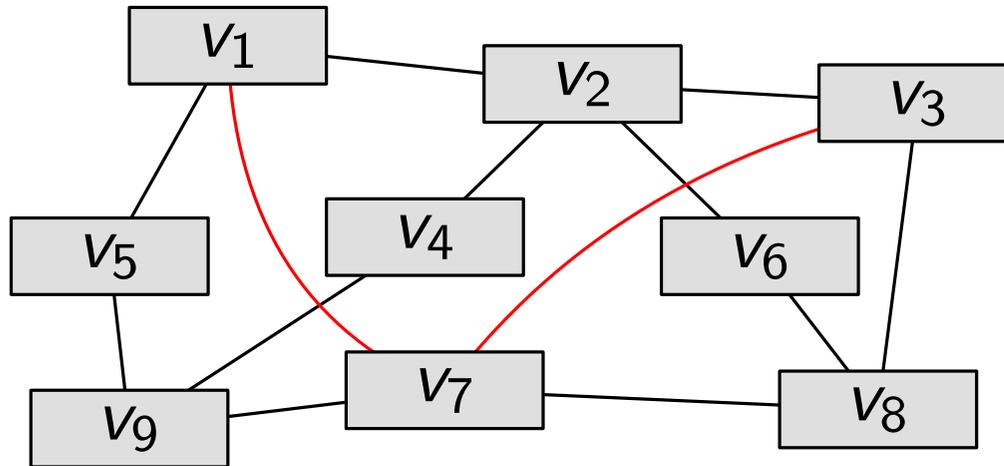
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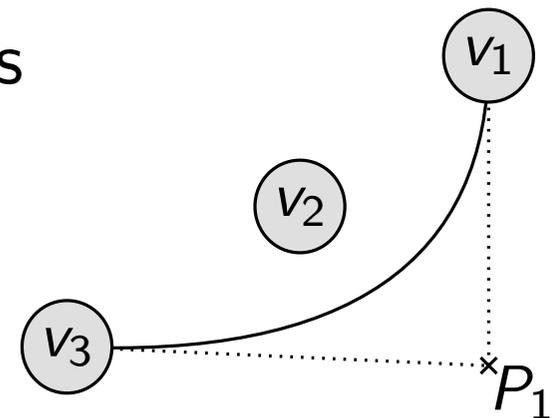


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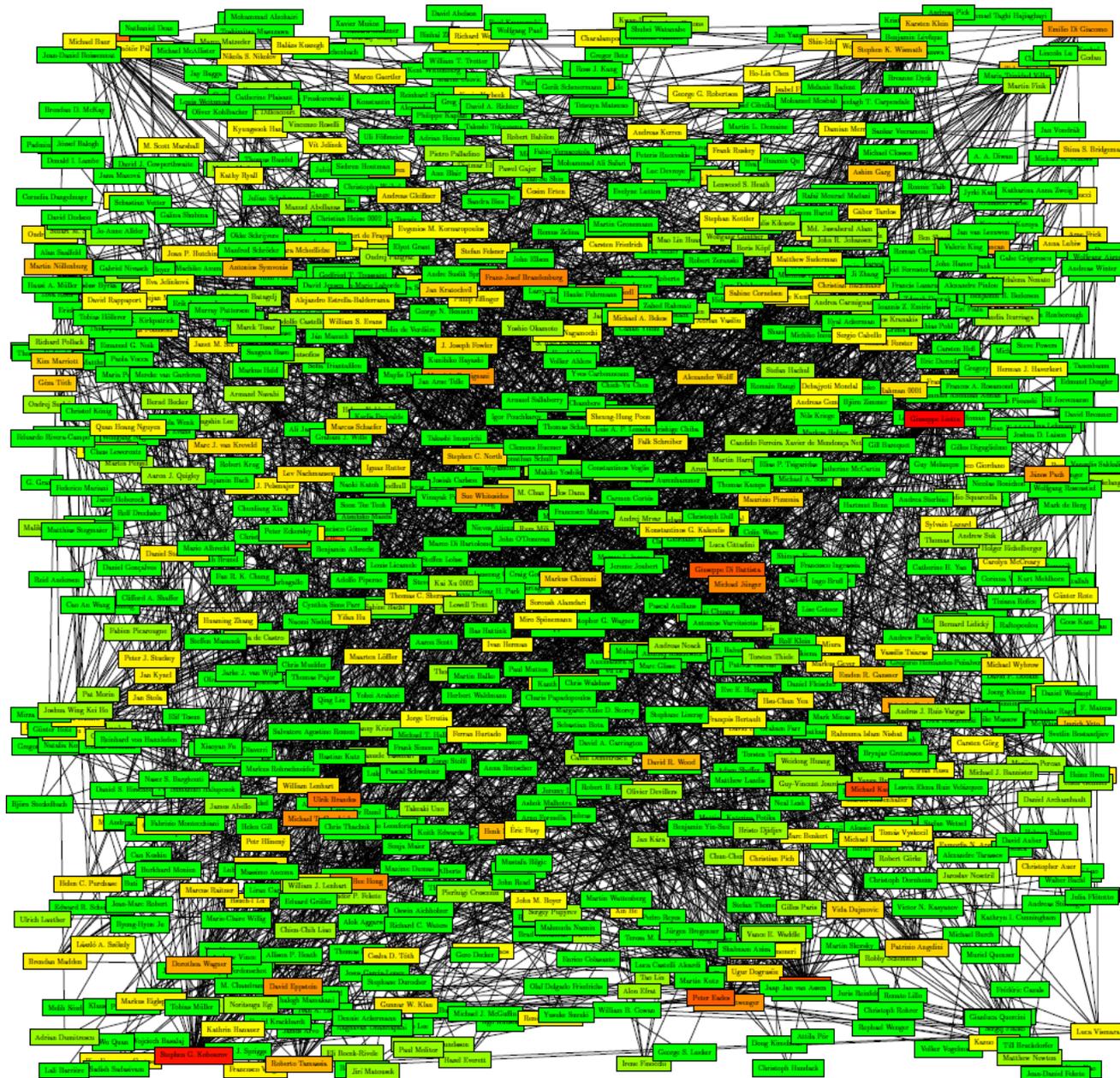
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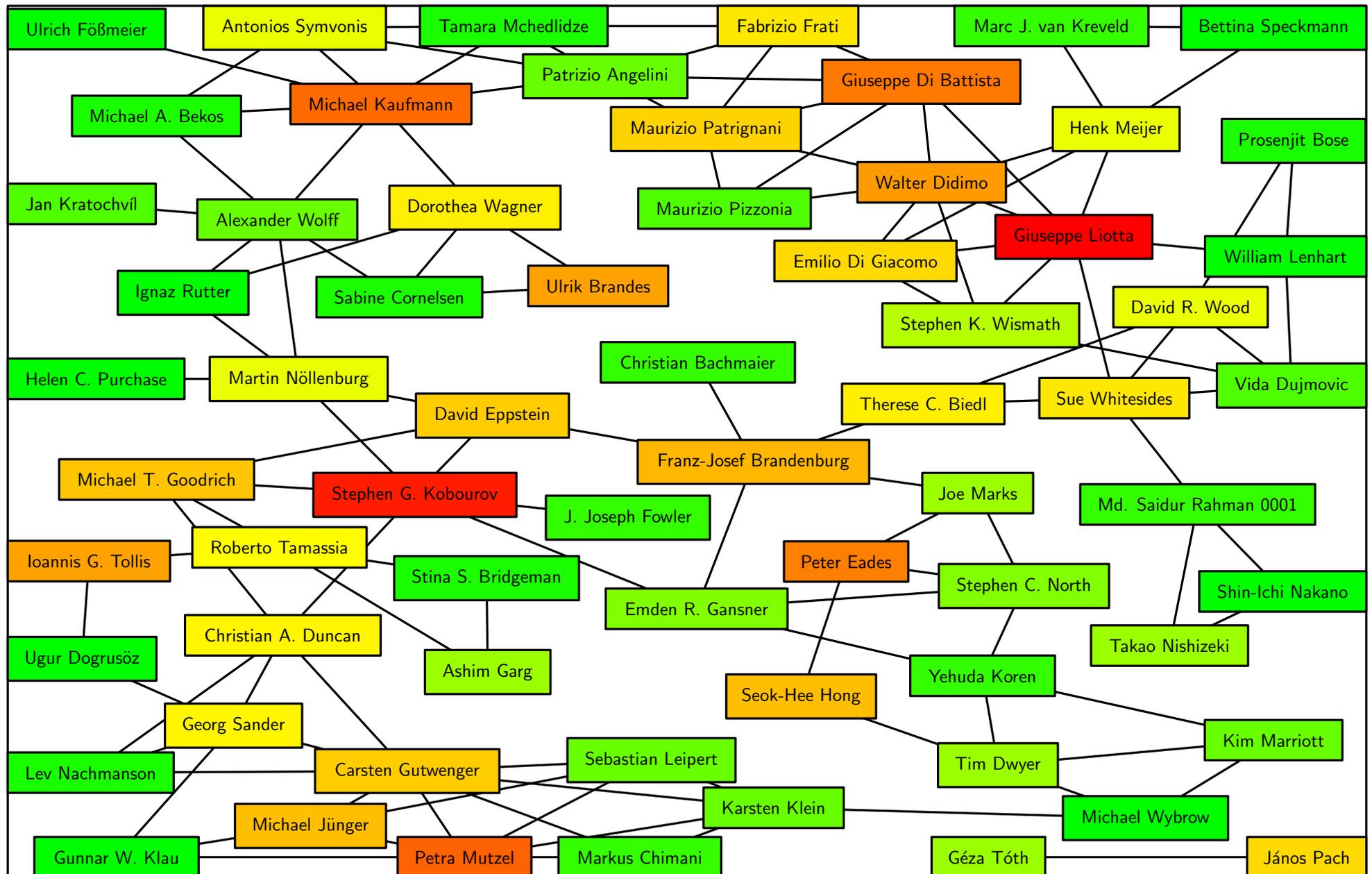
- draw some edges as quadratic Bézier curves
- force-directed computation of curve



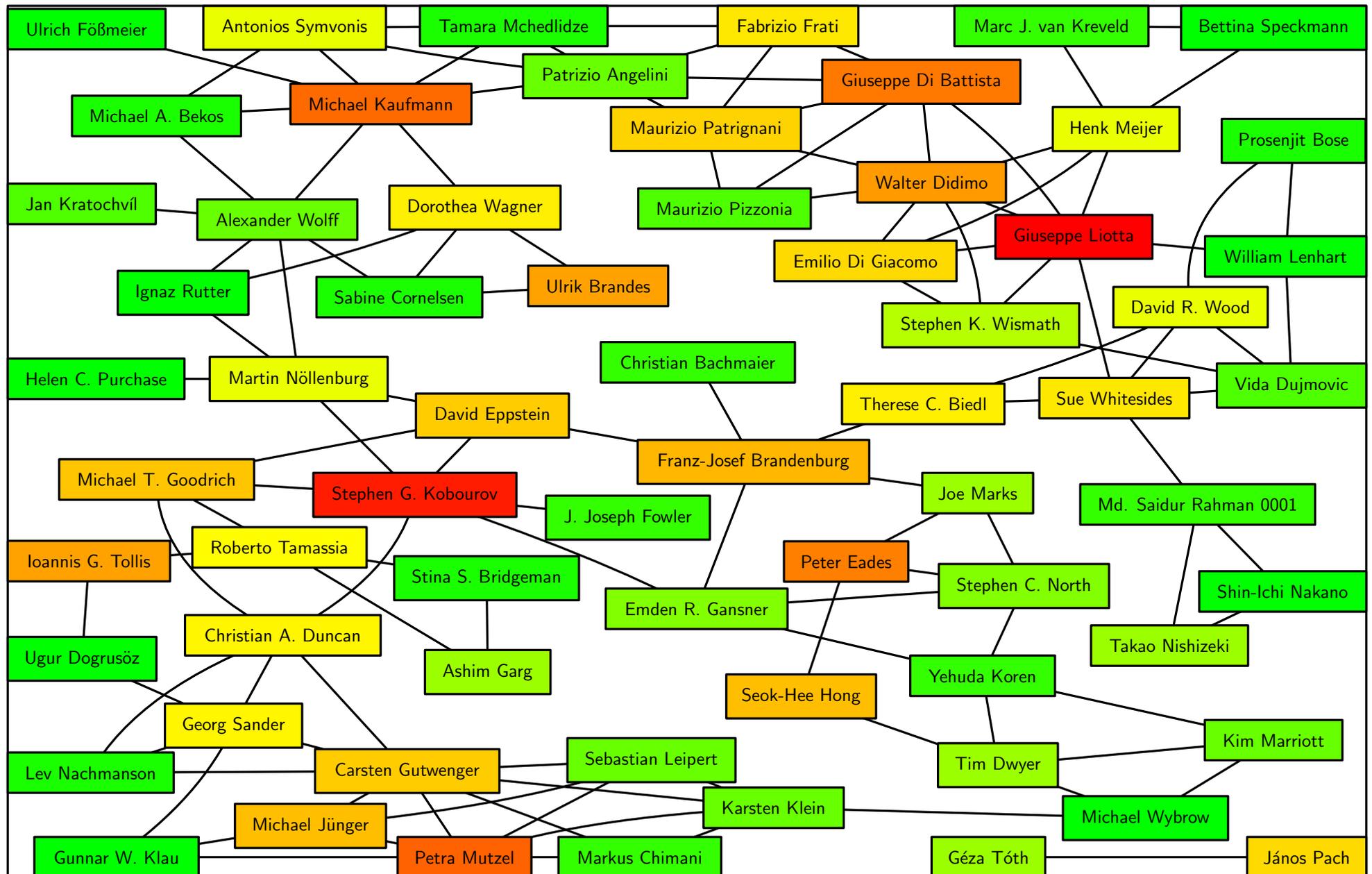
# Example – Input



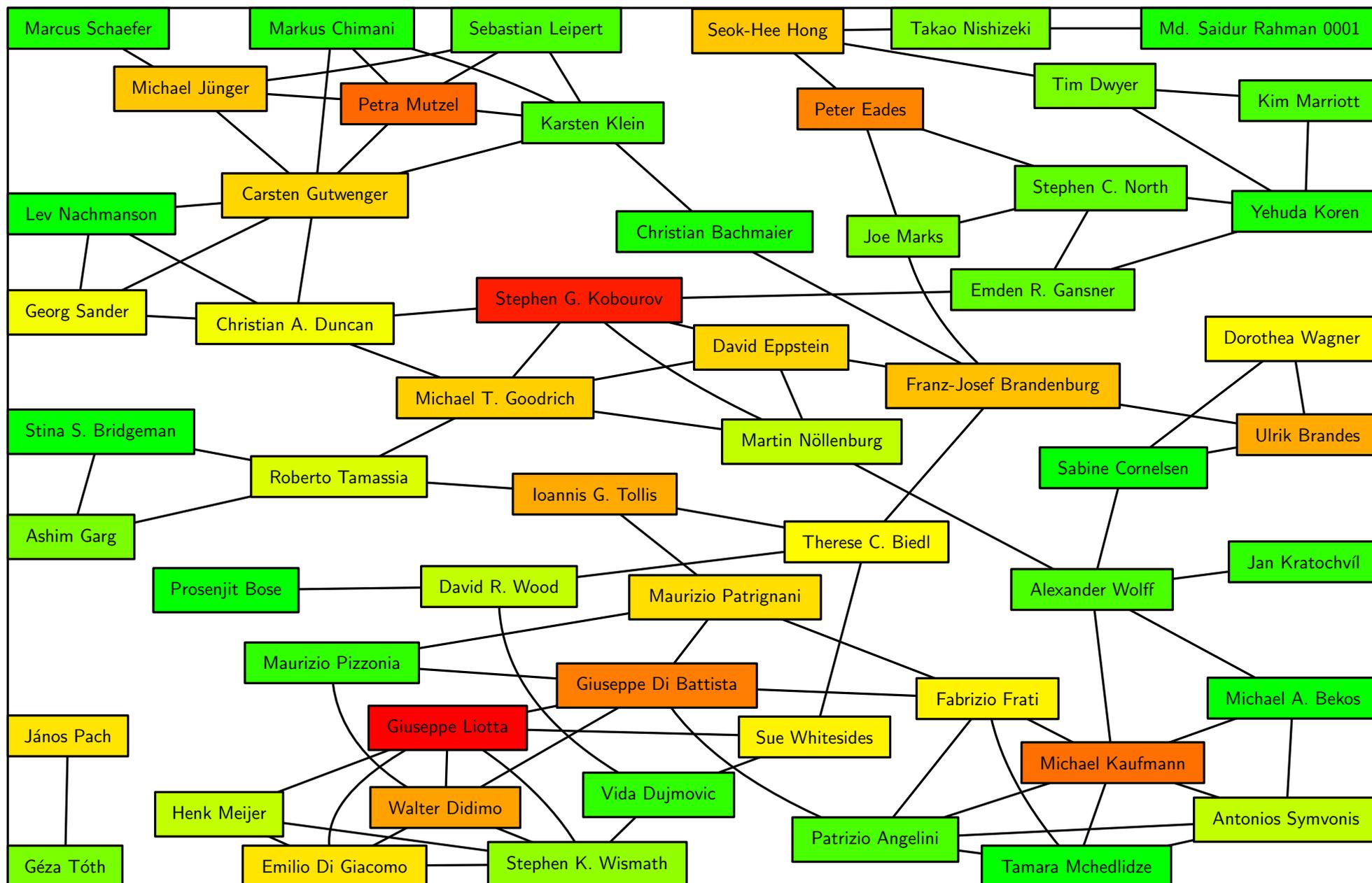
# Example – Output



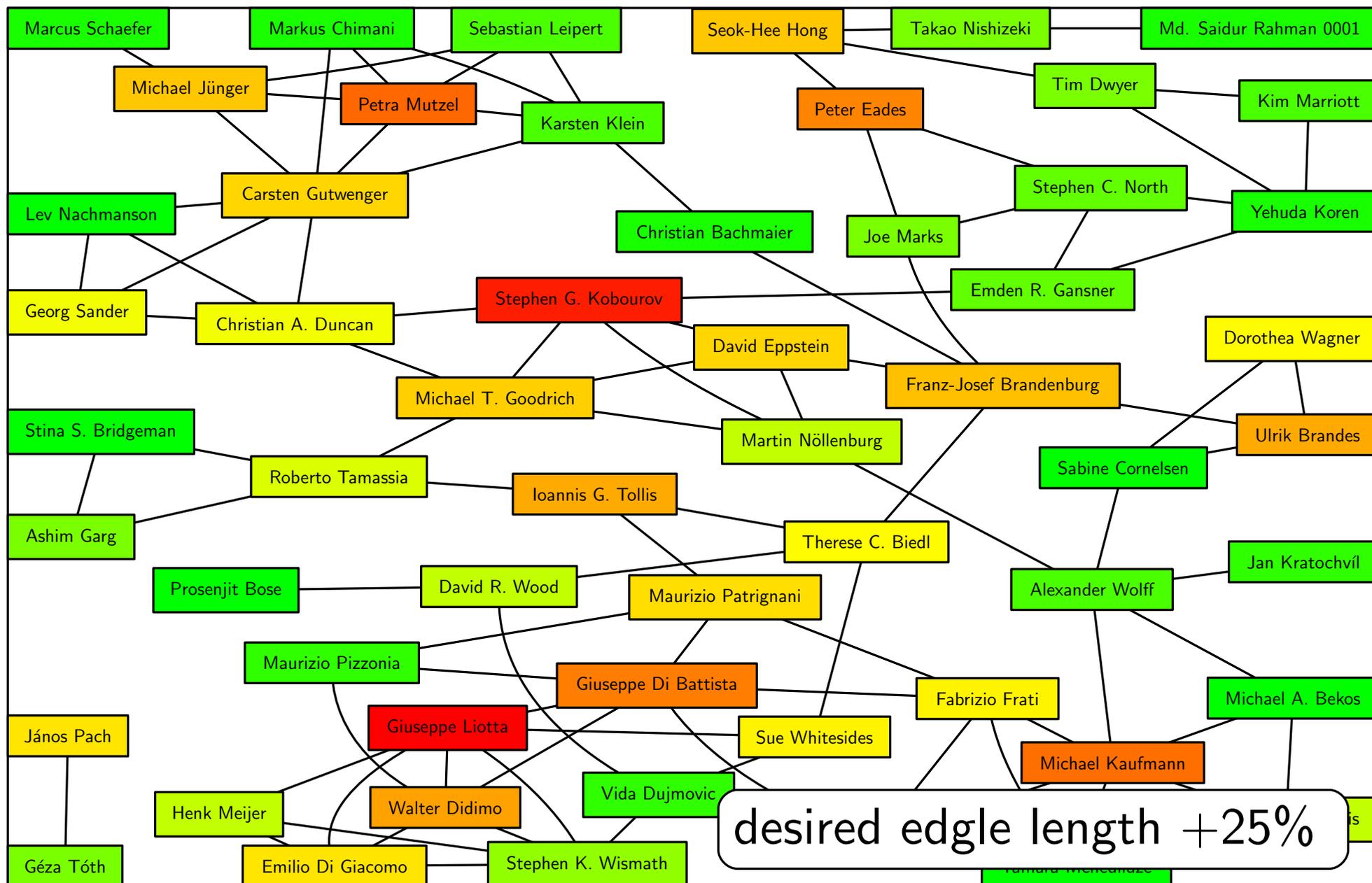
# Example – Curved Edges



# Example – Sparser Output



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# Remarks

- GD coauthor graph (1994 - 2012): 950, vertices 2559 edges → A4 paper, 10pt font:
  - runtime  $\approx$  2 minutes

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- activating edge-vertex repulsion only at the end of force-directed phase:
  - weight of edges in output +80%

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- Problems: – no alternative methods to compare with:  
real performance?  
– speedup